

THE SHAPE OF A CATEGORY UP TO DIRECTED HOMOTOPY

MARCO GRANDIS

ABSTRACT.

This work is a contribution to a recent field, Directed Algebraic Topology. Categories which appear as fundamental categories of ‘directed structures’, e.g. ordered topological spaces, have to be studied up to appropriate notions of *directed homotopy equivalence*, which are more general than ordinary equivalence of categories. Here we introduce *past* and *future equivalences* of categories—sort of symmetric versions of an adjunction—and use them and their combinations to get ‘directed models’ of a category; in the simplest case, these are the join of the *least full reflective* and the *least full coreflective* subcategory.

Introduction

Directed Algebraic Topology studies structures where paths and homotopies cannot generally be reversed, like ‘directed spaces’ in some sense—ordered topological spaces, ‘inequilogical spaces’, simplicial and cubical sets, etc. References for this domain are given below.

The study of homotopy invariance is far richer and more complex than in the classical case, where homotopy equivalence between ‘spaces’ produces a plain equivalence of their fundamental groupoids, for which one can simply take—as a minimal model—the categorical skeleton. Our directed structures have a *fundamental category* $\uparrow\Pi_1(X)$, and this must be studied up to appropriate notions of *directed* homotopy equivalence, which are more general than categorical equivalence.

We shall use two (dual) directed notions, which take care, respectively, of variation ‘in the future’ or ‘from the past’: *future equivalence* (a symmetric version of an adjunction, with two units) and its dual, a *past equivalence* (with two counits); and then study how to combine them. *Minimal models* of a category, up to these equivalences, are then introduced to better understand the ‘shape’ and properties of the category we are analysing, as well as of the process it represents.

An elementary example will give some idea of this analysis. Let us start from the standard *ordered* square $\uparrow[0, 1]^2$ (with the euclidean topology and the product order, $(x, y) \leq (x', y')$ if $x \leq x'$ and $y \leq y'$), and consider the (compact) ordered subspace

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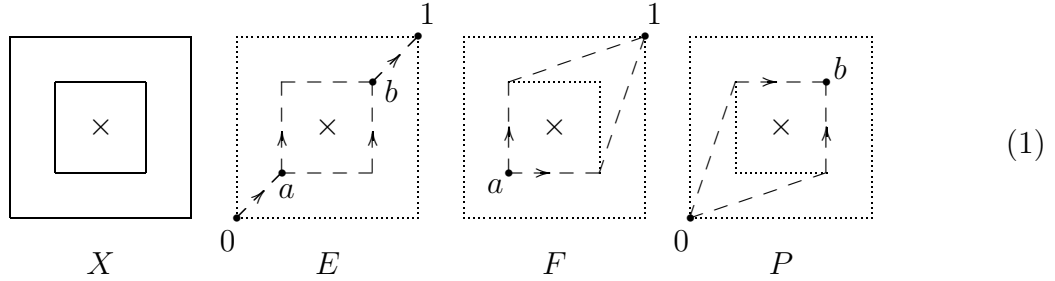
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Its directed paths are, by definition, the continuous *order-preserving* maps $\uparrow[0, 1] \rightarrow X$ defined on the standard ordered interval, and move ‘rightward and upward’ (in the weak sense). Directed homotopies of such paths are continuous order-preserving maps $\uparrow[0, 1]^2 \rightarrow X$. The fundamental category $C = \uparrow\Pi_1(X)$ has, for arrows, the classes of directed paths up to the equivalence relation *generated* by directed homotopy (with fixed endpoints, of course).

In our case, the whole category C is easy to visualise and ‘essentially represented’ by the full subcategory E on four vertices $0, a, b, 1$ (the central cell does not commute). But E is far from being equivalent to C , as a category, since C is *already a skeleton*, in the ordinary sense.

To get this result, we determine first the least *full reflective* subcategory F of C , which is future equivalent to C and minimal as such; its objects are a *future branching* point a (where one must choose between different ways out of it) and a *maximal* point 1 (where one cannot further proceed); they form the *future spectrum* $sp^+(C)$. Dually, we have the *past spectrum* P , i.e. the least *full coreflective* subcategory, whose objects form the *past spectrum* $sp^-(C)$. E is now the full subcategory of C on $sp(C) = sp^-(C) \cup sp^+(C)$, the *spectral injective model* of X (which is a minimal embedded model, in a sense which will be made precise).

The situation can now be analysed as follows, in E :

- the action begins at 0 , from where we move to a ,
- a is an (effective) future branching point, where we have to choose between two paths,
- which join at b , an (effective) past branching point,
- from where we can only move to 1 , where the process ends.

An alternative description will be obtained with the associated *projective model* M , the full subcategory of the category C^2 (of morphisms of C) on the four maps $\alpha, \beta, \sigma, \tau$ - obtained from a canonical factorisation of the composed adjunction $P \rightleftarrows C \rightleftarrows F$ (cf.

preorder relation is assumed to be reflexive and transitive; it is a (partial) *order* if it is also anti-symmetric. As usual, a preordered set will be *identified* with a (small) category having at most one arrow between any two given objects. We shall distinguish between the ordered real line \mathbf{r} and the ordered topological space $\uparrow\mathbf{R}$ (the euclidean line with the natural order), whose fundamental category is \mathbf{r} . The classical properties of adjunctions and equivalences of categories are used without reference (see [18]). \mathbf{Cat} denotes the category of small categories.

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1. Directed homotopies and the fundamental category

In this section we give a brief presentation of directed homotopies for preordered topological spaces. This will lead us to the question of 'homotopy equivalence' between fundamental categories and the problem of reducing the latter to simpler models. Exploring diagrammatic properties of comma squares (in 1.6) will give some hints for such problems.

1.1. HOMOTOPY FOR PREORDERED SPACES. The simplest topological setting where one can study directed paths and directed homotopies is likely the category \mathbf{pTop} of *preordered topological spaces* and *preorder-preserving continuous mappings*; the latter will be called simply *morphisms* or *maps* (when it is understood we are in this category).

In this setting, a (directed) *path* in the preordered space X is a map $a: \uparrow[0, 1] \rightarrow X$, defined on the standard directed interval $\uparrow\mathbf{I} = \uparrow[0, 1]$ (with euclidean topology and natural order). A (directed) *homotopy* $\varphi: f \rightarrow g: X \rightarrow Y$, *from* f *to* g , is a map $\varphi: X \times \uparrow\mathbf{I} \rightarrow Y$ coinciding with f on the 0-basis of the *cylinder* $X \times \uparrow\mathbf{I}$, with g on the 1-basis. Of course, this (directed) cylinder is a product in \mathbf{pTop} : it is equipped with the product topology *and* with the product preorder, where $(x, t) \prec (x', t')$ if $x \prec x'$ in X and $t \leq t'$ in $\uparrow\mathbf{I}$.

The fundamental category $C = \uparrow\Pi_1(X)$ has, for arrows, the classes of directed paths up to the equivalence relation *generated* by directed homotopy with fixed endpoints; composition is given by the concatenation of consecutive paths.

Note that the fundamental category of a preordered space X is *not* a preorder, generally (cf. 1.2); but any loop in X lives in a zone of equivalent points and is reversible, so that all endomorphisms of $\uparrow\Pi_1(X)$ are invertible. Moreover, if X is *ordered*, all loops are constant: the fundamental category has no endomorphisms and no isomorphisms, except the identities, and is skeletal.

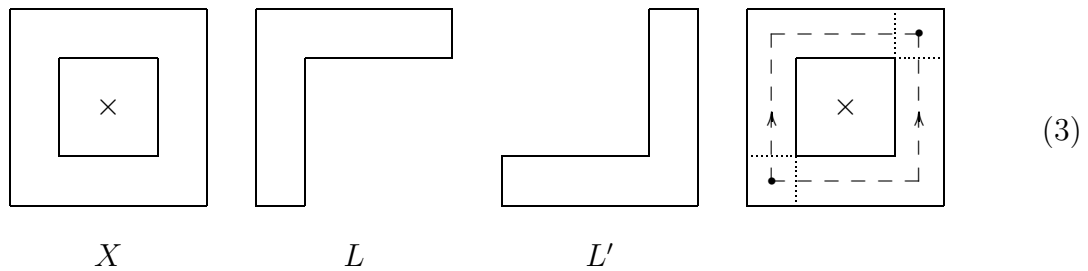
The fundamental category of a preordered space can be computed by a van Kampen-type theorem, as proved in [10], Thm. 3.6, in a much more general setting ('d-spaces', defined by a family of distinguished paths).

The forgetful functor $U: \mathbf{pTop} \rightarrow \mathbf{Top}$ to the category of topological spaces has both a left and a right adjoint, $D \dashv U \dashv C$, where DX (resp. CX) is the space X with the *discrete* order (resp. the *coarse* preorder). Therefore, U preserves limits and colimits. The standard embedding of \mathbf{Top} in \mathbf{pTop} will be the *coarse* one, so that *all* (*ordinary*)

paths in X are directed in CX . Note that the category of ordered spaces does not allow for such an embedding, and has different colimits.

1.2. AN EXAMPLE. It will be useful to see how directed homotopy works in an elementary case, the ordered space $X \subset \uparrow[0, 1]^2$ of the Introduction (the complement of $]1/4, 3/4[^2$ in $\uparrow\mathbf{I}^2$).

Here, the fundamental category $C = \uparrow\Pi_1(X)$ has *some* arrow $x \rightarrow x'$ provided that $x \leq x'$ and both points are in L or in L' (the closed subspaces represented below)



Precisely, there are *two* arrows when $x \leq (1/4, 1/4)$ and $x' \geq (3/4, 3/4)$ (as in the last figure above), and *one* otherwise. This visible fact can be easily proved with the ‘van Kampen’ theorem cited above, using the closed subspaces L, L' (whose fundamental category is the induced order).

In this case, the fundamental category is a subcategory of the fundamental groupoid $\Pi_1(|X|)$ of the underlying topological space (forgetting the order). This is no longer the case in more complex situations, like the three-dimensional ordered spaces considered in Section 9 (complements of a cube in a cube).

We have already seen in the Introduction that, while the fundamental category C is quite simple, we have to find new ways of modelling it: ordinary equivalence is of no help, since there are no non-trivial isomorphisms and C is already a skeleton.

1.3. THE DIRECTED CIRCLE. Preordered topological spaces are not sufficient for the development of Directed Algebraic Topology: one cannot realise a model of the directed circle or the directed torus in \mathbf{pTop} . Some remarks about more general ‘directed topological structures’ may be of interest to the reader, even if not technically needed for the sequel.

Let us start with the fundamental *groupoid* $\Pi_1(\mathbf{S}^1)$ of the standard circle. We shall study its subcategory \mathbf{c} containing all points of the circle and the homotopy classes of the ‘anticlockwise’ paths, showing that \mathbf{c} is modelled by its full subcategory at any point x (5.6). Again, we need a new approach to formulate this result: while the fundamental group $\pi_1(\mathbf{S}^1, x)$ is the skeleton of the fundamental groupoid, \mathbf{c} has no non-trivial isomorphism and is its own skeleton.

Now, \mathbf{c} *cannot* be the fundamental category of a preordered topological space, because we have already noted that in such a category all endomorphisms are invertible (1.1).

However, \mathbf{c} can be viewed as the fundamental category of a ‘directed circle’, living in a more general setting: e.g. ‘locally ordered spaces’, as often considered in concurrency [4, 6, 7], ‘d-spaces’ [10] or—perhaps more simply—‘inequilogical spaces’.

The category \mathbf{pEqI} of *inequilogical spaces*, introduced in [12], is a directed version of D. Scott’s equilogical spaces [20, 19, 1]; an object of this category is a preordered topological space equipped with an equivalence relation, while a morphism is an equivalence class of preorder-preserving continuous mappings which respect the given equivalence relations (equivalent if they induce the same mapping, modulo the latter). There are various models of the directed circle, all ‘locally homotopy equivalent’, but the simplest (or the nicest) is perhaps the inequilogical space $\uparrow\bar{\mathbf{S}}_e^1 = (\uparrow\mathbf{R}, \equiv_{\mathbf{Z}})$, i.e. the quotient (in this category) of the *ordered* topological line $\uparrow\mathbf{R}$ modulo the action of the group \mathbf{Z} ([12], 1.7). The fundamental category of an inequilogical space is defined in [12], 2.4, and is based again on the directed interval $\uparrow\mathbf{I}$ (with equivalence relation the identity).

The powers of this directed circle $\uparrow\bar{\mathbf{S}}_e^1$ in \mathbf{pEqI} give the *inequilogical tori* $(\uparrow\bar{\mathbf{S}}_e^1)^n = (\uparrow\mathbf{R}^n, \equiv_{\mathbf{Z}^n})$, where directed paths have to turn ‘anticlockwise in each variable’; notice that, for $n \geq 2$, *this has nothing to do with orientation*, as was already the case for preordered spaces.

1.4. DIRECTED HOMOTOPY INVARIANCE. Let us summarise the problem we want to analyse.

In Algebraic Topology, the fundamental groupoid $\Pi_1(X)$ of a topological space is a homotopy invariant in a clear sense: a homotopy $\varphi: f \rightarrow g: X \rightarrow Y$ produces an isomorphism of the associated functors $f_*, g_*: \Pi_1(X) \rightarrow \Pi_1(Y)$, so that a homotopy equivalence $X \simeq Y$ produces *an equivalence of groupoids* $\Pi_1(X) \simeq \Pi_1(Y)$. Thus, a 1-dimensional homotopy model of the space is its fundamental groupoid, *up to groupoid-equivalence*; if we want a *minimal model*, we can always take a skeleton of the latter (choosing one point in each path component of the space).

In Directed Algebraic Topology, homotopy invariance requires a deeper analysis which we want to develop here, taking on a study begun in [10].

Now, paths and homotopies are no longer reversible, in general. Thus, a ‘directed topological structure’ (e.g. a preordered topological space) produces a fundamental category $\uparrow\Pi_1(X)$, and a homotopy $\varphi: f \rightarrow g: X \rightarrow Y$ only produces a natural transformation between the associated functors

$$\varphi_*: f_* \rightarrow g_*: \uparrow\Pi_1(X) \rightarrow \uparrow\Pi_1(Y), \quad \varphi_*x = [\varphi(x, -)]: f(x) \rightarrow g(x) \quad (x \in X), \quad (4)$$

which, generally, is *not* invertible, because the paths $\varphi(x, -): \uparrow\mathbf{I} \rightarrow Y$ need not be reversible.

Equivalence of categories is not, by far, sufficient to ‘link’ categories having—loosely speaking—the same appearance; and the problem of defining and constructing *minimal models* is important, both theoretically, for Directed Algebraic Topology, and in applications (see [5], where this problem is studied with the purpose of analysing concurrent processes).

1.5. DIRECTED HOMOTOPY FOR CATEGORIES. Let us begin with a description of *directed homotopy in \mathbf{Cat}* (the category of small categories), as presented in [10], 4.1. This elementary theory is based on the *directed interval* $\mathbf{2} = \{0 \rightarrow 1\}$, an order category on two objects, with the obvious *faces* $\partial^\pm: \mathbf{1} \rightarrow \mathbf{2}$ defined on the pointlike category $\mathbf{1} = \{*\}$. (We shall occasionally use the same notions for large categories.)

A *point* $x: \mathbf{1} \rightarrow X$ of a small category X is an object of the latter; we will also write $x \in X$. A (directed) *path* $a: \mathbf{2} \rightarrow X$ from x to x' is an arrow $a: x \rightarrow x'$ of X ; concatenation of paths amounts to composition in X (strictly associative, with strict identities). The (directed) *cylinder* functor $IX = X \times \mathbf{2}$ and its right adjoint, $PY = Y^{\mathbf{2}}$ (the category of morphisms of Y) show that a (directed) *homotopy* $\varphi: f \rightarrow g: X \rightarrow Y$ is the same as a natural transformation between functors; *their operations coincide with the 2-categorical structure of \mathbf{Cat}* .

The existence of a map $x \rightarrow x'$ in X (a path) produces the *path preorder* $x \prec x'$ (x reaches x') on the points of X ; the resulting *path equivalence* relation, meaning that there are maps $x \rightleftarrows x'$, will be written as $x \simeq x'$. For this preorder, a point x is

- *maximal* if it can only reach the points $\simeq x$,
- a *maximum* if it can be reached from every point of X ;

(the latter is the same as a *weak terminal* object, and is only determined up to path equivalence). If the category X ‘is’ a preorder, the path preorder coincides with the original relation.

For the fundamental category $X = \uparrow\Pi_1(T)$ of a preordered space T , note that the path-preorder $x \prec x'$ in X means that there is some directed path from x to x' in T , and *implies* the original preorder in T , which is generally coarser (cf. 1.2). Therefore, when the latter is an *order*, so must the path-preorder $x \prec x'$ be.

1.6. COMMA CATEGORIES AND HOMOTOPY PULLBACKS. The necessity of notions of directed homotopy in \mathbf{Cat} *already appears in the general theory of categories*, for instance in the diagrammatic properties of (co)comma squares.

Consider the pasting of two comma squares $X = f|g, Y = q|h$

$$\begin{array}{ccc}
 Y & \xrightarrow{p'} & X & \xrightarrow{p} & A \\
 q' \downarrow & \swarrow \beta & q \downarrow & \swarrow \alpha & \downarrow f \\
 D & \xrightarrow{h} & B & \xrightarrow{g} & C
 \end{array}
 \qquad
 \begin{array}{ccc}
 Z & \xrightarrow{p''} & A \\
 q'' \downarrow & \swarrow \gamma & \downarrow f \\
 D & \xrightarrow{gh} & C
 \end{array}
 \tag{5}$$

and the ‘global’ comma $Z = f|(gh)$. The categories Y and Z are generally *not* equivalent; but Z is—canonically—a *full reflective subcategory* of Y , with embedding i , reflector r and unit $\eta: 1 \rightarrow ir$ (with obvious notation: $a \in A$, etc.; u in C and v in B)

$$\begin{aligned}
 i: Z &\rightarrow Y, & r: Y &\rightarrow Z, & \eta: 1 &\rightarrow ir: Y \rightarrow Y, \\
 i(a, d; u: f(a) &\rightarrow gh(d)) &= (a, h(d), d; u: f(a) &\rightarrow gh(d), 1_{h(d)}), \\
 r(a, b, d; u: f(a) &\rightarrow g(b); v: b &\rightarrow h(d)) &= (a, d; g(v) \circ u: f(a) \rightarrow gh(d)), \\
 \eta(a, b, d; u, v) &= (1_a, v, 1_d): (a, b, d; u, v) &\rightarrow (a, hd, d; gv \circ u, 1_{hd}).
 \end{aligned}
 \tag{6}$$

Reversing the ‘direction’ of comma categories ($X = g|f$, $Y = h|q$, $Z = (gh)|f$), the global comma Z becomes a full *coreflective* subcategory of Y . Similar results hold for other diagrammatic properties of (co)commas. A general treatment should be based on the universal properties of the latter, to take advantage of duality and avoid the complicated construction of cocomma categories.

Now, a comma category in **Cat** corresponds to a *standard homotopy pullback* in **Top**, and it is well known that pasting homotopy pullbacks of spaces, as in (5), one obtains a space Y which is *homotopy equivalent* to the ‘global’ standard homotopy pullback Z . We should therefore be prepared to consider a full reflective *or* coreflective subcategory $Z \subset Y$ as ‘equivalent’ to Y , in some sense related with directed homotopy in **Cat**. And indeed, being full reflective (resp. coreflective) subcategories of a common one will amount to the notion of ‘future equivalence’ (resp. ‘past equivalence’) studied below. Future and past equivalences are thus natural tools to describe the diagrammatic properties of comma and cocomma categories.

2. Future and past homotopy equivalences

Directed homotopy equivalence of categories is introduced in two dual forms, which are meant to identify *future invariant* and *past invariant* properties, respectively. Each of them is a symmetric version of the notion of adjunction.

2.1. FUTURE HOMOTOPY EQUIVALENCES. A *homotopy equivalence in the future* $(f, g; \varphi, \psi)$ between the categories X, Y (as defined in [10]) consists of a pair of functors and a pair of natural transformations (i.e., directed homotopies), the *units*

$$f: X \rightleftarrows Y :g \quad \varphi: 1_X \rightarrow gf, \quad \psi: 1_Y \rightarrow fg, \quad (7)$$

which go *from* the identities of X, Y *to* the composed functors. This four-tuple will be called a *future equivalence*, or a *forward equivalence*, if the following coherence conditions hold

$$f\varphi = \psi f: f \rightarrow fgf, \quad \varphi g = g\psi: g \rightarrow gfg \quad (\text{coherence}). \quad (8)$$

Here, we shall only use the coherent form. A property (making sense *in* a category, or *for* a category) will be said to be *future invariant* if it is preserved by future equivalences. Some elementary examples will be discussed in 2.7; more interesting ones will follow in Section 6.

A future equivalence is a ‘variation’ of the notion of adjunction, and some aspects of the theory will be similar. But let us note at once that, in a future equivalence, f need not determine g (see (30)). Our data produce two natural transformations between hom-functors (which will often be used implicitly in what follows)

$$\begin{aligned} \Phi: Y(fx, y) &\rightarrow X(x, gy), & b &\mapsto gb.\varphi x & (\varphi x = \Phi(1_{fx}), f(\Phi(b)) = \psi y.b), \\ \Psi: X(gy, x) &\rightarrow Y(y, fx), & a &\mapsto fa.\psi y & (\psi y = \Psi(1_{gy}), g(\Psi(a)) = \varphi x.a). \end{aligned} \quad (9)$$

One can also note that an adjunction $f \dashv g$ with *invertible* counit $\varepsilon: fg \cong 1$ amounts to a future equivalence with invertible $\psi = \varepsilon^{-1}$; this case will be treated later and called a split future equivalence (2.4).

A future equivalence $(f, g; \varphi, \psi)$ will be said to be *faithful* if the functors f and g are faithful and, moreover, all the components of φ and ψ are *epi* and *mono*. (Motivations for the latter condition will appear in 2.4 and Thm. 2.5.) The next lemma (similar to classical properties of adjunctions) will prove that it suffices to know that *one* of the following equivalent conditions holds:

- (i) all the components of φ and ψ are mono,
- (ii) f and g are faithful and all the components of φ and ψ are epi.

Plainly, all future equivalences between preordered sets (viewed as categories) are faithful. There are non-faithful future equivalences where all unit-components are epi (see 2.8d). A faithful future equivalence between *balanced* categories (where every map which is mono *and* epi is an isomorphism) is plainly an equivalence. But a faithful future equivalence can link a balanced category with a non-balanced one (see (55)).

Dually, a *past equivalence*, or *backward equivalence*, has natural transformations in the opposite direction, *from* the composed functors *to* the identities, called *counits*

$$\begin{array}{lll} f: X \rightleftarrows Y :g & \varphi: gf \rightarrow 1, & \psi: fg \rightarrow 1, \\ f\varphi = \psi f: fgf \rightarrow f, & \varphi g = g\psi: gfg \rightarrow g & \text{(coherence).} \end{array} \tag{10}$$

An adjoint equivalence is at the same time a future and a past equivalence. Future equivalences, which will be shown to be linked with reflective subcategories and idempotent monads (2.4), will generally be given priority over the dual case (related with coreflective subcategories and comonads).

2.2. LEMMA. [Cancellation Lemma] *Let $(f, g; \varphi, \psi)$ be a future equivalence (2.1).*

- (a) *If all the components $\varphi x: x \rightarrow gfx$ are mono, then all of them are epi and f is faithful.*
- (b) *The transformation φ is invertible if and only if all its components are split mono; in this case f is right adjoint to g , full and faithful.*
- (c) *If g is faithful and all the components of φ are epi, then f preserves all epis.*
- (d) *If gf is faithful and all the components of φ are epi, then they are also mono.*
- (e) *The conditions (i) and (ii) of 2.1 are equivalent; when they hold, f and g preserve all epis.*

PROOF. (a) Assume that all the components φx are mono, and let $a_i.\varphi x = a$ in X ($i = 1, 2$).

$$\begin{array}{ccccc} x & \xrightarrow{\varphi x} & gfx & \xrightarrow{\varphi gfx} & fgfx \\ & \searrow a & \downarrow a_i & \dashrightarrow gfa & \downarrow gfa_i \\ & & x' & \xrightarrow{\varphi x'} & gfx' \end{array} \tag{11}$$

Since $\varphi g f = g f \varphi$ (by coherence) we have $\varphi x'.a_i = g f a_i . \varphi g f x = g f (a_i . \varphi x) = g f (a)$, and—cancelling $\varphi x'$ —we deduce $a_1 = a_2$. The faithfulness of $g f$ (hence of f) works as in adjunctions: given $a_i: x \rightarrow x'$ with $g f a_1 = g f a_2$, we get $\varphi x'.a_1 = g f a_i . \varphi x = \varphi x'.a_2$ and we cancel $\varphi x'$.

(b) The first assertion follows from (a). Then $g \dashv f$ with an invertible counit $\varphi^{-1}: g f \rightarrow 1$, which implies that f is full and faithful [18].

(c) Assume that g is faithful and that all the components of φ are epi. Given an epimorphism $a: x \rightarrow x'$, we have that $g f a . \varphi x = \varphi x'.a$ is also epi, whence $g f a$ is epi and $f a$ as well.

(d) Assume that $g f$ is faithful and that all the components of φ are epi. Let $\varphi x.a_i = a: x' \rightarrow g f x$; then $g f a_i . \varphi x' = \varphi x.a_i = a$; cancelling $\varphi x'$ we have $g f a_1 = g f a_2$, and $a_1 = a_2$.

(e) The equivalence of (i) and (ii) follows from (a) and (d); the last point from (c). ■

2.3. FUTURE HOMOTOPY EQUIVALENCE OF CATEGORIES. Future equivalences can be composed (much in the same way as adjunctions), which shows that *being future equivalent categories* is an equivalence relation. Given $(f, g; \varphi, \psi)$ (as in (7, 8)) and a second future equivalence

$$\begin{aligned} h: Y \rightleftharpoons Z : k, & & \vartheta: 1_Y \rightarrow k h, & \zeta: 1_Z \rightarrow h k, \\ h \vartheta = \zeta h: h \rightarrow h k h, & & \vartheta k = k \zeta: k \rightarrow k h k. \end{aligned} \quad (12)$$

their *composite* will be:

$$h f: X \rightleftharpoons Z : g k, \quad g \vartheta f . \varphi: 1_X \rightarrow g k . h f, \quad h \psi k . \zeta: 1_Z \rightarrow h f . g k. \quad (13)$$

Its coherence is proved by the following computation, where $f g \vartheta . \psi = \psi k h . \vartheta$

$$\begin{aligned} h f (g \vartheta f . \varphi) &= h (f g \vartheta f . f \varphi) = h (f g \vartheta f . \psi f) = h (f g \vartheta . \psi) f, \\ (h \psi k . \zeta) h f &= (h \psi k h . \zeta h) f = (h \psi k h . h \vartheta) f = h (\psi k h . \vartheta) f. \end{aligned} \quad (14)$$

(This composition is easily seen to be associative, with obvious identities.) The same holds in the *faithful* case. Indeed, using the form 2.1(ii), it suffices to note that the general component $g(\vartheta f x) . \varphi x$ is epi (also because g preserves epis, by 2.2e).

Two categories will be said to be *past and future equivalent* if they are both past equivalent and future equivalent. Generally, one needs *different* pairs of functors for these two notions (see 2.6); finer relations, linking the past and future structure, will be introduced later and give more interesting results. Marginally, we also consider *coarse equivalence* of categories, defined as the equivalence relation generated by past equivalence and future equivalence.

2.4. FULL REFLECTIVE SUBCATEGORIES AS FUTURE RETRACTS. We deal now with a special case of future equivalence, which is important for its own sake, but will also be shown (in Thm. 2.5) to generate the general case.

A *split* future equivalence of F into X (or of X onto F) will be a future equivalence $(i, p; 1, \eta)$ where the unit $1 \rightarrow p i$ is an identity

$$\begin{aligned} i: F \rightleftharpoons X : p & & \eta: 1_X \rightarrow i p & & \text{(the main unit)} \\ p i = 1_F, & & p \eta = 1_p, & & \eta i = 1_i & & (p \dashv i). \end{aligned} \quad (15)$$

We also say that F is a *future retract* of X . Note that p is now left adjoint to i , which is full and faithful. (Note also that $(i, p; 1, \eta)$ is a split mono in the category of future equivalences, with retraction $(p, i; \eta, 1)$.)

As in 2.1, we say that this future equivalence is *faithful* if all the components of η are mono; but, because of the adjunction, *this is equivalent to saying that p is faithful* (and implies that all the components of η are epi). In this case, we say that F is a *faithful future retract* of X .

Forgetting about direction, a future retract corresponds—in Topology—to a *strong deformation retract* (with an additional coherence condition, $p\eta = 1$). Here, this structure means that F is (isomorphic to) a *full reflective subcategory* of X , i.e. that there is a full embedding $i: F \rightarrow X$ with a left adjoint $p: X \rightarrow F$ (then p is essentially determined by i , and—via the universal property of the unit—can always be constructed so that the counit $pi \rightarrow 1_F$ be an identity, as we are assuming).

Equivalently, one can assign a *strictly idempotent monad* (e, η) on X

$$e: X \rightarrow X, \quad \eta: 1_X \rightarrow e, \quad ee = e, \quad e\eta = 1_e = \eta e. \tag{16}$$

Indeed, given $(i, p; \eta)$, we take $e = ip$; given (e, η) , we factor $e = ip$ splitting e through the subcategory F of X formed of the objects and arrows which e leaves fixed.

Dually, a *split past equivalence, of P into X* (or *of X onto P*) is a past equivalence $(i, p; 1, \varepsilon)$ where the counit $pi \rightarrow 1_P$ is an identity

$$\begin{array}{lll} i: P \rightleftarrows X : p & \varepsilon: ip \rightarrow 1_X & \text{(the counit)} \\ pi = 1_P, & p\varepsilon = 1_p, & \varepsilon i = 1_i \quad (i \dashv p). \end{array} \tag{17}$$

This amounts to saying that $i(P)$ is a *full coreflective subcategory* of X (with a choice of the coreflection making the unit $1 \rightarrow pi$ an identity); P will also be called a *past retract* of X .

2.5. THEOREM. [Future equivalence and reflective subcategories]

(a) A future equivalence $(f, g; \varphi, \psi)$ between X and Y (2.1) has a canonical factorisation into two split future equivalences

$$X \begin{array}{c} \xrightarrow{i} \\ \xleftarrow{p} \end{array} W \begin{array}{c} \xrightarrow{q} \\ \xleftarrow{j} \end{array} Y \quad (\eta: 1_W \rightarrow ip, \quad \eta': 1_W \rightarrow jq), \tag{18}$$

so that X and Y are full reflective subcategories of W . (It is a mono-epi factorisation in the category of future equivalences, through a sort of ‘graph’ of $(f, g; \varphi, \psi)$).

(b) Two categories are future equivalent if and only if they are full reflective subcategories of a third.

(c) Two categories are faithfully future equivalent if and only if they are faithful future retracts of a third.

(d) A property is future invariant if and only if it is preserved by all embeddings of full reflective subcategories, as well as by their reflectors. Similarly in the faithful case.

PROOF. (a). First, we construct the category W :

(i) an object is a four-tuple $(x, y; u, v)$ such that:

$$u: x \rightarrow gy \text{ (in } X), \quad v: y \rightarrow fx \text{ (in } Y), \quad gv.u = \varphi x, \quad fu.v = \psi y, \quad (19)$$

$$\begin{array}{ccc} x & \xrightarrow{u} & gy \\ & \searrow \varphi x & \downarrow gv \\ & & gfx \end{array} \qquad \begin{array}{ccc} y & \xrightarrow{v} & gy \\ & \searrow \psi y & \downarrow fu \\ & & fgy \end{array} \quad (20)$$

(ii) a morphism is a pair $(a, b): (x, y; u, v) \rightarrow (x', y'; u', v')$ such that:

$$a: x \rightarrow x' \text{ (in } X), \quad b: y \rightarrow y' \text{ (in } Y), \quad gb.u = u'.a, \quad fa.v = v'.b, \quad (21)$$

$$\begin{array}{ccc} x & \xrightarrow{u} & gy \\ a \downarrow & & \downarrow gb \\ x' & \xrightarrow{u'} & gy' \end{array} \qquad \begin{array}{ccc} y & \xrightarrow{v} & gy \\ b \downarrow & & \downarrow fa \\ y' & \xrightarrow{v'} & fgy' \end{array} \quad (22)$$

Then, we have a split future equivalence of X into W :

$$\begin{array}{ll} i: X \rightleftarrows W : p, & \eta: 1_W \rightarrow ip, \\ i(x) = (x, fx; \varphi x, 1_{fx}), & i(a) = (a, fa), \\ p(x, y; u, v) = x, & p(a, b) = a, \\ \eta(x, y; u, v) = (1_x, v): (x, y; u, v) \rightarrow (x, fx; \varphi x, 1_{fx}). & \end{array} \quad (23)$$

The correctness of the definitions is easily verified, as well as the coherence conditions: $pi = 1_W$, $p\eta = 1_p$, $\eta i = 1_i$ (in particular, i is well defined because the given equivalence is coherent.)

Symmetrically, there is a split future equivalence of Y into W :

$$\begin{array}{ll} j: Y \rightleftarrows W : q, & \eta': 1_W \rightarrow jq, \\ j(y) = (gy, y; 1_{gy}, \psi y), & j(b) = (gb, b), \\ q(x, y; u, v) = y, & q(a, b) = b, \\ \eta'(x, y; u, v) = (u, 1_y): (x, y; u, v) \rightarrow (gy, y; 1_{gy}, \psi y). & \end{array} \quad (24)$$

Finally, composing these two equivalences as in (18) (cf. (13)), gives back the original future equivalence $(f, g; \varphi, \psi)$

$$\begin{array}{ll} qi(x) = f(x), & qi(a) = f(a), \\ p\eta'i: 1_X \rightarrow pj.qi, & p\eta'i(x) = p\eta'(x, fx; \varphi x, 1_{fx}) = p(\varphi x, 1_{fx}) = \varphi x. \end{array} \quad (25)$$

Now, (b) follows immediately from (a). For (c), it suffices to modify the previous construction: if $(f, g; \varphi, \psi)$ is faithful, we use the full subcategory $W_0 \subset W$ on the objects $(x, y; u, v)$ where u and v are *mono*. Then, the functor i take values in W_0 (as $i(x) = (x, fx; \varphi x, 1_{fx})$); we restrict p, η and get a future retract which is faithful, since the general component $\eta(x, y; u, v) = (1_x, v)$ is obviously *mono*. Symmetrically for j, q, η' . (One can also use a smaller full subcategory W_1 , requiring that u, v be *mono and epi*).

Finally, (d) is an obvious consequence. ■

2.6. FUTURE CONTRACTIBLE CATEGORIES. We say that a category X is *future contractible* if it is future equivalent to $\mathbf{1}$ (the singleton category $\{*\}$); this happens if and only if X has a terminal object.

Indeed, if this is the case, we have a (split) future equivalence $t: \mathbf{1} \rightleftarrows X : p$ where $\eta x: x \rightarrow t(*)$ is the unique map to the terminal object of X . Conversely, a future equivalence $t: \mathbf{1} \rightleftarrows X : p$ necessarily splits: $pt = 1$; thus $t: \mathbf{1} \rightarrow X$ is right adjoint to p and preserves the terminal object. (More analytically: every object x has a map $\eta x: x \rightarrow t(*)$; and indeed a unique one: given $a: x \rightarrow t(*)$, the naturality of η implies $a = \eta x$.)

It is interesting to note that *faithful* contractibility is much more restrictive than the previous condition. In fact, *the* functor $p: X \rightarrow \mathbf{1}$ is faithful if and only if each hom-set of X has at most one element, which means that X ‘is’ a preordered set. Therefore, a category is *faithfully* future contractible—i.e. faithfully future equivalent to $\mathbf{1}$ —if and only if it is a *preordered set with a maximum*; and dually for the past.

Finally, a category is *past and future contractible* (i.e., past and future equivalent to $\mathbf{1}$) if and only if it has an initial *and* a terminal object. Then, the *future embedding* ($t: \mathbf{1} \rightarrow X$) and the *past* one ($i: \mathbf{1} \rightarrow X$) can only coincide if X has a zero object (this will amount to contractibility for the finer relation of injective equivalence studied later, see 5.4). Marginally, we also use the notion of *coarse contractibility*, meaning coarse equivalent to $\mathbf{1}$ (2.3). Examples for all these cases will be considered in 2.8.

The *future cone* C^+X , obtained by freely adding a terminal object to the category X , is future contractible; it is also past contractible if and only if X is past contractible or empty.

2.7. LEMMA. [Extremal points] *The following properties of an object $x \in X$ are future invariant:*

- (a) x is the terminal object of X ,
- (b) x is a weak terminal object of X , i.e. a maximum for the path preorder \prec (1.5),
- (c) x is maximal in X , for the path preorder,
- (d) x does not reach a maximal point z .

PROOF. Let $f: X \rightleftarrows Y : g$ be a future equivalence.

(a) Follows immediately from 2.6 (and 2.3): composing the future equivalence $t: \mathbf{1} \rightleftarrows X : p$ produced by the terminal object x with the given one, we get a composite $ft: \mathbf{1} \rightleftarrows Y : pg$, which shows that $ft(*) = f(x)$ is terminal in Y .

(b) If x is a maximum in X , for every $y \in Y$: $g(y) \prec x$ and $y \prec fg(y) \prec f(x)$.

(c) Let x be maximal and $f(x) < y$ in Y . Then $x \prec gf(x) \prec g(y)$ and all these points are equivalent, whence $f(x) \simeq fg(y)$. But $f(x) \prec y \prec fg(y)$ and $y \simeq f(x)$.

(d) Since z is maximal, from $z \prec gf(z)$ we deduce that $z \simeq gf(z)$. Therefore, if $f(x) \prec f(z)$ in Y , we have $x \prec gf(x) \prec gf(z) \simeq z$, and $x \prec z$ in X . ■

2.8. ELEMENTARY EXAMPLES.

(a) Let us begin with a few examples, produced by finite or countable ordered sets. For preordered sets (viewed as categories), a future equivalence consists of a pair of preorder-preserving mappings $f: X \rightrightarrows Y :g$ such that $1_X \leq gf$ and $1_Y \leq fg$, and *is necessarily faithful*. We already know that future contractibility means having a maximum

$$\bullet \quad \bullet \rightarrow \bullet \quad \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \quad (\text{past and future contractible}) \quad (26)$$

$$\begin{array}{ccc} \begin{array}{c} \bullet \\ \searrow \\ \bullet \rightarrow \bullet \end{array} & \begin{array}{c} \bullet \\ \searrow \\ \bullet \rightarrow \bullet \\ \nearrow \\ \bullet \end{array} & \dots \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \end{array} \quad (\text{just future contractible}) \quad (27)$$

$$\begin{array}{ccc} \begin{array}{c} \bullet \\ \nearrow \\ \bullet \rightarrow \bullet \end{array} & \begin{array}{c} \bullet \quad \bullet \\ \nearrow \quad \nearrow \\ \bullet \rightarrow \bullet \rightarrow \bullet \\ \searrow \quad \searrow \\ \bullet \end{array} & \dots \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \dots \end{array} \quad (\text{just past contractible}) \quad (28)$$

$$\begin{array}{ccc} \begin{array}{c} \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \\ \curvearrowright \quad \curvearrowleft \\ \bullet \end{array} & \begin{array}{c} \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \\ \curvearrowright \quad \curvearrowleft \\ \bullet \end{array} & \dots \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \dots \end{array} \quad (\text{just coarse-contractible}) \quad (29)$$

(b) Consider again (as in (28)) the ordered set \mathbf{n} of natural numbers, as a category. (Not to be confused with the monoid \mathbf{N} , a quite different category on one object.) There are future equivalences

$$\begin{array}{ll} f: \mathbf{n} \rightrightarrows \mathbf{n} :g, & f(x) = x, \\ g(x) = \max(x, x_0), & \varphi(x) = \psi(x): x \leq g(x), \end{array} \quad (30)$$

where $x_0 \in \mathbf{n}$ is arbitrary (and coherence automatically holds, since our categories are preorders). Thus, f does *not* determine g . Note also (in relation with a previous result, 2.2b) that all components $\psi(x)$ are mono and epi, but g is not full, i.e. does not reflect the preorder (when $x_0 > 0$).

(c) Now we consider some finite categories, generated by the directed graphs drawn below; the outer cells, marked with a cross, do not commute and these categories are not preorders. The category represented in (31) is (faithfully) future equivalent to the first in (32), past equivalent to the second, past and future equivalent to the third and coarse-equivalent to the last

$$\begin{array}{ccc} \begin{array}{c} \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \\ \curvearrowright \quad \quad \quad \curvearrowleft \\ 0 \rightarrow a \quad \quad \quad \times \quad \quad \quad b \rightarrow 1 \\ \curvearrowleft \quad \quad \quad \curvearrowright \\ \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \rightarrow \bullet \end{array} & & (31) \end{array}$$

$$\begin{array}{cccc} \begin{array}{c} 0 \rightarrow a \quad \times \quad 1 \\ \curvearrowright \quad \quad \quad \curvearrowleft \end{array} & \begin{array}{c} 0 \quad \times \quad b \rightarrow 1 \\ \curvearrowright \quad \quad \quad \curvearrowleft \end{array} & \begin{array}{c} 0 \rightarrow a \quad \times \quad b \rightarrow 1 \\ \curvearrowright \quad \quad \quad \curvearrowleft \end{array} & \begin{array}{c} 0 \quad \times \quad 1 \\ \curvearrowright \quad \quad \quad \curvearrowleft \end{array} & (32) \end{array}$$

This shows a situation of interest in concurrency. There is a given *starting point* 0, which is minimal (1.5), but *not* initial *nor* the unique minimal point (generally); and a given *ending point* 1, which is maximal. Moreover:

- 0 is also a *future branching* point, where one has to choose among different ways of going *forward*; being such is a future invariant property (as will be proved in Thm. 6.6);
- *a* is a *deadlock*, i.e. a maximal *unsafe vertex* (from where one cannot reach 1); this is again a future invariant property, as already proved in 2.7;
- *b* is a minimal *unreachable vertex* (which cannot be reached from 0); being such is a past invariant property (according to the dual of 2.7);
- 1 is a *past branching* point, preserved by past equivalences (Thm. 6.6).

The ‘past and future model’ above (the third category in (32)) *preserves all these properties*, while the coarse one only recognises that there are two paths from 0 to 1.

(d) Finally, the following category (described by generators and relations)

$$\begin{array}{ccc}
 0 & \xrightarrow{h} & a \\
 & \searrow h' & \downarrow u \\
 & & b \xrightarrow{k} 1
 \end{array}
 \quad
 \begin{array}{l}
 uh = vh = h', \\
 ku = kv = k',
 \end{array}
 \tag{33}$$

has an initial object (0) and a terminal one (1): it is past and future contractible, but *not* faithfully so. Note also that, in the future contraction, all the components of the unit ($x \rightarrow 1$) are epi.

3. Bilateral directed equivalences

In this section we study past and future equivalences *sharing one functor*, under the name of *pf-equivalences*. A particular case has been studied in category theory—essential localisations (3.7); the dual case, an *adjoint reflexive cograph* (3.6), should also be of interest.

The opposition between past and future is often marked with an index α which takes values 0, 1, written $-$, $+$ in superscripts (a standard notation in cubical homotopical algebra).

3.1. PF-EQUIVALENCES. We have already considered categories which are ‘separately’ past and future equivalent (e.g., in 2.6). However, an *unrelated* pair formed of a past equivalence and a future equivalence between the same categories is not an effective tool.

A *pf-equivalence from X to Y* will be a pair formed of a past equivalence ($f, g^-; \varepsilon_X, \varepsilon_Y$) and a future equivalence ($f, g^+; \eta_X, \eta_Y$) sharing the same functor $f: X \rightarrow Y$, and also

satisfying a further *pf-coherence* condition (35) linking the two pairs:

$$\begin{array}{ll}
f: X \rightarrow Y, & g^-, g^+: Y \rightarrow X, \\
\varepsilon_X: g^- f \rightarrow 1_X, & \varepsilon_Y: f g^- \rightarrow 1_Y, \\
f \varepsilon_X = \varepsilon_Y f: f g^- f \rightarrow f, & \varepsilon_X g^- = g^- \varepsilon_Y: g^- f g^- \rightarrow g^-, \\
\eta_X: 1_X \rightarrow g^+ f, & \eta_Y: 1_Y \rightarrow f g^+, \\
f \eta_X = \eta_Y f: f \rightarrow f g^+ f, & \eta_X g^+ = g^+ \eta_Y: g \rightarrow g^+ f g^+,
\end{array} \tag{34}$$

$$\begin{array}{ccc}
g^- & \xrightarrow{\eta_Y} & g^- f g^+ \\
\eta_X \downarrow & & \downarrow \varepsilon_X g^+ \\
g^+ f g^- & \xrightarrow{g^+ \varepsilon_Y} & g^+
\end{array} \quad (\text{pf-coherence}). \tag{35}$$

This yields a natural transformation, the *comparison* from past to future

$$g: g^- \rightarrow g^+: Y \rightarrow X, \quad g = \varepsilon_X g^+ \cdot g^- \eta_Y = g^+ \varepsilon_Y \cdot \eta_X g^- . \tag{36}$$

which—when convenient—will be seen as a functor $g: Y \rightarrow X^2$

$$g: Y \rightarrow X^2, \quad gy: g^- y \rightarrow g^+ y, \quad g(b) = (g^- b, g^+ b). \tag{37}$$

A pf-equivalence will often be written as $f: X \rightleftarrows Y$ or $f: X \rightleftarrows Y : g^\alpha$, leaving the rest understood. It will be said to be *faithful* if both the past and the future equivalence which compose it are faithful. By 2.1, this is the case if and only if our data satisfy these equivalent conditions:

- (i) all the components of η_X, η_Y (resp. $\varepsilon_X, \varepsilon_Y$) are mono (resp. epi),
- (ii) f, g^-, g^+ are faithful and all the components of η_X, η_Y (resp. $\varepsilon_X, \varepsilon_Y$) are epi (resp. mono).

Two dual types of pf-equivalences, where g^-, g^+ are ‘split’ adjoint to f , will be treated below.

3.2. COMPOSITION. A pf-equivalence is not a symmetric structure. But they compose, by the composition of past equivalences and future equivalences (2.3).

Given $f: X \rightleftarrows Y : g^\alpha$ (as in (34)) and a second pf-equivalence $h: Y \rightleftarrows Z : k^\alpha$

$$\begin{array}{l}
h: Y \rightleftarrows Z : k^\alpha \quad (\alpha = \pm), \\
\sigma_Y: k^- h \rightarrow 1_Y, \quad \sigma_Z: h k^- \rightarrow 1_Z, \quad \zeta_Y: 1_Y \rightarrow k^+ h, \quad \zeta_Z: 1_Z \rightarrow h k^+,
\end{array} \tag{38}$$

their composite is:

$$\begin{array}{l}
hf: X \rightleftarrows Z : g^\alpha k^\alpha \quad (\alpha = \pm), \\
\varepsilon_X \cdot g^- \sigma_Y f: g^- k^- \cdot hf \rightarrow g^- f \rightarrow 1_X, \\
\sigma_Z \cdot h \varepsilon_Y k^-: hf \cdot g^- k^- \rightarrow hf \cdot g^- k^- \rightarrow 1_Z, \dots
\end{array} \tag{39}$$

The following diagram shows that coherence holds (functors are replaced with $*$'s, in the labels of arrows)

$$\begin{array}{ccccc}
 g^-k^- & \xrightarrow{* \zeta_Z} & g^-k^- .hk^+ & \xrightarrow{* \eta_Y^*} & g^-k^- .hf.g^+k^+ \\
 \parallel & & \downarrow & \searrow & \downarrow \\
 g^-k^- & \xrightarrow{* \eta_Y^*} & g^-fg^+k^- & \xrightarrow{* \zeta_Z} & g^-f.g^+k^- .hk^+ & \xrightarrow{* \sigma_Y^*} & g^-f.g^+k^+ \\
 \eta_X^* \downarrow & \square & \downarrow \varepsilon_X^* & & \downarrow \varepsilon_X^* & & \downarrow \varepsilon_X^* \\
 g^+f.g^-k^- & \xrightarrow{* \varepsilon_Y^*} & g^+k^- & \xrightarrow{* \zeta_Z} & g^+k^- .hk^+ & & \\
 * \zeta_Y^* \downarrow & & * \zeta_Y^* \downarrow & \square & \downarrow * \sigma_Y^* & & \downarrow \varepsilon_X^* \\
 g^+k^+ .hf.g^-k^- & \xrightarrow{* \varepsilon_Y^*} & g^+k^+ .hk^- & \xrightarrow{* \sigma_Z} & g^+k^+ & \xlongequal{\quad\quad\quad} & g^+k^+
 \end{array} \quad (40)$$

In fact, the outer square commutes, because all the inner ones do, by pf-coherence of the data (*when marked with a box*) or by middle-four interchange.

3.3. LEMMA. [Pf-coherence] *In a pf-equivalence $f: X \rightleftarrows Y :g^\alpha$, the condition of pf-coherence is redundant (follows from the rest of the axioms) whenever f is faithful or surjective on objects.*

PROOF. Indeed, composing the diagram (35) with the functor f , we get two diagrams whose commutativity follows from the other coherence conditions and middle-four interchange

$$\begin{array}{ccc}
 fg^- & \xrightarrow{fg^- \eta_Y} & fg^- fg^+ \\
 f \eta_X g^- \downarrow & \varepsilon_Y \searrow & \downarrow f \varepsilon_X g^+ \\
 f.g^+ fg^- & \xrightarrow{fg^+ \varepsilon_Y} & f.g^+
 \end{array}
 \quad
 \begin{array}{ccc}
 g^-f & \xrightarrow{g^- \eta_Y f} & g^-fg^+f \\
 \eta_X g^- f \downarrow & \varepsilon_X \searrow & \downarrow \varepsilon_X g^+ f \\
 g^+fg^-f & \xrightarrow{g^+ \varepsilon_Y} & g^+f
 \end{array} \quad (41)$$

Since a faithful functor is left-cancellable with respect to *parallel* natural transformations ($f\varphi = f\psi$ implies $\varphi = \psi$), while a functor surjective on objects is right-cancellable, the thesis follows. \blacksquare

3.4. INJECTIONS AND PROJECTIONS.

(a) A pf-equivalence $f: X \rightleftarrows Y :g^\alpha$ will be called a *pf-injection*, or *pf-embedding*, if the functor f is a *full embedding* (i.e., full, faithful and injective on objects). Pf-embeddings compose, with the composition of pf-equivalences (3.2); they will produce the ‘injective models’ of a category (4.1).

It is easy to see that a pf-embedding $f: X \rightleftarrows Y : g^\alpha$ amounts to these three functors together with the *two* natural transformations *at* Y , satisfying the conditions below

$$\begin{aligned} \varepsilon_Y: fg^- &\rightarrow 1_Y && \text{(the main counit),} \\ \eta_Y: 1_Y &\rightarrow fg^+ && \text{(the main unit),} \\ fg^- \varepsilon_Y &= \varepsilon_Y fg^-, && fg^+ \eta_Y = \eta_Y fg^+. \end{aligned} \quad (42)$$

In fact, these data can be uniquely completed to a pf-injection: there is a unique natural transformation $\eta_X: 1_X \rightarrow g^+f$ (the *derived unit*) such that $f\eta_X = \eta_Y f: f \rightarrow fg^+f$ (because the latter transformation lives in the ‘full image’ of f in Y); the other relation comes from cancelling f in $f(\eta_X g^+) = \eta_Y fg^+ = f(g^+\eta_Y)$. Similarly, there is one $\varepsilon_X: g^-f \rightarrow 1_X$ such that $f\varepsilon_X = \varepsilon_Y f$. Finally, pf-coherence holds, by the previous Lemma.

(b) A pf-equivalence $f: X \rightleftarrows Y : g^\alpha$ will be called a *pf-surjection* if the functor f is surjective on objects, and a *pf-projection* if, moreover, the associated functor $g: Y \rightarrow X^2$ (37) is a full embedding. The latter structure will give a ‘projective model’ of the category X (4.1).

We already know that, in a pf-surjection, pf-coherence is automatic (3.3); it is also obvious that the transformations *at* Y are determined by the ones *at* X (since $\varepsilon_Y f = f\varepsilon_X$, $\eta_Y f = f\eta_X$), but here it seems to be less easy to deduce the former from the latter.

It is rather obvious that a general pf-equivalence $f: X \rightleftarrows Y : g^\alpha$ can be restricted to a pf-surjection $X \rightleftarrows Z$, replacing Y with the full subcategory Z of the objects of type fx ($x \in X$); this fact can be formulated in a more symmetric way (which is not a factorisation, generally).

3.5. THEOREM. [The middle model] *A pf-equivalence $f: X \rightleftarrows Y : g^\alpha$ has an associated pf-surjection and an associated pf-injection*

$$p: X \rightleftarrows Z : r^\alpha, \quad i: Z \rightleftarrows Y : h^\alpha, \quad (43)$$

where $f = ip$. This determines Z (the middle model), i and p up to category isomorphism. If the given pf-equivalence is faithful, so are the two associated ones.

(In general, the composition of these two pf-equivalences does not give back the original one. The pf-surjection need not be a pf-projection, but this will be true in the cases of interest.)

PROOF. The given units and counits will be written as in (34). Plainly, the functor $f: X \rightarrow Y$ has an essentially unique factorisation $f = ip$ where p is surjective on objects and $i: Z \rightarrow Y$ is a full embedding: take for Z the full subcategory on the objects fx ($x \in X$).

Then, we define the functors r^α, h^α ($\alpha = \pm$)

$$r^\alpha = g^\alpha i: Z \rightarrow X, \quad h^\alpha = pg^\alpha: Y \rightarrow Z, \quad (44)$$

so that:

$$\begin{aligned} r^\alpha p &= g^\alpha f, && ih^\alpha &= fg^\alpha, \\ pr^\alpha &= pg^\alpha i = h^\alpha i, && r^\alpha h^\alpha &= g^\alpha ipg^\alpha = g^\alpha fg^\alpha. \end{aligned} \quad (45)$$

(Here we can already note that $r^\alpha h^\alpha$ need not be g^α .) Now, for the pf-injection, we just need to observe that the original natural transformations ε_Y, η_Y work as *main* counit and unit (42)

$$\varepsilon_Y: ih^- = fg^- \rightarrow 1_Y, \quad \eta_Y: 1_Y \rightarrow ih^+ = fg^+, \quad (46)$$

since we already know that they commute with $ih^- = fg^-$ and $ih^+ = fg^+$, respectively.

On the other hand, the first pf-equivalence is completed with the natural transformations

$$\begin{aligned} \varepsilon_X: r^-p = g^-f \rightarrow 1_X, & & \eta_X: 1_X \rightarrow r^+p = g^+f, \\ \varepsilon_Z: pr^- \rightarrow 1_Z, & & i\varepsilon_Z = \varepsilon_Y i: ipr^- = fg^-i \rightarrow i, \\ \eta_Z: 1_Z \rightarrow pr^+, & & i\eta_Z = \eta_Y i: i \rightarrow ipr^+i = fg^+i, \end{aligned} \quad (47)$$

where ε_X, η_X are the original ones; ε_Z is a restriction of ε_Y (justified by the fact that $\varepsilon_Y i: fg^-i = ipr^- \rightarrow i$ lives in the full subcategory Z); and, similarly, η_Z is a restriction of η_Y .

Its coherence is deduced below, in brackets, from the homologous properties of the original data (recall that pf-coherence need not be checked, by 3.3)

$$\begin{aligned} p\varepsilon_X = \varepsilon_Z p & \quad (ip\varepsilon_X = f\varepsilon_X = \varepsilon_Y f = \varepsilon_Y ip = i\varepsilon_Z p), \\ \varepsilon_X r^- = r^- \varepsilon_Z & \quad (\varepsilon_X r^- = \varepsilon_X g^-i = g^- \varepsilon_Y i = g^- i\varepsilon_Z = r^- \varepsilon_Z), \\ p\eta_X = \eta_Z p & \quad (ip\eta_X = f\eta_X = \eta_Y f = \eta_Y ip = i\eta_Z p), \\ \eta_X r^+ = r^+ \eta_Z & \quad (\eta_X r^+ = \eta_X g^+i = g^+ \eta_Y i = g^+ i\eta_Z = r^+ \eta_Z). \end{aligned} \quad (48)$$

Finally, let us assume that the original pf-equivalence is faithful (3.1). We know that all the components of η_X, η_Y are mono, whence the components of $i\eta_Z = \eta_Y i$ are also, and the ones of η_Z as well, since i is faithful; dually for counits. ■

3.6. SPLIT PF-INJECTIONS. A *split pf-injection*, or *adjoint reflexive cograph*, will be a pf-equivalence $i: E \rightleftarrows X : p^\alpha$ where the natural transformations $p^-i \rightarrow 1_E$ and $1_E \rightarrow p^+i$ are identities.

So it consists of three functors $i: E \rightleftarrows X : p^\alpha$ and two natural transformations ε and η such that:

$$\begin{aligned} i: E \rightarrow X, & & p^+ \dashv i \dashv p^-, \\ \varepsilon: ip^- \rightarrow 1_X \text{ (the past counit),} & & \eta: 1_X \rightarrow ip^+ \text{ (the future unit),} \\ p^-i = 1_E = p^+i, & & \\ p^-\varepsilon = 1, \quad \varepsilon i = 1, & & p^+\eta = 1, \quad \eta i = 1. \end{aligned} \quad (49)$$

Note that i is a full embedding, so that we do have a pf-injection; moreover, it essentially determines the rest of the structure: it embeds E as a full subcategory, reflective and coreflective, with reflector p^+ and coreflector p^- . Conversely, given a *full subcategory*, *reflective and coreflective*, we can always choose the reflector so that the counit be an identity, and the coreflector so that the unit be an identity.

Pf-coherence yields one comparison $p: p^- \rightarrow p^+$ from the right adjoint to the left:

$$p = p^-\eta = p^+\varepsilon: p^- \rightarrow p^+: X \rightarrow E \quad (\eta.\varepsilon = ip^-\eta = ip^+\varepsilon: ip^- \rightarrow ip^+), \quad (50)$$

(the right-hand formulas, which follow from middle-four interchange or (41), can also be useful).

Examples related with the present notions will be given in Section 5. Forgetting about smallness, there is a nice example linked with homology (which the author learned from F.W. Lawvere). Start from the embedding $i: G_*\mathbf{Ab} \rightarrow C_*\mathbf{Ab}$ of graded abelian groups into chain complexes, as complexes with a null differential. The left and right adjoints are computed, on a chain complex $A = (A_*, \partial_*)$, as

$$p^+A = \text{Coker}(\partial_*) = A_*/\partial_*(A_*), \quad p^-A = \text{Ker}(\partial_*), \quad (51)$$

and the graded group $H_*(A)$ can be defined as the image of the comparison $pA: p^-A \rightarrow p^+A$. Note the symmetry of this presentation.

3.7. SPLIT PF-PROJECTIONS. The dual notion of *split pf-projection* is well-known in category theory: it has been studied under the name of *essential localisation* [16, 2], or ‘unity and identity of adjoint opposites’ [17]; presently, the term ‘adjoint reflexive graph’ is also used by F.W. Lawvere.

It can be presented as a pf-equivalence $p: X \rightleftarrows M : i^\alpha$ where the natural transformations $pi^- \rightarrow 1_M$ and $1_M \rightarrow pi^+$ are identities. The structure consists thus of three functors and two natural transformations satisfying:

$$\begin{aligned} p: X &\rightarrow M, & i^- \dashv p \dashv i^+, \\ \varepsilon: i^-p &\rightarrow 1_X \text{ (the past counit),} & \eta: 1_X \rightarrow i^+p \text{ (the future unit),} \\ pi^- &= 1_M = pi^+, & \\ p\varepsilon = 1, \quad \varepsilon i^- &= 1, & p\eta = 1, \quad \eta i^+ = 1. \end{aligned} \quad (52)$$

Note that i^- and i^+ are full and faithful, because the past unit and the future counit are invertible. (Starting from a pair of adjunctions $i^- \dashv p \dashv i^+$ in a 2-category, it is well known—but not obvious—that the unit of the first adjunction is invertible if and only if the counit of the second is; cf. [16], Prop. 2.3.)

Again, pf-coherence yields *one* comparison $i: i^- \rightarrow i^+$

$$i = \eta i^- = \varepsilon i^+: i^- \rightarrow i^+: M \rightarrow X \quad (\eta.\varepsilon = \eta i^- p = \varepsilon i^+ p: i^- p \rightarrow i^+ p). \quad (53)$$

Finally, p is obviously surjective on objects (and maps as well). Moreover, each functor i^α is a section, whence the comparison $i: M \rightarrow X^2$ is an embedding. To prove that it is full, take a morphism in X^2 , from iy to iy' ; since i^- and i^+ are full (3.7), we have a commutative square

$$\begin{array}{ccc} i^-y & \xrightarrow{iy} & i^+y \\ i^-b' \downarrow & & \downarrow i^+b'' \\ i^-y' & \xrightarrow{iy'} & i^+y \end{array} \quad i = \eta i^- = \varepsilon i^+. \quad (54)$$

Applying p , and noting that the natural transformation pi is the identity, we deduce that $b' = b''$; calling $b: y \rightarrow y'$ this morphism of M , it follows that $i(b): iy \rightarrow iy'$ is the given square.

Again, examples will be given in Section 5. But we can already note that the forgetful functor $p: \mathbf{Top} \rightarrow \mathbf{Set}$ from topological spaces to sets has such a structure, with left (resp. right) adjoint provided by the discrete (resp. coarse) topology

$$p: \mathbf{Top} \rightleftarrows \mathbf{Set} : i^\alpha, \quad i^- \dashv p \dashv i^+ \quad (\varepsilon: i^- p \rightarrow 1, \eta: 1 \rightarrow i^+ p), \quad (55)$$

(so that \mathbf{Set} is a faithful projective model of \mathbf{Top} , as defined in 4.1).

3.8. TWO STRUCTURAL PF-EQUIVALENCES. (a) Any category X has a structural split pf-injection *into* X^2 , determined by the cocylinder structure of the latter (or, equivalently, by the structure of $\mathbf{2}$ as a reflexive graph in \mathbf{Cat})

$$\begin{aligned} e: X \rightleftarrows X^2 : \partial^\alpha, & \quad e(x) = 1_x: x \rightarrow x; & \quad \partial^\alpha(a: x^- \rightarrow x^+) = x^\alpha, \\ \varepsilon(a: x^- \rightarrow x^+) = (1, a): 1_{x^-} \rightarrow a & & \quad (\text{the counit}), \\ \eta(a: x^- \rightarrow x^+) = (a, 1): (a: x^- \rightarrow x^+) \rightarrow 1_{x^+} & & \quad (\text{the unit}), \\ \partial = id: X^2 \rightarrow X^2 & & \quad (\text{the comparison}); \end{aligned} \quad (56)$$

4. Injective and projective models

Injective and projective models, defined in 4.1, will be our main tool. A pf-presentation of a category, formed of a past and a future retract (4.2), produces an injective model (4.3) and a projective one (4.6).

4.1. DEFINITION. (a) Let $i: E \rightleftarrows X$ be a pf-embedding (i.e. a pf-equivalence where i is a full embedding, 3.4). In this situation, we say that E is an *injective model* of X , and that X is *injectively modelled* by E .

Two categories will be said to be *injectively equivalent* if they can be linked by a finite chain of pf-embeddings, forward or backward. *Faithful* pf-injections (3.1) give raise to *faithful injective models* and *faithfully injectively equivalent* categories.

(b) Similarly, a *projective model* M of X is given by a pf-projection $p: X \rightleftarrows M : r^\alpha$ (3.4), and will generally be seen as a full subcategory $r: M \rightarrow X^2$. The *projective equivalence* relation is generated by pf-projections. The *faithful* case is defined analogously.

In the rest of this section, *the faithful case will generally be inserted in square brackets*.

4.2. PF-PRESENTATIONS. We introduce now another structure which combines past and future notions, and will then show how it produces an injective model (4.3) and a projective one (4.6).

A [faithful] *pf-presentation* of the category X will be a diagram consisting of a [faithful] past retract P and a [faithful] future retract F of X (which are thus a full coreflective

transformation $\eta_E: 1_E \rightarrow j^+q^+$ such that $u\eta_E = \eta u$, and it is easy to verify that $\eta_E j^+ = 1$ and $q^+ \eta_E = 1$.

(e) Then, we complete the pf-embedding letting $r^\alpha = j^+p^\alpha: X \rightarrow E$ and observe that:

$$ur^+ = uj^+p^+ = i^+p^+, \quad r^+u = j^+p^+u = j^+q^+. \quad (60)$$

Therefore, we can take the natural transformation

$$\eta: 1_X \rightarrow i^+p^+ = ur^+, \quad (61)$$

as main unit (42) of the pf-embedding $u: E \rightleftarrows X : r^\alpha$; the derived one is η_E , by (c); and similarly for counits. Finally, (f) is a straightforward consequence of $i^\alpha p^\alpha = ur^\alpha$.

[The faithful case is proved in the same way. Point (d) requires a specific argument (as in 3.5): we know that all the components of η are mono, whence so are the components of $u\eta_E = \eta u$, and also the ones of η_E , since u is faithful; dually for counits.] ■

4.4. FACTORISATION OF ADJUNCTIONS. We have already seen, in Thm. 2.5, that a future equivalence has a canonical factorisation into a future section followed by a future retraction. Similarly, we show now that an adjunction has a canonical factorisation into a *past section* (the embedding of a full coreflective subcategory) followed by a *future retraction* (the reflection onto a full reflective subcategory). Within the category of adjunctions, this factorisation is functorial (cf. [14]) and mono-epi, but we shall not need these facts.

Let $f: X \rightleftarrows Y : g$ be an adjunction, with $\eta: 1 \rightarrow gf$ and $\varepsilon: fg \rightarrow 1$. We shall factor it through the following comma category, the *graph* of the adjunction

$$W = f|Y = X|g, \quad (62)$$

where we identify an object $(x, y; u: x \rightarrow gy)$ of the category $X|g$ with the corresponding $(x, y; v: fx \rightarrow y)$ in $f|Y$. The factorisation is obvious

$$X \begin{array}{c} \xrightarrow{i^-} \\ \xleftarrow{p^-} \end{array} W \begin{array}{c} \xrightarrow{p^+} \\ \xleftarrow{i^+} \end{array} Y \quad i^- \dashv p^-, \quad p^+ \dashv i^+, \quad (63)$$

$$\begin{aligned} i^-(x) &= (x, fx; 1: fx \rightarrow fx), & p^-(x, y; v: fx \rightarrow y) &= x, \\ \varepsilon_W: i^- p^- &\rightarrow 1_W, \end{aligned} \quad (64)$$

$$\begin{aligned} \varepsilon_W(x, y; v: fx \rightarrow y) &= (1_x, v): (x, fx; 1_{fx}) \rightarrow (x, y; v: fx \rightarrow y), \\ i^+(y) &= (gy, y; 1: gy \rightarrow gy), & p^+(x, y; u: x \rightarrow gy) &= y, \\ \eta_W: 1_W &\rightarrow i^+ p^+, \\ \eta_W(x, y; u: x \rightarrow gy) &= (u, 1_y): (x, y; u: x \rightarrow gy) \rightarrow (gy, y; 1_{gy}). \end{aligned} \quad (65)$$

In fact, composing these split adjunctions we get back the original one:

$$\begin{aligned} p^+ i^-(x) &= fx, & p^- i^+(y) &= gy, \\ (p^- \eta_W i^-)(x) &= p^- \eta_W(x, fx; 1_{fx}) = p^-(\eta x, 1_y) = \eta x, \\ (p^+ \varepsilon_W i^+)(y) &= p^+ \varepsilon_W(gy, y; 1_{gy}) = p^+(1_x, \varepsilon y) = \varepsilon y. \end{aligned} \quad (66)$$

The lower row is the canonical factorisation of the composed adjunction $P \rightleftarrows F$ (62), through its graph, the category W , which (here) can be embedded as a full subcategory of X^2

$$W = (P|p^-i^+) = (p^+i^-|F) = (i^-|i^+) \subset X^2. \quad (72)$$

Then, there is a pf-equivalence $f: X \rightleftarrows W : r^\alpha$, with

$$r^\alpha f = i^\alpha p^\alpha, \quad j^\alpha = f i^\alpha, \quad (73)$$

which inherits the counit ε from the adjunction $i^- \dashv p^-$ and the unit η from $p^+ \dashv i^+$; its comparison $r: W \rightarrow X^2$ coincides with the embedding $(i^-|i^+) \subset X^2$.

Finally, replacing W with the full subcategory M of objects of type fx (for $x \in X$) we have a projective model $p: X \rightleftarrows M$. The adjunctions of the lower row can be restricted to M (since $j^\alpha = f i^\alpha$), so that P and F are also, canonically, a past and a future retract of M .

(b) If the given pf-presentation of X is faithful, proceeding as above with the faithful graph W_0 (4.5), the full subcategory of W (and X^2) on the objects $(x, y; w: i^-x \rightarrow i^+y)$ such that:

$$p^-w: x \rightarrow p^-i^+y \text{ is mono and } p^+w: p^+i^-x \rightarrow y \text{ is epi.} \quad (74)$$

we obtain a faithful projective model $p: X \rightleftarrows M_0$.

PROOF. (a) The comma category $W = (i^-|i^+)$ is a full subcategory of X^2 , because both i^α are full embeddings; it has a canonical isomorphism with the graph $(P|p^-i^+) = (p^+i^-|F)$

$$\begin{aligned} (i^-|i^+) \rightarrow (P|p^-i^+), & \quad (x, y; w: i^-x \rightarrow i^+y) \mapsto (x, y; p^-w: x \rightarrow p^-i^+y), \\ (P|p^-i^+) \rightarrow (i^-|i^+), & \quad (x, y; u: x \rightarrow p^-i^+y) \mapsto (x, y; \varepsilon i^+y. i^-u: i^-x \rightarrow i^+y), \\ p^-(\varepsilon i^+y. i^-u) = u, & \quad \varepsilon i^+y. i^-p^-w = w. \varepsilon x = w. \varepsilon i^-p^-x = w. \end{aligned} \quad (75)$$

We define the three functors $f: X \rightleftarrows W : r^\alpha$

$$\begin{aligned} f(x) &= (p^-x, p^+x; \eta x. \varepsilon x: i^-p^-x \rightarrow i^+p^+x), \\ r^-(x, y; w: i^-x \rightarrow i^+y) &= i^-x, \quad r^+(x, y; w: i^-x \rightarrow i^+y) = i^+y, \end{aligned} \quad (76)$$

and observe that they satisfy the relations (73). Then, we complete the pf-equivalence with the following counits and units (ε, η are the given ones):

$$\begin{aligned} \varepsilon_X &= \varepsilon: r^-f = i^-p^- \rightarrow 1_X, & \eta_X &= \eta: 1_X \rightarrow r^+f = i^+p^+, \\ \varepsilon_W &= fr^- \rightarrow 1_W, & \eta_W &= 1_W \rightarrow fr^+, \\ \varepsilon_W(x, y; w: i^-x \rightarrow i^+y) &= & & \\ (1_x, p^+w): (x, p^+i^-x; \eta i^-x: x \rightarrow i^+p^+i^-x) &\rightarrow (x, y; w: i^-x \rightarrow i^+y), & & \\ \eta_W(x, y; w: i^-x \rightarrow i^+y) &= & & \\ (p^-w, 1_y): (x, y; w: i^-x \rightarrow i^+y) &\rightarrow (p^-i^+y, y; \varepsilon i^+y: i^-p^-i^+y \rightarrow y). \end{aligned} \quad (77)$$

The coherence conditions are easily verified. Moreover, the comparison functor $r: W \rightarrow X^2$ (coming from the natural transformation $r = \varepsilon_X r^+ . r^- \eta_W: r^- \rightarrow r^+$) coincides with the full embedding $(i^- | i^+) \subset X^2$ (use (75))

$$\begin{aligned} r(x, y; w: i^- x \rightarrow i^+ y) &= \varepsilon_X i^+ y . r^-(p^- w, 1_y) = \varepsilon i^+ y . i^- p^- w = w, \\ r(a, b) &= (i^- a, i^+ b). \end{aligned} \quad (78)$$

The last assertion follows from 3.5, since $M \subset W \subset X^2$ is also full in the latter.

(b) Assume that the given pf-presentation is faithful. We know (from 4.5) that the presentation of W_0 is also faithful; moreover, the right adjoint p^- preserves monos and the left adjoint p^+ preserves epis. It follows that $f: X \rightarrow W$ takes values in W_0 . The restricted pf-equivalence $X \rightleftarrows W_0$ is faithful, because its units $\eta_X = \eta$ and $\eta_{W_0}(x, y; w) = (p^- w, 1_y)$ have monic components, while the counits have epi components. Finally, the associated projective model is faithful as well (3.5). ■

4.7. FROM INJECTIVE TO PROJECTIVE MODELS. In particular, a *split* injective model $i: E \rightleftarrows X : p^\alpha$ has an *associated* projective model (which is generally not split, cf. 5.5). In fact, our structure gives a pf-presentation

$$E \begin{array}{c} \xrightarrow{i} \\ \xleftarrow{p^-} \end{array} X \begin{array}{c} \xrightarrow{p^+} \\ \xleftarrow{i} \end{array} E \quad \varepsilon: ip^- \rightarrow 1_X, \quad \eta: 1_X \rightarrow ip^+, \quad (79)$$

which produces, as above, a pf-equivalence based on the comparison $p: p^- \rightarrow p^+$ as a functor

$$p: X \rightleftarrows E^2 : i^\alpha, \quad E^2 = (i | i) \subset X^2, \quad (80)$$

and a pf-projection $p': X \rightleftarrows E'$ with values in the full subcategory $E' \subset E^2$ whose objects are the morphisms $p x: p^- x \rightarrow p^+ x$. (Example 5.5 will show that this can be a proper subcategory).

5. Minimal models of a category

In this section, pf-equivalences are used to analyse a category, via injective and projective models. The faithful case is considered at the end, in 5.7.

5.1. ORDINARY SKELETA. Let us briefly review the usual, non-directed notion of a skeleton (cf. [18]). A category is said to be *skeletal* if it has a unique object in each class of isomorphism; two equivalent skeletal categories are necessarily isomorphic.

The *skeleton* of a category X is a skeletal category equivalent to the former, determined up to isomorphism of categories. It always exists: *choose* one object in each class of isomorphic objects of X and take their full subcategory (whose embedding in X is faithful, full and essentially surjective on objects). Two categories are equivalent if and only if their skeleta are isomorphic, so that *skeleta classify equivalence classes of categories*.

For our present analysis, it will be useful to note two facts. First, the skeleton of a category X can be defined as a category E such that:

- (a) E has an equivalent embedding into X ,
- (b) every equivalent embedding $E' \rightarrow E$ is an isomorphism of categories,

where 'equivalent embedding' denotes an equivalence of categories which is injective on objects.

Second, the uniqueness of the skeleton of a category X can be expressed as follows: given two skeleta $i: E \rightarrow X$ and $j: E' \rightarrow X$

- (c) there is a unique mapping $u: ObE \rightarrow ObE'$ such that, for every $z \in E$, $i(z) \cong ju(z)$ in X ,
- (d) for every choice of a family of isomorphisms $\lambda(z): i(z) \rightarrow ju(z)$, the mapping u has a unique extension to a functor $u: E \rightarrow E'$ making that family a natural isomorphism $\lambda: i \rightarrow ju$.

Thus, the equivalent embedding $E \rightarrow X$ is determined up to a natural isomorphism, which is not unique.

5.2. MINIMAL MODELS. (a) By definition, an injective model of the category X is given by a pf-embedding $i: E \rightleftarrows X$ (4.1). We say that E is a *minimal injective model* of X if:

- (i) E is an injective model of every injective model E' of X ,
- (ii) every injective model E' of E is isomorphic to E .

We say that it is a *strongly minimal injective model* if it satisfies the stronger condition (i'), together with (ii):

- (i') E is an injective model of every category injectively equivalent to X .

Note that we are not requiring any consistency of the embeddings. Thus, the minimal injective model of a category X is determined up to isomorphism (when existing); *but the isomorphism itself is generally undetermined*, and the pf-embedding $E \rightarrow X$ will not even be determined up to isomorphism, as we will see in various examples (cf. 5.5, 5.6).

Plainly, two categories having a common injective model are injectively equivalent. Moreover, *strongly minimal injective models classify injective equivalence* (when they exist): if the category X has a strongly minimal injective model E , then the category Y is injectively equivalent to X if and only if E is also an injective model of Y (in which case, it is also a strongly minimal injective model of the latter).

- (b) Similarly, a *projective model* of X is given by a pf-projection $p: X \rightleftarrows M$ (4.1). We define a (strongly) *minimal projective model* of X as above.

We shall see that the two notions are different: a category with initial and terminal object is always projectively contractible, while it is injectively contractible if and only if it is pointed (5.4). Other comparisons are in Section 9, and in the Introduction; injective models will often give a finer analysis.

Note that, even if the projective model M is a full subcategory of X^2 , we are *not* interested in the minimal *injective* model of the latter, which is injectively equivalent to X (3.8a).

(c) Let us begin considering the case of a groupoid X . Every full subcategory E containing at least one object in each class of isomorphic objects is an injective model (since the embedding can be completed to an adjoint equivalence, which can be viewed as a past and a future equivalence). Therefore, the ordinary skeleton of a groupoid is its minimal injective model. The same holds in the projective case.

5.3. LEMMA. *Let $i: E \rightleftarrows X : r^\alpha$ be a pf-embedding.*

(a) *The functor i preserves and reflects the existence of the initial and terminal objects, as well as their being isomorphic or not.*

(b) *The three functors i, r^-, r^+ preserve the zero object.*

PROOF. (a) The functor i is part of a past and a future equivalence, therefore it preserves the initial and terminal object (Lemma 2.7), their being isomorphic (obviously) or not (being full and faithful). Suppose now that X has an initial object 0 and a terminal one, 1 . Then $r^-(0)$ is initial and $r^+(1)$ is terminal in E ; moreover $ir^-(0) \cong 0$ (because it is also initial in X) and $ir^+(1) \cong 1$, so that $0 \cong 1$ in X if and only if $r^-(0) \cong r^+(1)$ in E (again because i is full and faithful). The point (b) has also been proved. ■

5.4. INJECTIVE AND PROJECTIVE CONTRACTIBILITY. We say that a category X is *injectively contractible* if it is injectively equivalent to $\mathbf{1}$. This condition is equivalent to the following ones:

- (a) X is pointed (i.e., it has a zero object),
- (b) $\mathbf{1}$ is a (split) injective model of X ,
- (c) $\mathbf{1}$ is a strongly minimal injective model of X .

Indeed, if X is injectively equivalent to $\mathbf{1}$ then it is pointed (because of the previous Lemma). If this is true, then we have functors $i: \mathbf{1} \rightleftarrows X : p$ with $p \dashv i \dashv p$, so that $\mathbf{1}$ is a (split) injective model of X . In this case, strong minimality is obvious. Finally, (c) trivially implies that X is injectively equivalent to $\mathbf{1}$.

On the other hand, a category X with non-isomorphic initial and terminal object is injectively modelled by the ordinal $\mathbf{2} = \{0 \rightarrow 1\}$, with the obvious pf-embedding $i: \mathbf{2} \rightleftarrows X : r^\alpha$ (not split)

$$\begin{aligned} r^-(x) &= 0, & \varepsilon_E(z) &: 0 \rightarrow z, & \varepsilon(x) &: 0 \rightarrow x, \\ r^+(x) &= 1, & \eta_E(z) &: z \rightarrow 1, & \eta(x) &: x \rightarrow 1. \end{aligned} \tag{81}$$

This is actually *the strongly minimal injective model* of X . Indeed, again by the previous Lemma, every category injectively equivalent to X has an initial and terminal object which are not isomorphic, and is thus injectively modelled by $\mathbf{2}$. Second, any injective model $E' \rightarrow \mathbf{2}$ is surjective on objects (and a full embedding), whence an isomorphism.

It is interesting to note that $\mathbf{2}$, the *standard interval* of \mathbf{Cat} , is *not* contractible in this sense.

On the other hand, on the projective side, the existence of the initial and terminal objects is sufficient (and necessary) to make a category X *projectively equivalent* to $\mathbf{1}$, via the split pf-projection $p: X \rightleftarrows \mathbf{1} : i^\alpha$, with $i^-(*) = 0$ and $i^+(*) = 1$.

In all these cases, the *faithful* analogue restricts the categories X to preorders (as in 2.6).

5.5. THE MODEL OF THE ORDERED LINE. (Here, all the categories will be ordered sets, so that all coherence conditions are automatically satisfied and all equivalences are faithful.) We want to model the ordered real line \mathbf{r} as a category; note that it is the fundamental category of the ordered topological space $\uparrow\mathbf{R}$.

The full subcategory \mathbf{z} of integers is a *split injective model* of \mathbf{r} , with the inclusion $i: \mathbf{z} \subset \mathbf{r}$ and

$$\begin{aligned} p^-(x) &= \max\{k \in \mathbf{z} \mid k \leq x\}, & \varepsilon x: ip^-(x) \leq x, & & p^-i = id & (i \dashv p^-), \\ p^+(x) &= \min\{k \in \mathbf{z} \mid k \geq x\}, & \eta x: x \leq ip^+(x), & & p^+i = id & (p^+ \dashv i); \end{aligned} \tag{82}$$

(p^- is the integral part, and $p^+(x) = -p^-(-x)$).

It is indeed a *minimal* injective model of \mathbf{r} . For every injective model $u: E \rightleftarrows \mathbf{r} : r^\alpha$, E is a subset of \mathbf{r} with the induced preorder, necessarily *initial*, i.e. ‘past unbounded’ (since $ur^-(x) \leq x$), and *final* i.e. ‘future unbounded’; choosing an arbitrary order-preserving embedding $(x_k)_{k \in \mathbf{z}}$ of \mathbf{z} into E , unbounded both ways, we have again a split pf-injection $\mathbf{z} \rightarrow E$ (with right and left adjoint constructed as above). Moreover, if E is an injective model of \mathbf{z} , then it is unbounded there and necessarily order-isomorphic to it.

Of course, \mathbf{r} contains various minimal injective models, all isomorphic but not isomorphically embedded (since the only isomorphisms of \mathbf{r} are the identities); e.g. $2\mathbf{z}$ (properly contained in \mathbf{z}) and $1/2 + \mathbf{z}$ (disjoint from \mathbf{z}). Injective models of trees will be considered later (9.1).

By 4.7, the split pf-injection $\mathbf{z} \rightarrow \mathbf{r}$ has an associated pf-equivalence $p: \mathbf{r} \rightleftarrows \mathbf{z}^2 : g^\alpha$ with values in the order category of pairs of integers (k, k') with $k \leq k'$

$$p(x) = (p^-x, p^+x), \quad g^-(k, k') = k, \quad g^+(k, k') = k', \tag{83}$$

which—essentially—sends a real number to the least interval $[k, k']$ with integral end-points, containing it. Reducing the codomain of p to the full subcategory $\mathbf{z}' \subset \mathbf{z}^2$ of pairs (k, k') with $0 \leq k' - k \leq 1$, we get the associated projective model $p': \mathbf{r} \rightleftarrows \mathbf{z}'$, which is not split ($p'g^-(k, k') = (k, k)$).

It is interesting to note that there is no split pf-projection $\mathbf{r} \rightarrow \mathbf{z}$; in fact, the pre-images of integers would form a sequence of disjoint compact intervals $I_k = [i^-(k), i^+(k)]$, with I_k (strictly) preceding I_{k+1} ; but such a sequence cannot cover the line, leaving gaps $]i^+(k), i^-(k+1)[$.

5.6. THE MODEL OF THE DIRECTED CIRCLE. Consider now (as in 1.3) the subcategory \mathbf{c} of the fundamental groupoid $\Pi_1(\mathbf{S}^1)$ of the circle containing all points and the homotopy classes of those paths which move ‘anticlockwise’ in the plane \mathbf{R}^2 .

We prove now that the minimal injective model of \mathbf{c} is its full subcategory E at a(ny) point x , which we identify with the additive monoid \mathbf{N} of the natural numbers. (It is the fundamental monoid of the inequilogical circle $\uparrow\bar{\mathbf{S}}_e^1 = (\uparrow\mathbf{R}, \equiv_{\mathbf{Z}})$ considered in 1.3).

First, we show that the embedding $i: E \rightarrow \mathbf{c}$ has a left and a right adjoint, forming a split pf-injection

$$\begin{aligned} i: E \rightarrow \mathbf{c}, & & p^+ \dashv i \dashv p^-, \\ \varepsilon: ip^- \rightarrow 1_{\mathbf{c}} \text{ (the past counit),} & & \eta: 1_{\mathbf{c}} \rightarrow ip^+ \text{ (the future unit).} \end{aligned} \tag{84}$$



$$p^-[b] = 1, \quad p^-[c] = 0, \quad p^-[d] = 1, \quad p^+[b] = 1, \quad p^+[c] = 1, \quad p^+[d] = 0. \tag{86}$$

Roughly speaking, both the functors $p^-, p^+: \mathbf{c} \rightarrow E$ count the number of times that a *directed* path a in \mathbf{S}^1 crosses the point x , a number which only depends on the homotopy class $[a]$ in \mathbf{c} , because of our restriction on paths. But the precise definition is different: $p^-[a]$ is the number of times that a reaches x from below, while $p^+[a]$ is the number of times that a leaves x upwards (the examples above show the difference). Then, the counit component $\varepsilon x': x \rightarrow x'$ is the class of the ‘least anticlockwise path’ from x to x' (so that $p^-(\varepsilon x') = 0$ is indeed the identity of the monoid); and dually for $\eta x': x' \rightarrow x$ (now, $p^+(\eta x') = 0$). The coherence properties (49) hold.

Now, if E' is an injective model of \mathbf{c} (hence a full subcategory), the full subcategory of E' (and \mathbf{c}) on some point x' is pf-embedded in E' as above, and isomorphic to E ; moreover, E —having just one object—is the unique injective model of itself.

Similarly, one can prove that the minimal injective model of the fundamental category of the inequilogical torus $(\uparrow\bar{\mathbf{S}}_e^1)^n = (\uparrow\mathbf{R}^n, \equiv_{\mathbf{Z}^n})$ (1.3) is the fundamental monoid at any point, isomorphic to \mathbf{N}^n . (The projective model of \mathbf{c} produced by the split pf-injection $E \rightarrow \mathbf{c}$ is the full subcategory of the category E^2 on the two objects $0, 1: x \rightarrow x$; which seems not to be of much interest.)

5.7. MINIMAL FAITHFUL MODELS. The terminology of this section can be adapted to the faithful case (4.1) in the obvious way, for the injective and the projective case. For instance, we say that E is a *minimal faithful injective model* of X if:

- (i) E is a faithful injective model of every faithful injective model E' of X ,
- (ii) every faithful injective model E' of E is isomorphic to E .

If X is *balanced*, every faithful pf-embedding $i: E \rightarrow X$ is essentially surjective on objects (each component $\eta x: x \rightarrow ir^+(x)$ being an isomorphism), whence an equivalence of categories. Therefore, the minimal faithful injective model of X is simply its skeleton.

A category can have a minimal injective model and a *different* minimal faithful injective model. For instance, the well-known category Δ^+ of finite ordinals (the site of augmented simplicial sets), being skeletal and balanced, is already a minimal *faithful* injective model (of itself), while its minimal injective model is $\mathbf{2}$ (5.4); the same happens with the category of finite cardinals (and all mappings), or the category described in 2.8d, which is not balanced.

6. Future invariant properties

In this section we investigate various properties, of morphisms and objects, which are invariant under future (or past) equivalence. They are linked with 'branching' or 'non-branching' properties, as in the definition of filtered categories (cf. 6.5), and will be used in the next sections to identify and construct minimal models of categories.

6.1. FUTURE REGULARITY. A morphism $a: x \rightarrow x'$ in X will be said to be V^+ -regular if it satisfies condition (i), O^+ -regular if it satisfies (ii), and *future regular* if it satisfies both:

- (i) given $a': x \rightarrow x''$, there is a commutative square $ha = ka'$ (V^+ -regularity),
- (ii) given two maps $a_i: x' \rightarrow x''$ such that $a_1a = a_2a$, there is some h such that $ha_1 = ha_2$ (O^+ -regularity),

$$\begin{array}{ccc}
 x & \xrightarrow{a} & x' \\
 a' \downarrow & & \downarrow h \\
 x'' & \xrightarrow{k} & \bullet
 \end{array}
 \qquad
 x \xrightarrow{a} x' \xrightarrow[a_2]{a_1} x'' \xrightarrow{h} \bullet
 \tag{87}$$

Future regular morphisms are closed under composition (6.2), but they are not invertible, in general. The equivalence relation \sim^+ in $\text{Ob}X$ generated by the existence of a future regular morphism between two objects will be called *future regularity equivalence*. The future regularity class of an object x will be written $[x]^+$.

In a category with finite colimits or with terminal object, all morphisms are future regular. In a preordered set, all arrows are O^+ -regular, and future regularity coincides with V^+ -regularity.

On the other hand, we shall say that the morphism a is V^+ -branching if it is not V^+ -regular; that it is O^+ -branching if it is not O^+ -regular; that it is a *future branching morphism* if it falls in (at least) one of the previous cases, i.e. if it is not future regular. In the category represented below, at the left, the morphism a is V^+ -branching and O^+ -regular, while at the right a is O^+ -branching and V^+ -regular

$$\begin{array}{ccc}
 x & \xrightarrow{a} & x' \\
 a' \downarrow & & \\
 x'' & &
 \end{array}
 \qquad
 \begin{array}{ccc}
 x & \xrightarrow{a} & x' \\
 b \searrow & & \downarrow a_1 \\
 & & x'' \\
 & & \downarrow a_2
 \end{array}
 \qquad
 (b = a_1a = a_2a).
 \tag{88}$$

Dually, we have V^- -regular, O^- -regular, past regular morphisms and the corresponding branching morphisms; the past regularity equivalence \sim^- and its past regularity classes $[x]^-$.

6.2. LEMMA.

(a) V^+ -regular, O^+ -regular and future regular morphisms form (wide) subcategories, containing all the isomorphisms.

(b) If a composite ba is V^+ -regular (resp. O^+ -regular), then the first map a (resp. the second map b) is also.

PROOF. Take two consecutive morphisms in X , $a: x \rightarrow x'$ and $b: x' \rightarrow x''$.

First, let us consider the property of V^+ -regularity. It is plainly consistent with composition. On the other hand, if ba is V^+ -regular also a is: for every $a': x \rightarrow \bar{x}$ there is a commutative square $h(ba) = ka'$, which can be rewritten as $(hb).a = ka'$.

Second, let us consider O^+ -regularity. If a and b are so, take two maps $b_i: x'' \rightarrow \bar{x}$ such that $b_1(ba) = b_2(ba)$; by O^+ -regularity of a there is some h such that $hb_1b = hb_2b$; then, by O^+ -regularity of b , there is some k such that $khb_1 = khb_2$. On the other hand, if ba is O^+ -regular, also b is: if $b_1b = b_2b$, then $b_1(ba) = b_2(ba)$ and there is some h such that $hb_1 = hb_2$. ■

6.3. THEOREM. [Future equivalence and regular morphisms] Given a future equivalence $f: X \rightleftarrows Y: g$, with natural transformations $\varphi: 1 \rightarrow gf$, $\psi: 1 \rightarrow fg$, we have:

(a) all the components φx and ψy are future regular morphisms,

(b) the functors f and g preserve V^+ -regular, O^+ -regular and future regular morphisms,

(c) the functors f and g preserve V^+ -branching, O^+ -branching and future branching morphisms (i.e. reflect V^+ -regular, O^+ -regular and future regular morphisms),

PROOF. (a) Take a component $\varphi x: x \rightarrow gfx$. Then, a map $a: x \rightarrow x'$ gives the left commutative diagram, showing that φx is V^+ -regular

$$\begin{array}{ccc}
 x & \xrightarrow{\varphi x} & gfx \\
 a \downarrow & & \downarrow gfa \\
 x' & \xrightarrow{\varphi x'} & gfx'
 \end{array}
 \qquad
 \begin{array}{ccccc}
 x & \xrightarrow{\varphi x} & gfx & \xrightarrow{\varphi gfx} & gfgfx \\
 & \searrow a & \downarrow a_i & \dashrightarrow gfa & \downarrow gfa_i \\
 & & x' & \xrightarrow{\varphi x'} & gfx'
 \end{array}
 \tag{89}$$

Moreover, given two maps $a_i: gfx \rightarrow x'$ such that $a_i \cdot \varphi x = a$, the right diagram shows that $\varphi x'$ coequalises a_i (as in (11)): from $\varphi gf = gf\varphi$ we deduce $\varphi x' \cdot a_i = gfa_i \cdot \varphi gfx = gf(a_i \cdot \varphi x) = gf(a)$.

(b) Suppose that $a: x \rightarrow x'$ is V^+ -regular in X ; we must prove that $fa: fx \rightarrow fx'$ is V^+ -regular in Y . Given $b: fx \rightarrow y$, we can form the left commutative diagram in X , and

then the right one, in Y

$$\begin{array}{ccc}
 x & \xrightarrow{a} & x' \\
 \varphi x \downarrow & & \downarrow h' \\
 g f x & & \\
 g b \downarrow & & \downarrow h \\
 g y & \xrightarrow{h} & x''
 \end{array}
 \qquad
 \begin{array}{ccc}
 f x & \xrightarrow{f a} & f x' \\
 b \downarrow & \searrow \psi f x = f \psi x & \downarrow f h' \\
 & f g f x & \\
 & \downarrow f g b & \\
 y & \xrightarrow{\psi y} f g y \xrightarrow{f h} & f x''
 \end{array}
 \tag{90}$$

Second, suppose that $a: x \rightarrow x'$ is O^+ -regular in X . Given two maps $b_i: f x' \rightarrow y$ such that $b_i \cdot f a = b$, we have (at the left, below): $g b_i \cdot \varphi x' \cdot a = g b_i \cdot g f a \cdot \varphi x = g b \cdot \varphi x$. Therefore, there exists an h in X such that the composite $h \cdot g b_i \cdot \varphi x'$ does not depend on i (see the left diagram below)

$$\begin{array}{ccc}
 x & \xrightarrow{a} & x' \\
 g b \cdot \varphi x \searrow & & \downarrow g b_i \cdot \varphi x' \\
 & & g y \xrightarrow{h} x''
 \end{array}
 \qquad
 \begin{array}{ccc}
 f x & \xrightarrow{f a} & f x' \xrightarrow{\psi f x'} f g f x' \\
 b \searrow & & \downarrow f \varphi x' \\
 & & y \xrightarrow{\psi y} f g y \xrightarrow{f h} f x'' \\
 & & \downarrow f g b_i
 \end{array}
 \tag{91}$$

Then, in the right diagram above, the composite $f h \cdot \psi y \cdot b_i = f h \cdot f g b_i \cdot \psi f x' = f(h \cdot g b_i \cdot \varphi x')$, in Y , does not depend on i either.

(c) First, given $a: x \rightarrow x'$ in X , suppose that $f a$ is V^+ -regular (in Y); we must prove that a is also. Given $a': x \rightarrow x''$, we can form the right commutative diagram in Y , and then the left one, in X

$$\begin{array}{ccc}
 x & \xrightarrow{a} & x' \\
 \varphi x \searrow & & \downarrow \varphi x' \\
 g f x & \xrightarrow{g f a} & g f x' \\
 a' \downarrow & & \downarrow g k' \\
 x'' & \xrightarrow{\varphi x''} g f x'' \xrightarrow{g k} & g y
 \end{array}
 \qquad
 \begin{array}{ccc}
 f x & \xrightarrow{f a} & f x' \\
 f a' \downarrow & & \downarrow k' \\
 f x'' & \xrightarrow{k} & y
 \end{array}
 \tag{92}$$

Second, let us suppose that $f a$ is O^+ -regular in Y ; given two maps $a_i: x' \rightarrow x''$ such that $a_i \cdot a = a'$, there is some k such that $k \cdot f a_i = k'$, in the right diagram; and then, in the left, $(g k \cdot \varphi x'') \cdot a_i = g(k \cdot f a_i) \cdot \varphi x' = g k' \cdot \varphi x'$ is independent of i

$$\begin{array}{ccc}
 x & \xrightarrow{a} & x' \xrightarrow{\varphi x'} g f x' \\
 a' \searrow & & \downarrow g f a_i \\
 & & g f x'' \xrightarrow{g k} g y \\
 & & \downarrow \varphi x''
 \end{array}
 \qquad
 \begin{array}{ccc}
 f x & \xrightarrow{f a} & f x' \\
 f a' \searrow & & \downarrow f a_i \\
 & & f x'' \xrightarrow{k} y \\
 & & \downarrow k'
 \end{array}
 \tag{93}$$

■

6.4. COROLLARY. *A future equivalence $f: X \rightleftarrows Y :g$ induces a bijection between the quotients $(\text{Ob}X)/\sim^+$ and $(\text{Ob}Y)/\sim^+$ (of objects up to future regularity equivalence). Therefore, the functors f and g preserve and reflect the future regularity equivalence relations \sim^+ .*

PROOF. By 6.3b, we have induced mappings $(\text{Ob}X)/\sim^+ \rightleftarrows (\text{Ob}Y)/\sim^+$, which are inverses by 6.3a. ■

6.5. BRANCHING POINTS. We consider now future invariant properties of *points* of a category X . We have already seen a few, concerning extremal points (2.7). A point x will be said to be V^+ -regular if it satisfies (i), O^+ -regular if it satisfies (ii), *future regular* if it satisfies both:

(i) every arrow starting from x is V^+ -regular (equivalently, two arrows starting from x can always be completed to a commutative square),

(ii) every arrow starting from x is O^+ -regular (i.e., given an arrow $a: x \rightarrow x'$ and two arrows $a_i: x' \rightarrow x''$ such that $a_1a = a_2a$, there exists an arrow h such that $ha_1 = ha_2$).

It is easy to verify that x is future regular in X if and only if the comma category $(x|X)$ of arrows starting from x is *filtered* [18], IX.1; but this will not be used here.

We shall say that x is a V^+ -branching point in X if it is not V^+ -regular (i.e., if there is some arrow starting from x which is V^+ -branching); that x is an O^+ -branching point if it is not O^+ -regular; that x is a *future branching point* if it falls in at least one of the previous cases, i.e. if it is not future regular.

Note now that, in the fundamental category C considered in the Introduction, the starting point 0 is V^+ -branching, but the choice between the different paths starting from it can be deferred, while at the point a (also V^+ -branching) the choice must be made. To distinguish these situations, we will say that a future branching point is *effective* when every future regular map starting from it is a split mono. (In the fundamental category of a preordered or ordered space, this amounts to an isomorphism or an identity, respectively).

Dually, we have the notions of V^- -, O^- - and *past regular* (resp. *branching*) point in X , and *effective past branching points*.

6.6. THEOREM. [Future equivalence and branching points] *The following properties of a point are future invariant (i.e., invariant up to future equivalence):*

(a) *being a V^+ -regular, or an O^+ -regular, or a future regular point,*

(b) *being a V^+ -branching, or an O^+ -branching, or a future branching point, or an effective one.*

PROOF. Let $f: X \rightleftarrows Y :g$ be a future equivalence, with $\varphi: \text{id}X \rightarrow gf$ and $\psi: \text{id}Y \rightarrow fg$.

(a) Let us take a point x which is V^+ -regular in X , and prove that every Y -arrow $b: fx \rightarrow y$ is V^+ -regular. Indeed, the map $a = gb \cdot \varphi x: x \rightarrow gy$ is V^+ -regular, whence also fa is (by Thm. 6.3); but $fa = fgb \cdot f\varphi x = fgb \cdot \psi fx = \psi y \cdot b$, whence also the ‘first map’ b is V^+ -regular (6.2b).

We assume now that x is O^+ -regular, and prove that every Y -map $b: fx \rightarrow y$ is also. Now, the composite $gb.\varphi x$ is O^+ -regular in X , whence the ‘second map’ gb is O^+ -regular (6.2b), and b itself is O^+ -regular in Y (by the reflection property, in Thm. 6.3).

(b) We take a point x in X such that fx is V^+ -regular (i.e., *not* V^+ -branching) and prove that also x is. For every $a: x \rightarrow x'$ in X , $fa: fx \rightarrow fx'$ is V^+ -regular in Y ; but then a is V^+ -regular in X , by the reflection property 6.3c. The same holds replacing the prefix V^+ with O^+ .

Finally, let x be an effective future branching point and $b: fx \rightarrow y$ a future regular map. Then $a = gb.\varphi x: x \rightarrow gy$ is future regular, whence a is a split mono and also fa is; but $fa = fgb.f\varphi x = fgb.\psi fx = \psi y.b$, whence also b is a split mono. ■

7. Directed spectra of a category

We define now the *future* and the *past spectrum* of a category, and show that they are its least full reflective and its least full coreflective subcategories. Their join forms the *pf-spectrum*, a strongly minimal injective model whose embedding in the original category is essentially unique. The pf-spectrum also produces a projective model.

7.1. LEAST FUTURE RETRACTS. By a *replete* subcategory of a category X we will mean a *full* subcategory which is closed (in X) under isomorphic copies of objects. If C is a full subcategory, its *replete closure* C' in X has the same skeleton.

Within full subcategories of X , we define the preorder of *essential inclusion* $C \prec D$ by the inclusion $C' \subset D'$ of their replete closures (which reduces to $C \subset D$, when X is skeletal—as it will often be the case in our applications). We are interested in a *least full reflective subcategory*, or *least future retract* F of X , for this preorder. If it exists, its replete closure is strictly determined as the *least replete reflective subcategory* of X (with respect to inclusion); and a category Y is future equivalent to X if and only if F is also a future retract of Y (by Thm. 2.5). Similarly for full coreflective subcategories.

One could define the *future skeleton* of X as the skeleton of the least future retract of X . Rather than developing this notion, we shall study a stronger one, called ‘future spectrum’, which will produce the same results and will be easier to determine, in the examples of Section 9.

The categories \mathbf{r} and \mathbf{c} have minimal future retracts, but do not have a least one (5.5, 5.6).

The ordered set of (replete) reflective subcategories of a category was investigated in [15] (see also its references). Such results are generally based on the existence of limits in the original category and cannot be applied here.

7.2. SPECTRA. Recall that we have defined, in the set of objects ObX , the equivalence relation $x \sim^+ x'$ of future regularity, with equivalence classes $[x]^+$ (6.1).

A *future spectrum* $sp^+(X)$ of the category X will be a subset of objects such that:

(*sp*⁺.1) $sp^+(X)$ contains precisely one object, written $sp^+(x)$, in every future regularity class $[x]^+$,

($sp^+.2$) for every $x \in X$ there is precisely one morphism $\eta x: x \rightarrow sp^+(x)$ in X ,

($sp^+.3$) every morphism $a: x \rightarrow sp^+(x')$ factors as $a = h.\eta x$, for a unique $h: sp^+(x) \rightarrow sp^+(x')$.

The second condition can be equivalently written as:

($sp^+.2'$) for every $x \in X$, $sp^+(x)$ is the terminal object of the full subcategory on $[x]^+$.

Also the full subcategory $Sp^+(X)$ of X on this set of objects will be called the *future spectrum*. We shall prove that the future spectrum (when it exists) is the least future retract (7.3) and that it, as well as its embedding in the category, are determined up to a *canonical* isomorphism (7.5). Therefore, the future spectrum is more strictly determined than the ordinary skeleton.

Dually we have the *past spectrum* $sp^-(X)$ and its full subcategory $Sp^-(X)$.

The categories \mathbf{r} and \mathbf{c} , defined in 5.5, 5.6, have neither future nor past spectra. Indeed, all their maps are future regular, and all objects form a unique future regularity class, which has no terminal object; and dually their objects form a unique past regularity class, which has no initial object. It is also easy to see that a category has future spectrum $\mathbf{1}$ if and only if it is future equivalent to $\mathbf{1}$, if and only if it has a terminal object (2.6).

7.3. THEOREM. [Properties of future spectra] *Let $F = Sp^+(X)$ be a future spectrum of the category X and $i: F \rightarrow X$ its inclusion.*

(a) *F is a future retract of X , with an essentially unique retraction p and unit η :*

$$i: F \rightleftarrows X : p, \quad \eta: 1_X \rightarrow ip: X \rightarrow X, \quad (94)$$

(b) *F is the least future retract of X , with respect to essential inclusion (of full subcategories, 7.1). It is a skeletal category, whose only endomorphisms are the identities. The inclusion $i: F \rightarrow X$ preserves and reflects future regularity.*

(c) *Replacing some objects of $sp^+(X)$ with isomorphic copies, the new subset is still a future spectrum of X .*

(d) *Every point of $sp^+(X)$ is either maximal in X (1.5) or an effective future branching point (6.5).*

PROOF. (a) The inclusion $i: Sp^+(X) \rightarrow X$ has a left adjoint $p: X \rightarrow Sp^+(X)$, since ($sp^+.3$) says that $\eta x: x \rightarrow sp^+(x) = ip(x)$ is a universal arrow from the object x to the functor i . Moreover, for $x_0 \in Sp^+(X)$, the counit $\varepsilon x_0: x_0 = pi(x_0) \rightarrow x_0$ is necessarily the identity, by ($sp^+.2$). It follows that $\eta i = 1$ and $p\eta = 1$.

(b) Let $(j, q; \zeta): G \rightarrow X$ be a future retract of X ; we want to prove that $Sp^+(X)$ is contained in the replete closure of G . Take an object $x_0 \in Sp^+(X)$; the unit $\zeta x_0: x_0 \rightarrow jqx_0 = x$ is future regular, whence $sp^+(x) = x_0$ and the left composite below is the identity, by ($sp^+.2$):

$$\eta x.\zeta x_0: x_0 \rightarrow x \rightarrow x_0, \quad e = \zeta x_0.\eta x: x \rightarrow x_0 \rightarrow x. \quad (95)$$

Now, for the right composite e , we have $e.\zeta x_0 = \zeta x_0 = 1_x.\zeta x_0$; since the unit-component $\zeta x_0: x_0 \rightarrow jqx_0$ is a universal arrow from x_0 to the full embedding $j: G \rightarrow X$, it follows that e too is the identity.

Moreover, $Sp^+(X)$ is skeletal by $(sp^+.1)$ and has no endomorphisms, except the identities, by $(sp^+.2)$. The last assertion follows from 6.3.

Finally, (c) is obvious. As to (d), if $x_0 \in sp^+(X)$ is not maximal for the path preorder in X , there is some arrow $a: x_0 \rightarrow x$ with no arrows backwards; since x_0 is terminal in its future regularity class, a is not future regular and x_0 is a future branching point. Moreover, if $a: x_0 \rightarrow x$ is future regular, then $x \sim^+ x_0$ and $\eta x.a = \text{id}_{x_0}$, whence a is a split mono. ■

7.4. LEMMA. [Characterisation of future spectra] *The following conditions on a functor $i: F \rightarrow X$ are equivalent:*

(a) *the functor i is an embedding and $i(F)$ is a future spectrum of X ;*

(b) *the category F has precisely one object in each future regularity class; the functor i is a future retract, i.e. it has a left adjoint $p: X \rightarrow F$ with $pi = 1_F$ as counit; moreover the unit-component $x \rightarrow ip(x)$ is the unique X -morphism with these endpoints;*

(c) *the category F has precisely one object in each future regularity class and only one endomorphism for every object; the functor i can be extended to a future equivalence $i: F \rightleftarrows X: p$, whose unit-component $x \rightarrow ip(x)$ is the unique X -morphism with these endpoints.*

Note. The form (c) is appropriate to link future spectra with future equivalences, cf. 8.1.

PROOF. Identifying F with $Sp^+(x)$ and i with the inclusion, the fact that (a) implies (b) and (c) has already been proved in 7.3a. Then (c) implies (b): for every $x_0 \in F$, $x_0 \sim^+ pi(x_0)$ (by 6.3a) whence $x_0 = pi(x_0)$ and the unit-component $x_0 \rightarrow pi(x_0)$ (of the future equivalence) is necessarily an identity. Finally, (b) implies (a): letting $sp^+(x) = ip(x)$, the universal property of the unit of an adjunction gives $(sp^+.3)$. ■

7.5. LEMMA. [Uniqueness of future spectra, I] *Let $i: F \rightarrow X$ and $j: G \rightarrow X$ be embeddings of future spectra of the category X .*

(a) *For every $x_0 \in F$ there is a unique $u(x_0)$ in G such that $i(x_0) \cong ju(x_0)$ in X ; and then, there is a unique morphism $\lambda_{x_0}: i(x_0) \rightarrow ju(x_0)$ in X ; the latter is invertible.*

(b) *The mapping $u: \text{Ob}F \rightarrow \text{Ob}G$ so defined has a unique extension to a functor $u: F \rightarrow G$ making the family (λ_{x_0}) into an (invertible) natural transformation $\lambda: i \rightarrow ju: F \rightarrow X$.*

PROOF. Obvious. (A more complete uniqueness result will be given in 8.6.) ■

7.6. SPECTRAL PRESENTATIONS. The *spectral pf-presentation* of X (cf. 4.2) will be a diagram where

$$\begin{array}{ccc}
 P & \begin{array}{c} \xrightarrow{i^-} \\ \xleftarrow{p^-} \end{array} & X & \begin{array}{c} \xrightarrow{p^+} \\ \xleftarrow{i^+} \end{array} & F \\
 \varepsilon: i^- p^- \rightarrow 1_X & (p^- i^- = 1, p^- \varepsilon = 1, \varepsilon i^- = 1), & & & \\
 \eta: 1_X \rightarrow i^+ p^+ & (p^+ i^+ = 1, p^+ \eta = 1, \eta i^+ = 1). & & &
 \end{array} \tag{96}$$

- (i) P is *the* past spectrum and F *the* future spectrum of X ,
(ii) given $x \in \text{Ob}P$ and $x' \in \text{Ob}F$, if $x \cong x'$ in X then $x = x'$ (*linked choice*).

Such a presentation exists if and only if X has a past spectrum and a future one, since the linked-choice condition can always be realised, replacing each object of P with its isomorphic copy in F , if any (7.3c). The set of objects produced by this linked choice will be called the *pf-spectrum* of X , or *spectral model*

$$sp(X) = \text{Ob}P \cup \text{Ob}F = sp^-(X) \cup sp^+(X). \tag{97}$$

The full subcategory $Sp(X)$ on these objects will also be called the *pf-spectrum* of X . We prove below that it is well determined, in the same form of future spectra (7.5); and we shall prove that it is a strongly minimal injective model (8.4); it is not split, in general.

The projective model $X \rightarrow M$ associated to the spectral pf-presentation (as in 4.6) will be called the *spectral projective model* of X . We have already seen in the Introduction that it need not be a minimal projective model.

7.7. THEOREM. [Uniqueness of pf-spectra] *Two pf-spectra, $i: E \subset X$ and $j: E' \subset X$, are given.*

(a) *For every $x_0 \in E$ there is a unique $u(x_0)$ in E' such that $i(x_0) \cong ju(x_0)$ in X ; and then there is a unique morphism $\lambda_{x_0}: i(x_0) \rightarrow ju(x_0)$ in X , which is invertible.*

(b) *The mapping $u: \text{Ob}E \rightarrow \text{Ob}E'$ so defined has a unique extension to a functor $u: E \rightarrow E'$ making the family (λ_{x_0}) into a natural transformation $\lambda: i \rightarrow ju: E \rightarrow X$, which is invertible (see the left diagram below)*

$$\begin{array}{ccc}
 E & \xrightarrow{i} & X \\
 u \downarrow & \swarrow \lambda & \parallel \\
 E' & \xrightarrow{j} & X
 \end{array}
 \qquad
 \begin{array}{ccccc}
 P & \xrightarrow{i^-} & E & \xleftarrow{i^+} & F \\
 u^- \downarrow & & u \downarrow & & \downarrow u^+ \\
 P' & \xrightarrow{j^-} & E' & \xleftarrow{j^+} & F'
 \end{array} \tag{98}$$

(c) *Let P, F be, respectively, the past and the future spectrum of X giving rise to E ; and similarly P', F' for E' . Their embeddings and the functor u produce the commutative right diagram above, where u^- and u^+ are the isomorphisms resulting from the uniqueness of these directed spectra of X (7.5).*

PROOF. (a) We already know (by 7.5a) that, if the point x_0 belongs to P (resp. F), there is a unique $u^-(x_0)$ in P' (resp. $u^+(x_0)$ in F') such that $x_0 \cong u^\alpha(x_0)$ in X ($\alpha = \pm$); moreover, if x_0 is in $P \cap F$, then $u^-(x_0) \cong x_0 \cong u^+(x_0)$, whence $u^-(x_0) = u^+(x_0)$, because of the linked-choice condition in E' . We have thus a unique object $u(x_0)$ consistent with the right diagram above.

We also have (again by 7.5a) a unique map $\lambda_{x_0}: i(x_0) \rightarrow ju(x_0)$ in X , which is an isomorphism. The points (b) and (c) follow now easily. ■

8. Spectra and pf-equivalence of categories

Pf-spectra are shown to be strongly minimal injective models (8.4) and to classify injective equivalence, in a strict sense (8.3).

8.1. THEOREM. [Preservation of future spectra] *If $f: X \rightleftarrows Y : g$ is a future equivalence and $i: F \rightarrow X$ is the embedding of a future spectrum, then $fi: F \rightarrow Y$ is also.*

PROOF. The units of the future equivalence will be written as $\varphi: 1 \rightarrow gf$ and $\psi: 1 \rightarrow fg$.

Let us use the characterisation 7.4c of embeddings of future spectra, taking into account the fact that future equivalences compose (2.3). Let $p: X \rightarrow F$ be the retraction and $\eta: 1 \rightarrow ip$ the unit of F (7.3a). We know that F has one object in each future regularity class and only one endomorphism for every object. It remains to show that, for every $y \in Y$, the composed unit $\eta'y = f\eta gy.\psi y: y \rightarrow fipgy$ is the *unique* morphism between these points.

Let $x = ipgy \in i(F)$ and note that the composite $\eta gfx.\varphi x: x \rightarrow gfx = ipgfx$ is the identity, because x and $ipgfx$ are equivalent up to future regularity, in $i(F)$. Take now any map $b: y \rightarrow fx$ in Y ; by naturality of ψ we have a commutative (solid) diagram

$$\begin{array}{ccccc}
 y & \xrightarrow{\psi y} & fgy & & \\
 b \downarrow & & fgb \downarrow & \dashrightarrow^{f\eta gy} & \\
 fx & \xrightarrow{\psi fx} & fgfx & \xrightarrow{f\eta gfx} & fx
 \end{array} \tag{99}$$

where the lower row is the identity, because of the previous remark and because $\psi fx = f\varphi x$. Also the right triangle commutes, since $\eta gfx.gb: gy \rightarrow x$ must coincide with $\eta gy: gy \rightarrow ipgy = x$. Finally, we have the thesis: $b = f\eta gy.\psi y$. ■

8.2. THEOREM. [Preservation of pf-spectra] *A pf-embedding preserves and reflects pf-spectra. More precisely, assuming that the category X has a pf-spectrum $i: E \subset X$, we have the following results (writing $E_0 = \text{Ob}E$).*

(a) *Given a pf-embedding $u: X \rightarrow Y$, $u(E_0)$ is the pf-spectrum of Y .*

(b) *Given a pf-embedding $v: Y \rightarrow X$, $v^{-1}(E_0)$ is the pf-spectrum of Y ,*

PROOF. (a) Follows from 8.1.

(b) Y is past and future equivalent to X , whence it also has a past and a future spectrum, and therefore a pf-spectrum H_0 , preserved by the pf-embedding $Y \rightarrow X$. Since the pf-spectrum of X is determined up to isomorphism, $v(H_0)$ coincides with E_0 , up to isomorphic copies of objects. Since v is a full embedding, it follows that $v^{-1}(E_0)$ coincides with H_0 (up to isomorphic copies of objects), and is a pf-spectrum of Y as well. ■

8.3. COROLLARY. *If the category X has a pf-spectrum E , then it is injectively equivalent to a category Y if and only if E is also a pf-spectrum of Y .*

PROOF. It is a straightforward consequence of the previous theorem. ■

8.4. THEOREM. [Spectra and injective models] *Given a pf-presentation of the category X , let E be the associated injective model (Thm. 4.3). Then, with the same notation of 4.3,*

(a) *the pf-presentation of X is spectral if and only if the same holds for E ;*

(b) *in this case, $E = Sp(X)$ is a strongly minimal injective model of X .*

PROOF. (a) Follows immediately from 8.2.

(b) Assume that the given pf-presentation is spectral, and let us show that E is a strongly minimal injective model of X . Given a category Y injectively equivalent to X , we know (8.3) that E is an injective model of Y . Secondly, given an injective model $v: E' \rightarrow E$, we have to prove that v is surjective on objects, hence an isomorphism. Indeed, we have the composite pf-embedding $E' \rightarrow X$, whence v must reach a isomorphic copy of every object of P and F ; one concludes with the linked-choice condition. ■

8.5. COMMENTS. Given a pf-presentation of the category X , and reconsidering the previous construction (in 8.4), one can note that:

$$\begin{array}{ccccc}
 P & \xrightleftharpoons[i^-]{i^-} & X & \xrightleftharpoons[p^+]{p^+} & F \\
 \parallel & & \begin{array}{c} \uparrow r^- \\ \downarrow r^+ \end{array} & & \parallel \\
 P & \xrightleftharpoons[j^-]{j^-} & E & \xrightleftharpoons[q^+]{q^+} & F \\
 & & \begin{array}{c} \leftarrow q^- \\ \rightarrow j^+ \end{array} & &
 \end{array} \tag{100}$$

(a) composing the future equivalences $F \rightleftharpoons X \rightleftharpoons E$, one gets $j^+: F \rightleftharpoons E : q^+$,

(b) composing the future equivalences $F \rightleftharpoons E \rightleftharpoons X$, one gets $i^+: F \rightleftharpoons X : p^+$, and symmetrically on the left-hand side.

On the other hand, the future equivalence $u: E \rightleftharpoons X : r^+$ is not the composition of the future equivalences $E \rightleftharpoons F \rightleftharpoons X$ (in general): the image of $i^+q^+: E \rightarrow X$ is ‘just’ F , instead of E .

We end this section with a second statement on the uniqueness of future spectra. It is more complete than the first (Lemma 7.5), being based on the whole structure of a future spectrum as a future retract; yet, it seems to be less useful than the first.

8.6. THEOREM. [Uniqueness of future spectra, II] *Two future spectra of the category X are given, as future retracts:*

$$i: F \rightrightarrows X : p, \quad j: G \rightrightarrows X : q \quad (\eta: 1_X \rightarrow ip, \quad \eta': 1_X \rightarrow jq). \quad (101)$$

(a) *We have: $qip = q$ and $q\eta = 1_q$; dually, $pjq = p$ and $p\eta' = 1_p$.*

(b) *There is a unique functor $u: F \rightarrow G$ such that $up = q$, namely $u = qi$, and it is an isomorphism.*

(c) *There is a unique natural transformation $\lambda: i \rightarrow ju: F \rightarrow X$, namely $\lambda = \eta'i$, and it is invertible.*

$$\begin{array}{ccccc} X & \xrightarrow{p} & F & \xrightarrow{i} & X \\ \parallel & & \downarrow u & \swarrow \lambda & \parallel \\ X & \xrightarrow{q} & G & \xrightarrow{j} & X \end{array} \quad (102)$$

PROOF. (a) To prove that $qip = q$, let us begin noting that this is true on every object $x \in X$, because $ip(x) \sim^+ x$ (by 6.3a) and $qip(x) = q(x)$. Now, the natural transformation $q\eta: q \rightarrow qip$ has general component $q\eta(x): qx \rightarrow qipx = qx$; but there is a *unique* map from qx to itself, in the future spectrum G , namely the identity of qx . It follows that $qip = q$ is also true on maps, and $q\eta = 1_q$.

(b) Uniqueness is plain: $up = q$ implies $u = qi$. Existence follows from (a): taking $u = qi: F \rightarrow G$, we have $up = qip = q$. Symmetrically, there is a unique functor $v: G \rightarrow F$ such that $vq = p$; and then u and v are inverses.

(c) We do have a natural transformation $\lambda = \eta'i: i \rightarrow jqi = ju$. Its component $\lambda(x_0): i(x_0) \rightarrow jqi(x_0)$ is the unique X -morphism between such objects (because they are future regular equivalent and the second is in G). But there is also a unique X -morphism backwards $jqi(x_0) \rightarrow i(x_0)$, because $i(x_0)$ is in F ; and their composites must be identities. ■

9. A gallery of spectra and models

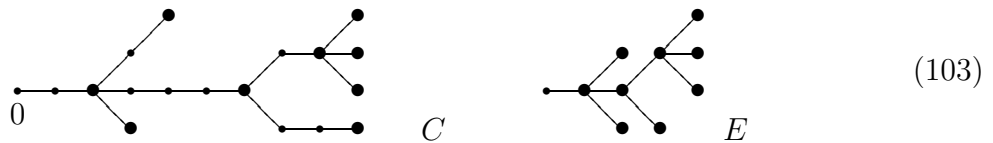
After considering pf-spectra of preorders (9.1), we will construct the pf-spectrum of the fundamental category of various ordered topological spaces; a preordered space is dealt with in 9.5. All these pf-spectra yield *faithful* injective models, except in 9.8. We end with a few hints to applications (9.9). Speaking of branching points, the term ‘effective’ (defined in 6.5) will generally be understood, unless we want to stress this fact.

9.1. FUTURE SPECTRA OF PREORDERS. Let C be a preorder category. All morphisms are O^+ -regular (6.1), so that future regularity coincides with V^+ -regularity and is always faithful. Explicitly, the ‘arrow’ $x \prec x'$ is future regular in C if, whenever $x \prec x''$ there exists some upper bound \bar{x} ($x' \prec \bar{x}$ and $x'' \prec \bar{x}$).

In this case, the existence (and choice) of a future spectrum $sp^+(C)$ (which is necessarily faithful) amounts to these conditions:

- (i) each future regularity class of objects $[x]^+$ has a maximum (determined up to \simeq), and we choose one, called $\max[x]^+$ (if C is ordered, the choice is determined),
- (ii) if $x \prec x'$ in C , then $\max[x]^+ \prec \max[x']^+$.

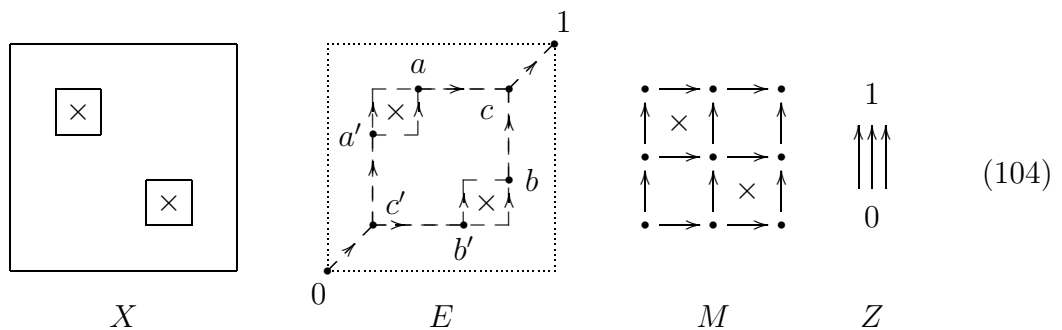
Every finite tree C has a spectrum. Indeed, C is past contractible, its root as past spectrum: $P = \{0\}$; its future spectrum F can be obtained omitting any point which has precisely one immediate successor. In the example below (ordered rightward), the points of the future spectrum are marked with a bigger bullet; the spectral injective model $E = P \cup F$ is shown at the right



The associated projective model, the full subcategory $E' \subset E^2$ on the objects $0 < y$ ($y \in F$), is isomorphic to F (and not isomorphic to E , unless $P \subset F$).

9.2. MODELLING AN ORDERED SPACE. Directed homotopy for preordered topological spaces has been recalled in Section 1. In the sequel, we will *generally* consider ordered topological spaces X with minimum (0) and maximum (1) and study the pf-spectrum of the fundamental category $C = \uparrow\Pi_1(X)$. The latter inherits a privileged ‘starting point’ 0 (a minimal point, but possibly not the unique one, cf. 9.6) and a privileged ‘ending point’ 1 (which is maximal in C). Furthermore, recall that C is skeletal (when X is ordered), so that the future spectrum—if it exists—is the least full (i.e. replete) reflective subcategory of C , strictly determined as a subset of C . Objects of C (i.e., points of X) will be denoted by letters x, a, b, c, \dots ; arrows of C (i.e. ‘homotopy classes’ of paths of X) by Greek letters $\alpha, \beta, \gamma \dots$

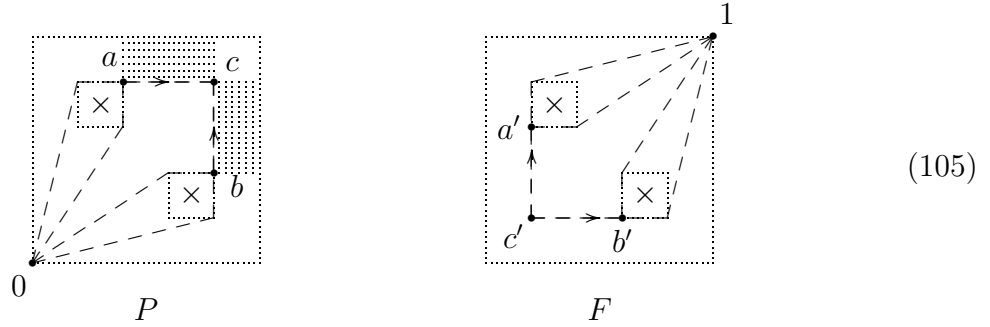
Consider, in the category \mathbf{pTop} , the (compact) ordered space X : a subspace of the standard ordered square $\uparrow[0, 1]^2$ obtained by taking out two *open* squares (marked with a cross), as in the left figure below



The fundamental category $C = \uparrow\Pi_1(X)$ is easy to determine (see 1.1). We shall prove that its pf-spectrum is the full subcategory E , on eight vertices (where the two cells

marked with a cross do not commute, while the central one does), while the associated projective model is M and the category Z is just a coarse model (of all three).

First, we show that the category $C = \uparrow\Pi_1(X)$ has a past spectrum



In fact, there are four past-regularity classes of objects, each having an initial object:

$$\begin{aligned}
 [c]^- &= \{x \mid x \geq c\} && \text{(unmarked),} \\
 [a]^- &= \{x \mid x \geq a\} \setminus [c]^-, && \text{(marked with dots),} \\
 [b]^- &= \{x \mid x \geq b\} \setminus [c]^-, && \text{(marked with dots),} \\
 [0]^- &= X \setminus ([c]^- \cup [a]^- \cup [b]^-) && \text{(unmarked),}
 \end{aligned}
 \tag{106}$$

where a, b, c are effective V^- -branching points and 0 is the global minimum, weakly initial in C .

These four points form the past spectrum $sp^-(C) = \{0, a, b, c\}$, as is easily verified with the characterisation 7.4b: take the full subcategory $P \subset C$ on these objects (represented in the same picture), its embedding $i^-: P \subset C$ and the projection p^- sending each point $x \in C$ to the minimum of its past regularity class. Now $i^- \dashv p^-$, with a counit-component $\varepsilon(x): i^-p^-(x) \rightarrow x$ which is uniquely determined in $\uparrow\Pi_1(X)$, since—within each of the four zones described above—there is at most one homotopy class of paths between two given points.

Symmetrically, we have the future spectrum: the full subcategory $F \subset C$ in the right figure above, on the following four objects (each of them a maximum in its future regularity class):

- 1 (the global maximum, *weakly* terminal); a', b', c' (V^+ -branching points).

The projection p^+ (left adjoint to $i^+: F \subset C$) sends each point $x \in C$ to the maximum of its future regularity class (i.e. the lowest distinguished vertex $p^+(x) \geq x$); the unit-component $\eta(x): x \rightarrow i^+p^+(x)$ is, again, uniquely determined in $\uparrow\Pi_1(X)$.

Globally, we have constructed a spectral pf-presentation of C (7.6); this generates the skeletal injective model E , as the full subcategory of C on $sp(C) = \{0, a, b, c, a', b', c', 1\}$. The full subcategory $Z \subset E$ on the objects $0, 1$ is isomorphic to the past spectrum of F , as well as to the future spectrum of P , hence coarse equivalent (2.3) to C and E .

Comments. The pf-spectrum E provides a category with the same past and future behaviour as C . This can be read as follows:

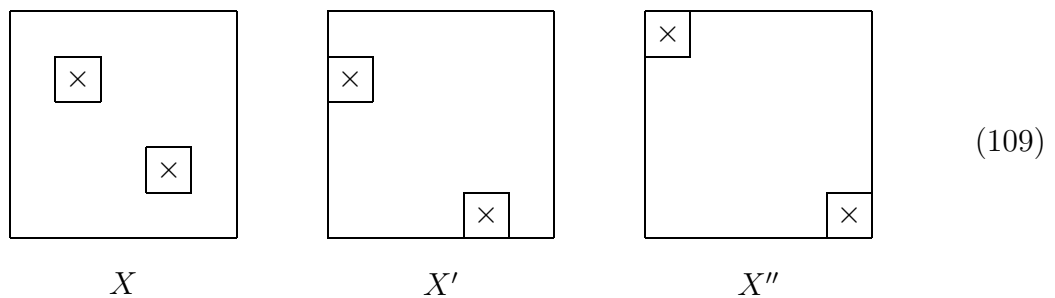
$$\begin{aligned}
 f^{-1}(\alpha) &= [0, 1/5]^2, & f^{-1}(\beta) &= [4/5, 1]^2 & & \text{(closed in X),} \\
 f^{-1}(\gamma) &=]1/5, 3/5[\times [0, 1/5], & f^{-1}(\gamma') &= [0, 1/5] \times]1/5, 3/5], \\
 f^{-1}(\delta) &= [4/5, 1] \times [2/5, 4/5[, & f^{-1}(\delta') &= [2/5, 4/5[\times [4/5, 1], \\
 f^{-1}(\sigma) &= X \cap]1/5, 4/5[^2 & & & & \text{(open in X),} \\
 f^{-1}(\sigma') &= X \cap (]3/5, 1[\times [0, 2/5]) & & & & \text{(open in X),} \\
 f^{-1}(\sigma'') &= X \cap ([0, 2/5[\times]3/5, 1]) & & & & \text{(open in X).}
 \end{aligned}
 \tag{108}$$

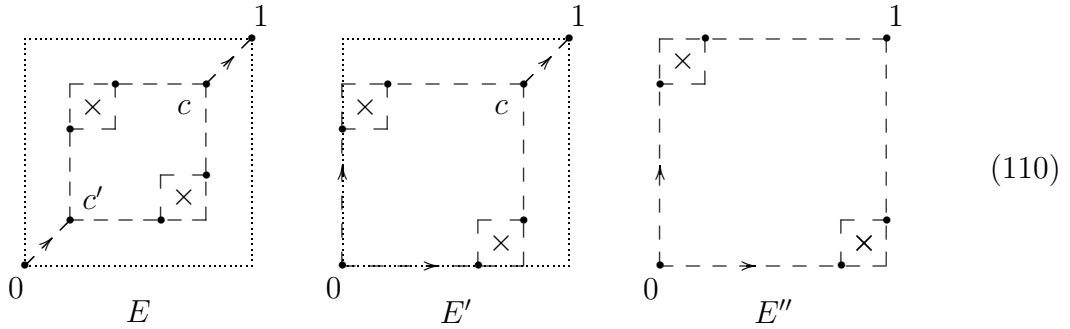
The interpretation of the projective model M is practically the same as above, in 9.2, with some differences:

- (i) in M there is no distinction between the starting point and the first future branching, as well as between the ending point and the last past branching;
- (ii) the different paths produced by the obstructions are ‘distinguished’ in M by three new intermediate objects: $\sigma, \sigma', \sigma''$.

Note also that—here and in many cases—one *can* also embed M in C , by choosing a suitable point of a suitable path in each homotopy class α, β, \dots ; but there is no canonical way of doing so. In order to compare the injective model E and the projective model M , the examples below will make clear that distinguishing 0 from c' (or c from 1) carries *some* information (like distinguishing the initial from the terminal object, in the injective model **2** of a non-pointed category having both, cf. 5.4). According to applications, one may decide whether this information is useful or redundant.

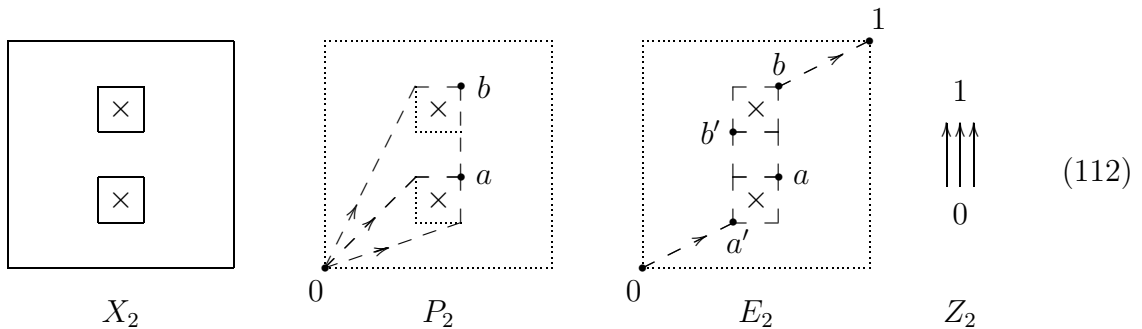
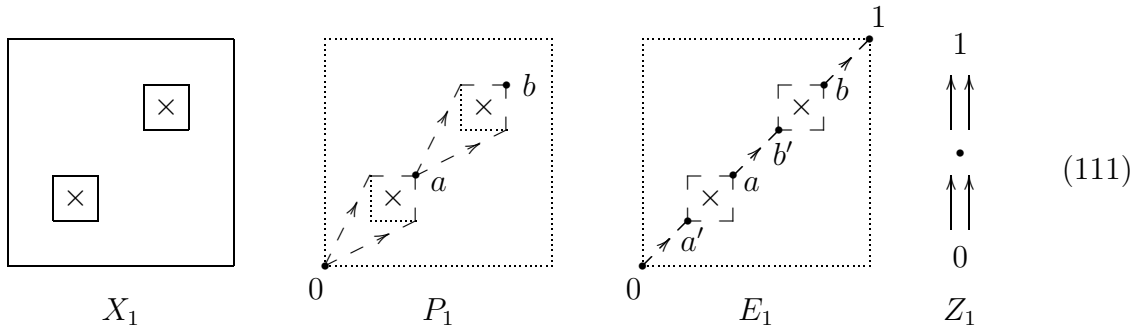
9.4. VARIATIONS. (a) Consider the previous ordered space X (9.2) together with the spaces X' and X'' , obtained by taking out, from the ordered square $\uparrow[0, 1]^2$, two open squares placed in different positions, ‘at’ the boundary





The pf-spectra E, E' and E'' distinguish these situations: in the second case the starting point 0 is an *effective* future branching point, and *we must make a choice from the very beginning* (either the upper/middle way or the middle/lower one); in the last case, this remains true and moreover the ending point is an *effective* past branching point. The projective models of these three spectra coincide (with the category M of 9.3).

(b) The following examples show similar situations, with a different injective (and projective) model. We start again from a (compact) ordered space $X_i \subset \uparrow[0, 1]^2$, obtained by taking out two open squares



In both cases, the past spectrum of the fundamental category $C_i = \uparrow\Pi_1(X_i)$ is the full subcategory P_i on three objects: 0 (the minimum), a, b (V^- -branching points), as shown above. The future spectrum is symmetric. The pf-spectrum, generated by the previous

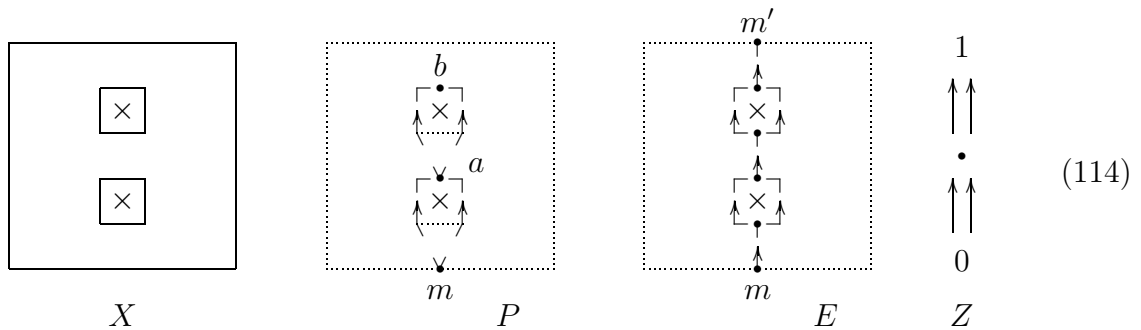
presentation, is the full subcategory E_i on the pf-spectrum $sp(C_i) = \{0, a, b, a', b', 1\}$. Coarse models of C_i are given by the categories Z_i generated by the graphs above; in particular, Z_1 has four arrows from 0 to 1.

In the second case, E_2 is better represented ‘abstractly’, to avoid the partial superposition of paths in the former embedding; the central cell commutes

$$\begin{array}{ccccc}
 & & b' & \begin{array}{c} \xrightarrow{\quad} \\ \times \\ \xleftarrow{\quad} \end{array} & b & \longrightarrow & 1 \\
 & & \uparrow & & \uparrow & & \\
 0 & \longrightarrow & a' & \begin{array}{c} \xrightarrow{\quad} \\ \times \\ \xleftarrow{\quad} \end{array} & a & & E_2
 \end{array} \tag{113}$$

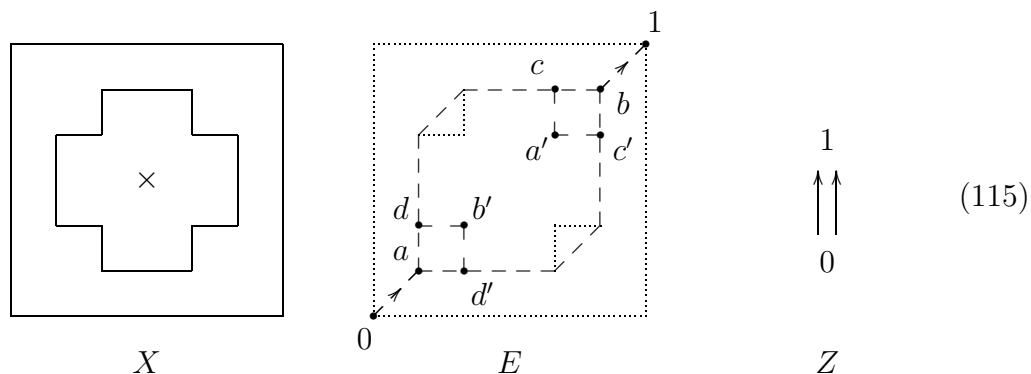
9.5. A PREORDERED SPACE. The compact space $X \subset [0, 1]^2$ represented below is now equipped with the preorder: $(x, y) \prec (x', y')$ if $y \leq y'$. All points having the same vertical coordinate are equivalent (and the topological spaces considered in (104), (111), with this preorder, would give the same results.)

The fundamental category $C = \uparrow\Pi_1(X)$ is no longer skeletal. Let us choose $m = (1/2, 0)$ as a minimum of X (weakly initial in C) and $m' = (1/2, 1)$ as a maximum

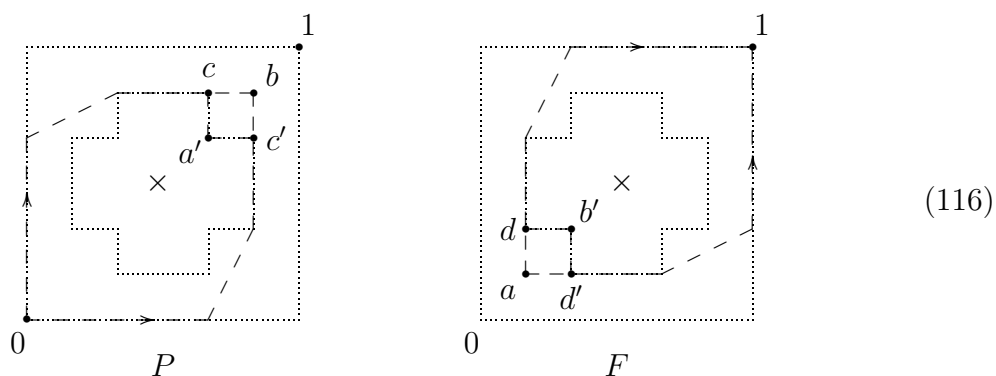


Now, the past spectrum of the fundamental category $C = \uparrow\Pi_1(X)$ is the full subcategory $P \subset C$ on three objects: m (a minimum), $a = (1/2, 2/5)$, $b = (1/2, 4/5)$ (V^- -branching points), as in the central figure above; of course, all of them can be equivalently moved, horizontally. The future spectrum is symmetric: $a' = (1/2, 1/5)$, $b' = (1/2, 3/5)$ and m' . The pf-spectrum is the full subcategory E on these six points (or any equivalent sextuple). It is isomorphic to the pf-spectrum E_1 of (111).

9.6. THE SWISS FLAG. Let us come back to ordered spaces. The following situation is often analysed as a basic one, in concurrency: the ‘Swiss flag’ $X \subset \uparrow[0, 1]^2$. See [4, 5, 6, 7] for a description of ‘the conflict of resources’ which it depicts, and [5], p. 84, for an analysis of the fundamental category which leads to a ‘category of components’ similar to the projective model we get here



Proceeding as above, the fundamental category $C = \uparrow\Pi_1(X)$ has an injective model E and a coarse model Z . Now, the past spectrum is the full subcategory $P \subset C$ represented below



The past spectrum $sp^-(C) = \{0, a', a, b, c, c'\}$ contains two minimal points $0, a'$ (note that the starting point 0 is not a minimum for \prec) and three V^- -branching points (b, c, c') . Similarly, the future spectrum is the full subcategory $F \subset C$ in the right figure above, on the future spectrum $sp^+(C) = \{a, d, d', b', 1\}$. The pf-spectrum of C is the full subcategory category E on $sp(C) = sp^-(C) \cup sp^+(C)$.

The spectral projective model M is shown below, under the same conventions as in (107)

$$\begin{array}{ccccc}
 \sigma' & \longrightarrow & \delta' & \longrightarrow & \beta \\
 \uparrow & & \uparrow & & \uparrow \\
 \gamma' & \longrightarrow & \mu & \xrightarrow{\nu} & \delta \\
 \uparrow & & \uparrow & & \uparrow \\
 \alpha & \longrightarrow & \gamma & \longrightarrow & \sigma''
 \end{array}
 \tag{117}$$

9.7. A THREE DIMENSIONAL CASE. Consider now the ordered compact space $X \subset \uparrow[0, 1]^3$ represented below (the complement of $]1/3, 2/3[^2 \times]2/3, 1[$)

$$\begin{array}{ccccc}
 0 & \longrightarrow & a & \xrightarrow{h} & b \\
 & & & \searrow h' & \downarrow u \\
 & & & & 1 \\
 & & & & \downarrow v \\
 & & & & 1
 \end{array}
 \tag{118}$$

$(uh = vh = h')$
 E

Then $C = \uparrow\Pi_1(X)$ is past contractible (0 is the initial object and past spectrum); it has future retract F formed of three points: 1 (the maximum, weakly terminal), a (an O^+ -branching point), b (V^+ -branching). The associated injective model (4.3) is the category E , embedded as the full subcategory on the objects $0, a, b, 1$.

9.8. FAITHFUL AND NON FAITHFUL SPECTRA. The situation is very different for the ordered compact space $X \subset \uparrow[0, 1]^3$ of the figure below (taking out an open cube in central position)

$$\begin{array}{l}
 X = \uparrow[0, 1]^3 \setminus A \\
 A =]1/3, 2/3[^3.
 \end{array}
 \tag{119}$$

The fundamental category $C = \uparrow\Pi_1(X)$ has an initial and a terminal object, 0 and 1. Therefore, C has pf-spectrum $\mathbf{2}$ (5.4), which is *not* faithful: indeed, C is not a preorder, since $C(x, y)$ has two arrows for

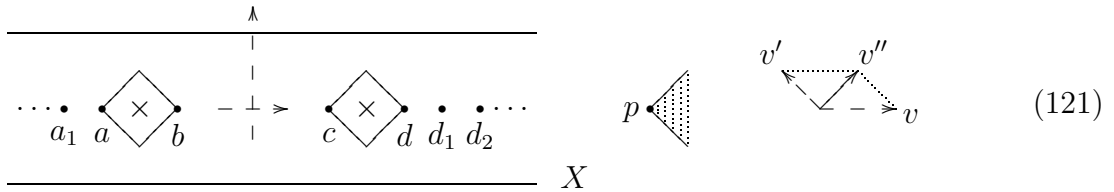
$$x < y, \quad a < x < a', \quad b < y < b', \quad x_3, y_3 \in]1/3, 2/3[. \quad (120)$$

Similar examples can be obtained by permutation of the coordinates.

Faithful directed equivalence should allow for a finer analysis; yet it does not seem simple to build a faithful injective or projective model: it seems reasonable that this should be at least countable, like the minimal injective model of the ordered line (5.5).

9.9. SOME HINTS TO APPLICATIONS. Applications of Directed Algebraic Topology to concurrency are well developed; the interested reader can begin from the references cited in the Introduction and see how the examples above can be interpreted in this domain. Here we want to hint to other possibilities, like the analysis of directed images, traffic networks and space-time models.

Consider the subspace $X \subset \mathbf{R} \times [-1, 1]$ obtained by taking out two open squares (marked with a cross). It is equipped with the order relation (122)



$$(x, y) \leq (x', y') \Leftrightarrow |y' - y| \leq x' - x, \quad (122)$$

whose ‘cone of the future’ at a point p is shown above.

First, this ordered spaces can be viewed as representing a stream with two islands; the stream moves rightward, with velocity v . The order relation expresses the fact that the observer can move, with respect to the stream, with an upper bound for scalar velocity (namely $|v'| \leq |v|.2^{-1/2}$), so that the composed velocity v'' can at most form an angle of 45° with the direction of the stream, as shown above, at the right.

Secondly, one can view the horizontal coordinate as time, the vertical one as position in a 1-dimensional physical medium and the order as the possibility of going from (x, y) to (x', y') with velocity ≤ 1 (with respect to a ‘rest frame’, linked with the medium). The two forbidden squares are now *linear* obstacles in the medium, with a limited duration in time (first expanding and then contracting).

The fundamental category $\uparrow\Pi_1(X)$ reveals obstructions (islands, temporary obstacles...). A minimal injective model E of the fundamental category is given by the full subcategory on the points marked above, in (121). E is generated by the following countable graph (under no conditions)

$$\dots a_2 \longrightarrow a_1 \longrightarrow a \rightrightarrows b \longrightarrow c \rightrightarrows d \longrightarrow d_1 \longrightarrow d_2 \dots \quad (123)$$

The analysis is similar to the one of (111). Moving the obstructions, one can get results similar to other previous cases (9.2, etc.); the fundamental category will detect whether these obstructions occur one after the other (as above) or ‘sensibly’ at the same time (as in 9.2).

Finally, the present analysis of a category through minimal past and future models has unexpectedly appeared to be related with notions recently introduced by A.C. Ehresmann [3], for investigating biosystems, neural systems, etc.—the ‘root’ and ‘coroot’ of a category. Such relations, having likely at their basis a common purpose of studying non-reversible phenomena, will be examined in a sequel.

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Dipartimento di Matematica Università di Genova
Via Dodecaneso 35 16146-Genova, Italy
Email: grandis@dima.unige.it

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