

Twisted Sectors for Lagrangian Floer Theory on Symplectic Orbifolds

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Abstract. The notion of twisted sectors play a crucial role in orbifold Gromov–Witten theory. We introduce the notion of dihedral twisted sectors in order to construct Lagrangian Floer theory on symplectic orbifolds and discuss related issues.

Key words: Floer theory; orbifold Lagrangians; dihedral twisted sectors

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*In honor of Professor Jean-Pierre Bourguignon
on the occasion of his 75th birthday*

1 Introduction

The mathematical theory of quantum cohomology and Gromov–Witten theory on symplectic manifolds was first developed by Y. Ruan and G. Tian [19] in the semi-positive case. This foundational work was extended later by K. Fukaya and the second named author [12], as well as J. Li and G. Tian [13], Y. Ruan [18] and B. Siebert [21]. W. Chen and Y. Ruan [3] extended the theory further to the case of symplectic orbifolds, where the object called twisted sectors or inertia orbifolds plays a significant role.

The inception of the theory, now known as Floer theory, is attributed to A. Floer. In [5], he laid the groundwork for the application to Lagrangian intersections, which became known as Lagrangian Floer theory. After the study in the case of monotone symplectic manifolds due to Y.-G. Oh [15, 16], K. Fukaya, Y.-G. Oh, H. Ohta and the second named author [6, 7] constructed Lagrangian Floer theory for general Lagrangian submanifolds. In the case that Lagrangian submanifolds do not intersect the orbifold loci in a symplectic orbifold, Lagrangian Floer theory was developed by C.-H. Cho and M. Poddar [4].

However, when considering Lagrangians that may intersect the orbifold loci, complications arise. To address this issue, we need to explore a specific class of Lagrangians and a variant of twisted sectors termed “dihedral twisted sectors”. These concepts are crucial for handling Lagrangian Floer theory. Since the diagonal in the product of two copies of an orbifold intersect the orbifold loci, we would like to treat the case that Lagrangians may intersect the orbifold loci.

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The main objective of this article is to present and elucidate these important concepts, demonstrating their significance in the context of Lagrangian Floer theory on symplectic orbifolds.

The contents are as follows. In Section 2, we briefly review Gromov–Witten theory and Lagrangian Floer theory on symplectic manifolds. Moving on to Section 3, we delve into fundamental notions concerning orbifolds and twisted sectors within the framework of orbifold Gromov–Witten theory. In Section 4, we introduce the notion of Lagrangians and their dihedral twisted sectors. In Section 5, we give a brief discussion on the filtered A_∞ -algebra associated with a Lagrangian in a closed symplectic orbifold.

2 The case of symplectic manifolds

In this section, we recall the framework of Gromov–Witten theory and Lagrangian Floer theory on symplectic manifolds. We use the construction over the universal Novikov ring, which is defined by

$$\Lambda_0 = \left\{ \sum_{i=1}^{\infty} a_i T^{\lambda_i} \mid a_i \in \mathbb{C}, \lambda_i \in \mathbb{R}_{\geq 0}, \lambda_i \rightarrow \infty \text{ for } i \rightarrow \infty \right\}.$$

Its unique maximal ideal Λ_+ is defined by replacing the condition $\lambda_i \in \mathbb{R}_{\geq 0}$ by $\lambda_i > 0$. The field of fractions of Λ_0 is denoted by Λ , which is called the universal Novikov field. Let (X, ω) be a closed symplectic manifold and J an almost complex structure compatible with ω . A J -holomorphic map from a nodal Riemann surface C equipped with distinct ordered ℓ marked points $\vec{x} = (x_1, \dots, x_\ell)$ away from nodes to (X, J) is called a stable map, if the automorphism group of $f: (C, \vec{x}) \rightarrow X$ is finite, i.e., the number of automorphisms φ of (C, \vec{x}) with $f \circ \varphi = f$ is finite.

For $A \in H_2(X; \mathbb{Z})$, we denote by $\mathcal{M}_{g,\ell}(X; A)$ the moduli space of stable maps of genus g , ℓ marked points and representing A . It is a compact metrizable space and carries the virtual fundamental class $[\mathcal{M}_{g,\ell}(X; A)]^{\text{vir}}$. Then the Gromov–Witten invariant is defined by

$$\text{GW}_{g,\ell,A}: H^*(X; \mathbf{Q})^{\otimes \ell} \rightarrow \mathbf{Q}, (\alpha_1, \dots, \alpha_\ell) \mapsto \int_{[\mathcal{M}_{g,\ell}(X; A)]^{\text{vir}}} \text{ev}_1^* \alpha_1 \wedge \cdots \wedge \text{ev}_\ell^* \alpha_\ell$$

and it satisfies Kontsevich–Manin’s axiom.¹ In particular, using genus 0 Gromov–Witten invariant, one obtains quantum cup product $*_c$ parametrized by $c \in H^*(X; \Lambda_0)$, i.e., the quantum cohomology ring of (X, ω) .

For a Lagrangian submanifold L in (X, ω) , one can also consider J -holomorphic maps from bordered nodal Riemann surfaces Σ with marked points to (X, J) which map the boundary $\partial\Sigma$ of Σ to L . Here nodes and marked points are of two types, i.e., (1) on the interior of Σ , (2) on the boundary $\partial\Sigma$. Boundary marked points $\vec{z} = (z_0, \dots, z_k)$ are disjoint from boundary nodes and interior marked points $\vec{x} = (x_1, \dots, x_\ell)$ are disjoint from interior nodes. A holomorphic map $u: (\Sigma, \partial\Sigma; \vec{z}, \vec{x}) \rightarrow (X, L)$ is called a bordered stable map, if the automorphism is finite. For $\beta \in H_2(X, L; \mathbb{Z})$, denote by $\mathcal{M}_{k+1,\ell}(X, L; \beta)$ the moduli space of bordered stable maps of genus 0 and with $k+1$ boundary marked points, ℓ interior marked points and connected boundary $\partial\Sigma$, representing β . For $k \geq 0$,² the moduli space $\mathcal{M}_{k+1,\ell}(X, L; \beta)$ is a compact metrizable space. A spin structure of L , if exists, determines orientation on $\mathcal{M}_{k+1,\ell}(X, L; \beta)$ and one can construct a virtual fundamental chain. Using the case that $\ell = 0$, we define a filtered A_∞ -algebra structure on the de Rham complex $\Omega^*(L) \hat{\otimes}_{\mathbb{C}} \Lambda_0$ by $\mathfrak{m}_k = \sum \mathfrak{m}_{k,\beta} T^{\int \beta, \omega}$, where $\mathfrak{m}_{k,\beta}: \Omega(L)^k \rightarrow \Omega(L)$ is given by

$$\begin{aligned} \mathfrak{m}_{k,\beta}(\xi_1, \dots, \xi_k) &= (-1)^*(\text{ev}_0)_!(\text{ev}_1^* \xi_1 \wedge \cdots \wedge \text{ev}_k^* \xi_k), & \text{unless } (k, \beta) = (0, 0), (1, 0), \\ \mathfrak{m}_{0,0} &= 0, & \mathfrak{m}_{1,0} = d \quad (\text{de Rham differential}). \end{aligned}$$

¹Except motivic axiom in symplectic case.

² $\mathcal{M}_{0,\ell}(X, L; \beta)$ may not be compact, unless we add stable map attached with a constant disk.

Here $(\text{ev}_0)_!$ is the integration along fibers, if ev_0 is a proper submersion. In general, it is defined using the theory of Kuranishi structures [11].

Using cases of all ℓ , we defined operators \mathfrak{p} , \mathfrak{q} (open-closed map, closed-open map) and bulk deformations of filtered A_∞ -structure by a cycle in X with Λ_+ -coefficients.

For a cleanly intersecting pair (L_0, L_1) of spin Lagrangian submanifolds, we can construct a filtered A_∞ -bimodule over the filtered A_∞ -algebras associated to L_0 and L_1 . We can extend these constructions for relatively spin Lagrangian submanifolds and relatively spin pair of Lagrangian submanifolds. For the definition and discussion on relative spin structures, see [7, Section 8.1.1]. The diagonal $\Delta_X \subset (X, -\omega) \times (X, \omega)$ is not necessary spin but relatively spin. Set $\xi_1 \cup_Q \xi_2 = (-1)^{\deg \xi_1 (\deg \xi_2 + 1)} \mathfrak{m}_2(\xi_1, \xi_2)$, Then we have the following.

Theorem 2.1 ([8]). *There is an isomorphism*

$$I: (\mathbb{H}^*(X; \Lambda_0), *_0) \cong (\mathbb{H}^*(\Delta_X; \Lambda_0), \cup_Q).$$

This statement must be plausible by naive comparison between the moduli spaces used for the product structures $*_0$, i.e., the small quantum product, and \cup_Q . However, the stable map compactifications of these moduli spaces have different boundary structures. To rectify such a discrepancy, a variant of the operation \mathfrak{p} mentioned above is used in the proof [8].

3 Orbifolds

3.1 Presentation of an orbifold by a proper étale Lie groupoid

A manifold is a geometric object locally modelled by a Euclidean space. A geometric object locally modelled by a quotient space of a Euclidean space by a finite group action³ is called an orbifold, which is a V-manifold⁴ introduced by Satake [20]. Namely, for each point p on an n -dimensional orbifold X , there is a neighborhood U of p such that $U \cong B^n/\Gamma_p$, where B^n is an open ball $B^n \subset \mathbb{R}^n$ and Γ_p is a finite group acting on \mathbb{R}^n linearly. We call $B^n \rightarrow B^n/\Gamma_p \cong U$ a local uniformizing cover. In the case of manifolds, there are coordinate changes among local coordinate neighborhoods. On an orbifold, there are equivariant diffeomorphisms among suitably shrunk local uniformization covers, which satisfy suitable compatibility condition.

We can define notions of (co)tangent vector bundles, more generally vector bundles, in a natural way. Differential forms and vector fields are defined as those on uniformization covers, which are invariant under the action of the finite groups Γ_p . For morphisms between orbifolds, if one defines it as a continuous map between the underlying topological spaces of orbifolds such that it is lifted to a smooth equivariant map between uniformization covers, one may still pull back differential forms. But this is not enough for pulling back vector bundles, in general. W. Chen and Y. Ruan introduced the notion of good maps. Here we review the notion using the terminology of groupoids, e.g., [14, Section 5.6].

A groupoid is a category $\mathcal{C} = (C_0, C_1, s, t, m, u, i)$ such that all morphisms are invertible. Here C_0 is the set of objects, C_1 is the set of morphisms, s (resp. t): $C_1 \rightarrow C_0$ is a map assigning the source (resp. target) to a morphism, $m: C_{1s} \times_{C_0} {}_t C_1 \rightarrow C_1$ is the composition of morphisms. Here $C_{1s} \times_{C_0} {}_t C_1 = \{(f, g) \in C_1 \times C_1 \mid s(f) = t(g)\}$ and the composition m enjoys the associativity. From now on, we may write $m(f, g) = f \circ g$. $i: C_1 \rightarrow C_1$ is a map assigning the inverse of a morphism, $u: C_0 \rightarrow C_1$ is the map assigning the unit morphism to an object in C_0 .

For $x, y \in C_0$, we define $x \sim_{\mathcal{C}} y$ if and only if $s^{-1}(x) \cap t^{-1}(y) \neq \emptyset$, namely, there is a morphism from x to y . Then $\sim_{\mathcal{C}}$ is an equivalence relation. Suppose that C_0, C_1 are manifolds, s, t are smooth maps such that s (or equivalently, t) is a submersion, $C_{1s} \times_{C_0} {}_t C_1$ has also a structure of a manifold. When m, u, i are also smooth maps, \mathcal{C} is called a Lie groupoid.

³We consider the action is effective in this article.

⁴T. Takakura asked Professor Satake what ‘‘V’’ stands for. His answer was Verzweigung.

Definition 3.1.

- (1) The quotient space of C_0 by the equivalence relation $\sim_{\mathcal{C}}$ is called the coarse space of \mathcal{C} , which is denoted by $|\mathcal{C}|$.
- (2) A groupoid \mathcal{C} is called a proper groupoid if $s \times t: C_1 \rightarrow C_0 \times C_0$ is proper.
- (3) A Lie groupoid \mathcal{C} is called a étale Lie groupoid, if s (or, equivalently, t) is a local diffeomorphism.

Roughly speaking, for an orbifold X , we can construct a proper étale Lie groupoid \mathcal{X} with an identification $|\mathcal{X}| \cong X$ of the coarse space of \mathcal{X} and the underlying topological space of the orbifold X . Namely, X_0 is the disjoint union of local uniformization covers and X_1 being the space of germs $[\psi]$ of local equivariant diffeomorphisms ψ between suitable open subsets of local uniformization covers such that ψ induces the identity on an open subset of $|\mathcal{X}| \cong X$. Denote by $\pi: X_0 \rightarrow |\mathcal{X}|$ the projection from the space of objects to the coarse space.

A proper étale Lie groupoid is locally described by an action groupoid (or translation groupoid) below [14, Proposition 5.30].

Definition 3.2. Let Γ be a group acting on U . We set $C_0 = U$, $C_1 = \Gamma \times U$, $s = \text{pr}_2$ (the projection to the second factor), $t: C_1 = \Gamma \times U \rightarrow U$ the action of Γ on U , $u(x) = (\text{id}, x)$, $i(\gamma, x) = (\gamma^{-1}, \gamma \cdot x)$. Define $m((\gamma, x), (\sigma, y)) = (\gamma \cdot \sigma, y)$, when $x = \sigma \cdot y$. Then $\mathcal{C} = (C_0, C_1, s, t, m, u, i)$ is a groupoid, which is called an action groupoid and is denoted by $\Gamma \ltimes U$. When U is a manifold and a finite group Γ acts on U smoothly, \mathcal{C} is a proper étale Lie groupoid.

From now on, we use the presentation of an orbifold X by a proper étale Lie groupoid \mathcal{X} in the following arguments.

Definition 3.3.

- (1) A differential form on an orbifold X presented by a proper étale Lie groupoid \mathcal{X} is a pair of differential forms η_0, η_1 on X_0 and X_1 , respectively, such that $\eta_1 = s^*\eta_0 = t^*\eta_0$. In particular, a symplectic form on X is a pair of symplectic forms ω_0, ω_1 on X_0, X_1 , respectively, such that $\omega_1 = s^*\omega_0 = t^*\omega_0$.
- (2) An almost complex structure on orbifold X is a pair of almost complex structures J_0, J_1 on X_0, X_1 , respectively, such that $s_* \circ J_1 = J_0 \circ s_*$, $t_* \circ J_1 = J_0 \circ t_*$.
- (3) A vector bundle E on an orbifold X is a pair of vector bundles E_0, E_1 on X_0, X_1 , respectively, equipped with consistent isomorphisms⁵ $s^*E_0 \cong E_1$, $t^*E_0 \cong E_1$. Principal bundles on an orbifold is defined in the same manner.

Next, we discuss the notion of morphisms between orbifolds. Let \mathcal{X} and \mathcal{Y} be proper étale Lie groupoids representing orbifolds X and Y . Since a groupoid is a category, it is natural to consider a functor $F = (F_0, F_1)$ such that $F_i: X_i \rightarrow Y_i$, $i = 0, 1$ are smooth (smooth functor). We call such a functor a strict smooth morphism from \mathcal{X} to \mathcal{Y} . It is, however, not sufficient, since, even in the case of smooth maps between manifolds, the image of a coordinate chart of X is not necessarily contained in a coordinate chart in Y . Therefore, we need to take a refinement of a groupoid.

Definition 3.4. A refinement of a proper étale Lie groupoid \mathcal{X} associated with an open covering $\{U^{(j)}\}$ of X_0 is a proper Lie groupoid with $U_0 = \bigsqcup_j U^{(j)}$, $U_1 = \bigsqcup_{i,j} t^{-1}(U^{(j)}) \cap s^{-1}(U^i)$ such that the structure maps s, t, m, u, i are naturally induced from those for \mathcal{X} .

⁵These isomorphisms gives an action of X_1 on E_0 .

For orbifolds X, Y , we define a morphism from X to Y as a smooth functor from some refinement of \mathcal{X} to \mathcal{Y} . Let us go back to the case of smooth maps between manifolds, the *same* map may be described as various system of maps between coordinate charts, i.e., the image of a coordinate chart of X may be contained in various coordinate charts of Y . Hence the description as a smooth functor is not unique. Thus we need to consider smooth natural transformation between two smooth functors.

To be precise, let $\mathbf{Mor}_0(\mathcal{X}, \mathcal{Y})$ be the object space consisting of smooth functors from a refinement of \mathcal{X} to \mathcal{Y} , with its element given by

$$\mathcal{X} \xleftarrow{\phi} \mathcal{U} \xrightarrow{u} \mathcal{Y},$$

where $\phi: \mathcal{U} \rightarrow \mathcal{X}$ is a refinement of \mathcal{X} , and $u: \mathcal{U} \rightarrow \mathcal{Y}$ is a strict smooth morphism. We simply denote this object by (\mathcal{U}, ϕ, u) . Given two objects (\mathcal{U}, ϕ, u) and (\mathcal{V}, ψ, v) a morphism from (\mathcal{U}, ϕ, u) and (\mathcal{V}, ψ, v) is a common refinement \mathcal{W} of \mathcal{U} and \mathcal{V} together with a natural transformation $\alpha: u \circ \pi_1 \Rightarrow v \circ \pi_2$ as illustrated in following diagram:

This forms the morphism space $\mathbf{Mor}_1((\mathcal{U}, \phi, \mathbf{u}), (\mathcal{V}, \psi, \mathbf{v})) \subset \mathbf{Mor}_1(\mathcal{X}, \mathcal{Y})$. The composition of two composable morphisms and other structure maps can be found in [2] where the Sobolev completion of $\mathbf{Mor}(\mathcal{X}, \mathcal{Y})$ is developed.⁶ For any continuous morphism $f \in \mathbf{Mor}_0(\mathcal{X}, \mathcal{Y})$ in this sense, we can pull-back vector bundle E in the sense of Definition 3.3 (3). For $f, g \in \mathbf{Mor}_0(\mathcal{X}, \mathcal{Y})$, if there is a morphism $T \in \mathbf{Mor}_1(\mathcal{X}, \mathcal{Y})$ from f to g , T induces an isomorphism between f^*E and g^*E .

3.2 Twisted sector and orbifold stable maps

We introduce the notion of the twisted sector (or inertia groupoid) for an orbifold X presented by a proper étale Lie groupoid \mathcal{X} .

Definition 3.5. For a proper étale Lie groupoid \mathcal{X} , we set

$$\begin{aligned} IX_0 &= \{a \in X_1 \mid s(a) = t(a)\}, & IX_1 &= \{a \xrightarrow{g} b \mid a, b \in IX_0, g \in X_1, b = g \circ a \circ i(g)\}, \\ s(a \xrightarrow{g} b) &= a, & t(a \xrightarrow{g} b) &= b, & m(b \xrightarrow{h} c, a \xrightarrow{g} b) &= a \xrightarrow{h \circ g} c, \\ i(a \xrightarrow{g} b) &= b \xrightarrow{i(g)} a, & u(a) &= a \xrightarrow{u(s(a))} a. \end{aligned}$$

Then we obtain a groupoid

$$\mathcal{IX} = (IX_0, IX_1, s, t, m, u, i).$$

We call it the twisted sector (or inertia groupoid) of \mathcal{X} . The twisted sector of a proper étale Lie groupoid \mathcal{X} is a proper étale Lie groupoid, although the dimension depends on its connected components. Note that IX_0 contains the space of identities, which is identified with X_0 . The restriction of \mathcal{IX} to X_0 is called the trivial twisted sector (or the untwisted sector).

⁶There is a formulation in terms of bibundles. For the purpose of the moduli spaces of stable maps with Kuranishi structures, we use the description given here.

For example, the twisted sector $\mathcal{I}(\Gamma \times U)$ of an action groupoid $\Gamma \times U$ is described as

$$\begin{aligned} I(\Gamma \times U)_0 &= \{(\gamma, x) \in \Gamma \times U \mid \gamma \cdot x = x\}, \\ I(\Gamma \times U)_1 &= \{(\gamma, x) \xrightarrow{\rho} (\sigma, y) \mid \gamma \cdot x = x, \sigma \cdot y = y, y = \rho \cdot x, \sigma = \rho \circ \gamma \circ \rho^{-1}\}. \end{aligned}$$

When an orbifold X is equipped with an almost complex structure $J = (J_0, J_1)$, we assign the age (or the degree shifting number) to $a \in IX_0$. Considering the situation locally, we reduce the discussion to the case of an action groupoid. Then a is given by $(\gamma, x) \in I(\Gamma \times U)_0$. We regard $\gamma: U \rightarrow U$ around x a J_0 -linear map $\gamma: \mathbb{C}^n \rightarrow \mathbb{C}^n$ (x corresponds to the origin of \mathbb{C}^n). Since Γ is a finite group, there is a minimal positive integer m such that $\gamma^m = \text{id}$ and the action by γ around x is diagonalizable and presented by a matrix conjugate to

$$\text{diag}(\exp(2\pi m_1 \sqrt{-1}/m), \dots, \exp(2\pi m_n \sqrt{-1}/m)),$$

where $0 \leq m_j < m$, $j = 1, \dots, n$. Then we set $\text{age}(\gamma, x) = (m_1 + \dots + m_n)/m$ and call it the age (or the degree shifting number) of (γ, x) . The age is a locally constant function on (the space of objects of) the twisted sector. More generally, for an orbifold complex vector bundle, we define the age of the Γ -action on the fiber.

The age is an important invariant associated with the action of $\gamma \in \Gamma$ on a complex vector bundle. Specifically, when considering the Dolbeault operator acting on sections of holomorphic orbifold vector bundle over an orbifold Riemann surface, its Fredholm index is, by definition, an integer. However, the orbifold Chern number is a rational number, not necessarily an integer. Consequently, in this context, the topological quantity appearing in Riemann–Roch theorem is corrected by the age (for the local action on the vector bundle). In the theory of stable maps from an orbifold Riemann surface, an elliptic operator acting on the pull-back of the tangent bundle of the target by an orbifold stable map appears as the linearization of the equation for pseudo-holomorphic maps. Such an operator has the same principal symbol as the Dolbeault operator with coefficients in a holomorphic orbifold vector bundle, i.e., the pull-back of the tangent bundle. Thus the (virtual) dimension of the moduli space is expressed by the Fredholm index of the linearization operator and the age mentioned above plays an important role.

A holomorphic map from an orbifold Riemann surface C to an almost complex orbifold X is defined to be a smooth functor $F = (F_0, F_1)$ from a refinement \mathcal{C} of a proper étale Lie groupoid representing C to a proper étale Lie groupoid \mathcal{X} equipped with an almost complex structure (J_0, J_1) representing X such that F_0, F_1 are holomorphic with respect to J_0, J_1 , respectively. Here, C is an effective orbifold (locally, the action groupoid $\Gamma \times D$ associated with an effective action of a finite group Γ on the unit disk $D \subset \mathbb{C}$ keeping the origin fixed). The almost complex orbifold X is also locally presented by an action groupoid associated with an effective action of a finite group G on an almost complex manifold. Then a morphism $\phi: \Gamma \times D \rightarrow G \times U$ is given by a pair of $\phi_0: D \rightarrow U$ and a homomorphism $\phi_1: \Gamma \rightarrow G$ such that ϕ_0 is ϕ_1 -equivariant J_0 -holomorphic map. In orbifold Gromov–Witten theory, we only consider those such that the homomorphism ϕ_1 is injective.

We next explain a pseudo-holomorphic $\phi: \mathcal{C} \rightarrow \mathcal{X}$ takes values in the twisted sector. Pick an action groupoid $\Gamma \times D$ (with $O \in D$ representing p) presenting a neighborhood of $p \in C$ and an action groupoid $G \times U$ presenting a neighborhood of $|\phi|(p) \in X$. Here $|\phi|$ is the map from $|\mathcal{C}|$ to $|\mathcal{X}|$ induced by ϕ . Let $\eta \in \Gamma$ be the generator corresponding to $\exp(2\pi\sqrt{-1}/m)$. Then $(\phi_1(\eta), \phi_0(O))$ belongs to IX_0 . If η is not trivial, $(\phi_1(\eta), \phi_0(O))$ belongs to a non-trivial twisted sector, since ϕ_1 is injective. When there is a natural transformation between $\phi = (\phi_0, \phi_1)$ and $\phi' = (\phi'_0, \phi'_1)$, the equivalence classes of $(\phi_1(\eta), \phi_0(O))$ and $(\phi'_1(\eta), \phi'_0(O))$ in $|\mathcal{X}|$ are the same. Therefore, the image in $|\mathcal{X}|$ is well defined.

An orbifold stable map from an orbifold nodal Riemann surface C to an almost complex orbifold X is defined in the following way. Take a normalization $p: \tilde{C} \rightarrow C$ of C . Then, for each

(possibly orbifold) node $z \in C$, there is a pair $(z', z'') \in \tilde{C} \times \tilde{C}$. An orbifold holomorphic map from C to X is represented by an orbifold holomorphic map from \tilde{C} to X such that, for each node z , $(z'$ and $z'')$ are mapped to (g, x) and (g^{-1}, x) , for some $g \in G$ and $x \in U$, in the twisted sector of $G \times U$ which is a local model of \mathcal{X} . The stable condition is, as usual, the finiteness of the automorphism of the map.

In ordinary Gromov–Witten theory, our focus lies on holomorphic maps from nodal Riemann surfaces. However, in orbifold Gromov–Witten theory, we also consider holomorphic maps from orbifold Riemann surfaces allowing orbifold nodes. It is not possible to obtain the nodal orbifold structure simply by looking at the degeneration of domain orbifold Riemann surfaces. Instead, we need to investigate the degeneration of holomorphic curves. To achieve this, we introduce an orbifold structure around nodes ensuring that the homomorphism ϕ_1 above is injective.

Similar to the case of manifolds, for a symplectic orbifold X , we pick an compatible almost complex structure. Fix a homology class A (the homology class of the map between coarse spaces), the moduli space $\mathcal{M}_{g,\mathbf{m}}(A)$ of orbifold stable maps representing A is compact Hausdorff and carries a virtual fundamental class. (The injectivity of ϕ_1 mentioned above is used for the effectivity of the Kuranishi structure.) Here, g is the genus of the domain curve, $\mathbf{m} = (m_1, \dots, m_\ell)$ is the data of marked orbifold points. (When $m_j = 1$, the marked point is a regular point.) We can define the evaluation map $\text{ev}_j: \mathcal{M}_{g,\mathbf{m}}(A) \rightarrow |\mathcal{I}X|$, $j = 1, \dots, \ell$. Using them, *orbifold Gromov–Witten invariant*

$$\text{GW}_{g,\ell,A}: H^*(|\mathcal{I}X|)^{\otimes \ell} \rightarrow \mathbb{Q}$$

is defined by

$$(\alpha_1, \dots, \alpha_\ell) \mapsto \sum_{|\mathbf{m}|=\ell} \int_{[\mathcal{M}_{g,\mathbf{m}}(A)]^{\text{vir}}} \text{ev}_1^* \alpha_1 \wedge \dots \wedge \text{ev}_\ell^* \alpha_\ell.$$

It is a convention that the grading of $H^*(|\mathcal{I}X|)$ is shifted by twice of the age of each connected component of $|\mathcal{I}X|$.

4 Lagrangian and dihedral twisted sector

4.1 Definition of Lagrangians

A Lagrangian submanifold L in a symplectic manifold X has a neighborhood, which is symplectomorphic to a tubular neighborhood of the zero section of the cotangent bundle T^*L of L (Weinstein). The zero section is the fixed point set of the fiberwise multiplication by -1 , which is an anti-symplectic involution. Hence there is a neighborhood W of L and an involution $\tau: W \rightarrow W$ with $\tau^* \omega = -\omega$ such that L is the fixed point set of τ . Based on this fact, we introduce an orientifold structure on a symplectic orbifold and define an associated Lagrangian in a symplectic orbifold as follows.

Let $(s, t): (X_1, \omega_1) \rightrightarrows (X_0, \omega_0)$ be a proper étale Lie groupoid representing the symplectic orbifold (\mathcal{X}, ω) , that is, (X_0, ω_0) is a symplectic manifold and $\omega_1 = s^* \omega_0 = t^* \omega_0$.

Firstly, we introduce the notion of symplectic orientifolds. Denote by $B\mathbb{Z}_2$ the action groupoid of the trivial $\mathbb{Z}_2 \cong \{\pm 1\}$ action on a point, i.e., $\{\pm 1\} \times \{pt\}$. An orientifold structure on (\mathcal{X}, ω) is a proper étale Lie groupoid $\tilde{\mathcal{X}} = (\tilde{X}_1 \rightrightarrows \tilde{X}_0)$

$$\mathcal{X} \longrightarrow \tilde{\mathcal{X}} \xrightarrow{\varepsilon} B\mathbb{Z}_2,$$

where $\tilde{X}_0 = X_0$ and $\varepsilon: \tilde{\mathcal{X}} = (\tilde{X}_1 \rightrightarrows \tilde{X}_0) \rightarrow B\mathbb{Z}_2 \cong \{\pm 1\} \times \{pt\}$ is a strict groupoid morphism such that $\text{Ker}(\varepsilon) = \mathcal{X}$ and, for any arrow $\gamma \notin \text{ker}(\varepsilon)$, the local diffeomorphism $\psi_\gamma: U_{s(\gamma)} \rightarrow U_{t(\gamma)}$

is an anti-symplectomorphism. Here $U_{s(\gamma)}$ and $U_{t(\gamma)}$ are open neighbourhoods of $s(\gamma)$ and $t(\gamma)$ respectively in X_0 such that, for $p \in U_{s(\gamma)}$ (resp. $q \in U_{t(\gamma)}$), ψ_γ gives an arrow γ' (resp. γ''), with $s(\gamma') = p$ (resp. $t(\gamma'') = q$). Namely, ψ_γ gives local sections $U_{s(\gamma)} \rightarrow \tilde{X}_1$ and $U_{t(\gamma)} \rightarrow \tilde{X}_1$. Equivalently, we can decompose the arrow space \tilde{X}_1 as a disjoint union $\tilde{X}_1 = X_1 \cup X_{-1}$, where $X_{-1} = \{\gamma \in \tilde{X}_1 \mid \varepsilon(\gamma) = -1\}$. The induced maps $(s, t): X_{-1} \rightrightarrows X_0$ satisfy $s^*\omega_0 = -t^*\omega_0$. Note that $(s, t): X_{-1} \rightrightarrows X_0$ is not a groupoid, as any product of composable arrows γ and γ' with $\varepsilon(\gamma) = \varepsilon(\gamma') = -1$ is not an arrow in X_{-1} as $\varepsilon(\gamma\gamma') = 1$. We call γ with $\varepsilon(\gamma) = -1$ an odd arrow (or odd morphism).

For $x \in X_0$, let Γ_x and $\tilde{\Gamma}_x$ be the isotropy group of x in \mathcal{X} and $\tilde{\mathcal{X}}$ respectively, then an orientifold structure induces an extension of the local group Γ_x

$$\{1\} \rightarrow \Gamma_x \longrightarrow \tilde{\Gamma}_x \longrightarrow \mathbb{Z}_2 \rightarrow \{1\}.$$

We simply denote an orientifold structure on (\mathcal{X}, ω) by $(\tilde{\mathcal{X}}, \omega, \varepsilon)$.

Now, we introduce the notion of Lagrangians in symplectic orbifolds. Let L be a subset of $X \cong |\mathcal{X}|$. We shall call L the underlying space of a Lagrangian in the symplectic orbifold X , if there is a neighborhood W of L equipped with an open orientifold structure on $\mathcal{W} = \pi^{-1}(W)$ in the following sense. Here $\pi: X_0 \rightarrow |\mathcal{X}|$ is the projection to the coarse space.

An open orientifold structure on (\mathcal{X}, ω) is an open suborbifold \mathcal{W} of (\mathcal{X}, ω) with an orientifold structure $(\tilde{\mathcal{W}}, \omega, \varepsilon)$ on (\mathcal{W}, ω) . Let (\mathcal{W}, ω) be an open suborbifold of (\mathcal{X}, ω) , represented by $(W_1 \rightrightarrows W_0)$, where W_0 is an open submanifold of X_0 , and $W_1 = s^{-1}(W_0) \cap t^{-1}(W_0)$. Assume that \mathcal{W} admits an orientifold structure $\tilde{\mathcal{W}} = ((\tilde{W}_1 \rightrightarrows \tilde{W}_0), \omega, \varepsilon)$. We can define a Lagrangian $\mathcal{L} = (L_1 \rightrightarrows L_0)$ in (\mathcal{X}, ω) associated to the orientifold structure $(\tilde{\mathcal{W}}, \varepsilon)$ as follows,

Denote by $\text{Inv}(\tilde{W}_1) = \{\tau \in \tilde{W}_1 \mid \varepsilon(\tau) = -1, s(\tau) = t(\tau), \tau^2 = u(s(\tau))\}$ the space of involutive odd arrows in \tilde{W}_1 . Then there is the adjoint action of W_1 on $\text{Inv}(\tilde{W}_1)$, i.e., $(\gamma, \tau) \in (W_1)_s \times_t \text{Inv}(\tilde{W}_1) \mapsto \gamma \cdot \tau \cdot \gamma^{-1} \in \text{Inv}(\tilde{W}_1)$. Note that $\text{Inv}(\tilde{W}_1)$ is a manifold of dimension $\frac{1}{2} \dim X$. A Lagrangian in a symplectic orbifold is the following data.

- (1) \mathcal{I} is a collection of connected components of $\text{Inv}(\tilde{W}_1)$, which is invariant under the adjoint action by W_1 .
- (2) The space L_0 is defined by

$$L_0 = \{(x, \tau) \mid x \in W_0, \tau \in \mathcal{I}, s(\tau) = t(\tau) = x\} = \bigsqcup_{\tau \in \mathcal{I}} \tilde{W}_0^\tau,$$

where $\tilde{W}_0^\tau = \{x \in \tilde{W}_0 = W_0 \mid x = s(\tau) = t(\tau)\}$ (the fixed point set of τ), such that

$$L = \bigcup_{\tau \in \mathcal{I}} \pi(\tilde{W}_0^\tau).$$

- (3) The morphism space L_1 between two elements (x, τ) and (y, τ') :

$$\text{Mor}_{\mathcal{L}}((x, \tau), (y, \tau'))$$

consists of $\gamma \in \text{Mor}_{\mathcal{W}}(x, y)$ satisfies $\gamma\tau\gamma^{-1} = \tau'$. There are canonical maps $(s, t): L_1 \rightrightarrows L_0$. The composition, unit and inverse maps are induced from the corresponding maps for $\mathcal{W} = (W_1 \rightrightarrows W_0)$.

If these conditions are fulfilled, we call \mathcal{L} a *Lagrangian* in the symplectic orbifold (\mathcal{X}, ω) associated to an open orientifold structure $(\tilde{\mathcal{W}}, \omega, \varepsilon)$ on an open suborbifold (\mathcal{W}, ω) of (\mathcal{X}, ω) . A Lagrangian in (\mathcal{X}, ω) is a Lagrangian associated to some open orientifold structure $(\tilde{\mathcal{W}}, \omega, \varepsilon)$ and some \mathcal{I} .

Note that $\mathcal{L} = (L_1 \rightrightarrows L_0)$ is a proper étale Lie groupoid. There is a canonical strict morphism

$$(\iota_1, \iota_0): (L_1 \rightrightarrows L_0) \longrightarrow (W_1 \rightrightarrows W_0)$$

such that $\iota_0: L_0 \rightarrow W_0$ is an immersion, and the groupoid structure on $L_1 \rightrightarrows L_0$ is induced from the groupoid action of \mathcal{W} on L_0 .

When \mathcal{W} is locally described by a finite group action groupoid $G \times U \rightrightarrows U$, the orientifold structure implies that there is an exact sequence of groups

$$\{1\} \rightarrow G \longrightarrow \tilde{G} \xrightarrow{\varepsilon} \mathbb{Z}_2 \rightarrow \{1\}$$

such that $g \in \tilde{G}$ -action on U satisfies $g^*\omega = \varepsilon(g)\omega$. Let I be a subset of $\text{Inv}(\tilde{G})$, which is the set of all $g \in \tilde{G}$ such that $g^2 = 1$ and $\varepsilon(g) = -1$. If I is invariant under the adjoint action by G , we can also have a Lagrangian \mathcal{L}_I , which is an open and closed suborbifold of \mathcal{L} .

As an example of a Lagrangian in a symplectic orbifold, we consider the diagonal $\Delta_{\mathcal{X}}$ in the product $(\mathcal{X} \times \mathcal{X}, -\text{pr}_1^*\omega + \text{pr}_2^*\omega)$ of a symplectic orbifold (\mathcal{X}, ω) . Firstly, we review the diagonal in the setting of orbifolds, cf. [1, Example 2.6]. Let \mathcal{X} be the proper étale Lie groupoid presenting X . Then we define the diagonal groupoid $\Delta_{\mathcal{X}}$ by

$$\begin{aligned} (\Delta_{\mathcal{X}})_0 &= \{(x, \alpha, y) \in X_0 \times X_1 \times X_0 \mid s(\alpha) = x, t(\alpha) = y\} \\ (\Delta_{\mathcal{X}})_1 &= \{(x, \alpha, y) \xrightarrow{h_1, h_2} (x', \alpha', y') \mid h_1, h_2 \in X_1, \\ &\quad s(h_1) = x, t(h_1) = x', s(h_2) = y, t(h_2) = y', m(h_2, \alpha) = m(\alpha', h_1)\} \end{aligned}$$

such that the structure maps s, t, m, u, i are naturally induced from \mathcal{X} . Then $\Delta_{\mathcal{X}}$ is a groupoid. When $\mathcal{X} = (G \times U \rightrightarrows U)$, we find that

$$(\Delta_{G \times U})_0 = \bigsqcup_{g \in G} \Delta_g, \Delta_g = \{(x, gx) \mid x \in U\}, \quad (\Delta_{G \times U})_1 = (G \times G) \times \left(\bigsqcup_{g \in G} \Delta_g \right).$$

We use the notation $(x, gx; g)$ for $(x, gx) \in \Delta_g$. We set $s((h_1, h_2), (x, gx; g)) = (x, gx; g)$, $t((h_1, h_2), (x, gx; g)) = (h_1x, h_2gx; h_2gh_1^{-1})$, etc. In other words, $\Delta_{G \times U}$ is the action groupoid $(G \times G) \times \bigsqcup \Delta_g$ associated with the action of $G \times G$ on $\bigsqcup \Delta_g$.

Now we discuss the canonical orientifold structure on $(\mathcal{X}, -\omega) \times (\mathcal{X}, \omega)$ defined by the canonical involution τ_{can} of switching two components. Suppose that a local model for \mathcal{X} is given by a finite group action groupoid $(G \times U \rightrightarrows U)$ as above. Note that Δ_{id} is the fixed point set of the involution $\tau_{\text{can}}(x, x') = (x', x)$. Since τ_{can} is the reflection with respect to Δ_{id} , we set $\tau_{\text{id}} = \tau_{\text{can}}$. Note also that $\Delta_g = (1, g)\Delta_{\text{id}}$ is the fixed point set of

$$\tau_g = (1, g) \circ \tau_{\text{id}} \circ (1, g^{-1}) = (g^{-1}, g) \circ \tau_{\text{id}}.$$

Denote by $\widetilde{G \times G}$ the group generated by $G \times G$ and τ_{id} . Then we see that $\widetilde{G \times G}$ is the semi direct product

$$\widetilde{G \times G} = (G \times G) \rtimes \mathbb{Z}_2$$

with the \mathbb{Z}_2 -action is defined by the adjoint action by the involution $(g_1, g_2) \mapsto \tau_{\text{can}} \cdot (g_1, g_2) \cdot \tau_{\text{can}}^{-1} = (g_2, g_1)$ for $(g_1, g_2) \in G \times G$. Then the corresponding local model for $\mathcal{X} \times \mathcal{X}$ is

$$(G \times G) \times (U \times U) \rightrightarrows U \times U.$$

Note that the odd involutive elements in $\widetilde{G \times G}$ consists of $\{(g^{-1}, g) \circ \tau_{\text{can}} \mid g \in G\}$, and the fixed point of the involution action $(g^{-1}, g) \circ \tau_{\text{can}}$ on $U \times U$ consists of $\{(x, gx) \mid x \in U\}$.

The Lagrangian \mathcal{L} for this orientifold structure can be described as follows. (In this case, we take $\mathcal{I} = \text{Inv}((\mathcal{X} \times \mathcal{X})_1)$.) For an order m element $g \in G$, there is a monomorphism from the dihedral group

$$D_m \longrightarrow \widetilde{G} \times G$$

with the image generated by (g^{-1}, g) and τ . So, locally over $U \times U$, the associated Lagrangian is presented by $(L_0^U \rightrightarrows L_1^U)$ with the unit space

$$L_0^U = \bigsqcup_{g \in G} \text{Fix}((g^{-1}, g) \circ \tau_{\text{can}}) = \bigsqcup_{g \in G} \{(x, gx; g) \mid g \in G, x \in U\},$$

and the morphism space $L_1^U = (G \times G) \times L_0^U$ with the obvious action

$$(h_1, h_2): (x, gx; g) \mapsto (h_1x, h_2gx; h_2gh_1^{-1})$$

for $(h_1, h_2) \in G \times G$, here (h_1x, h_2gx) is a fixed point of the involutive element

$$(h_1g^{-1}h_2^{-1}, h_2gh_1^{-1}) \circ \tau_{\text{can}}.$$

We clearly see that \mathcal{L} is equivalent to $\Delta_{\mathcal{X}}$, which we discussed above. So this canonical Lagrangian is indeed \mathcal{X} diagonally embedded in $(\mathcal{X}, -\omega) \times (\mathcal{X}, \omega)$. Locally, we can check that the natural inclusion $(\phi_1, \phi_0): (G \rtimes U \rightrightarrows U) \rightarrow (L_1^U \rightrightarrows L_0^U)$ is the equivalence where $\phi_0(x) = (x, x; \text{id})$ and $\phi_1(g, x) = ((g, g), (x, x; \text{id}))$.

Clearly, the groupoid $\Delta_{G \times U}$ is isomorphic to $(L_1^U \rightrightarrows L_0^U)$, which we obtained from the symplectic orientifold.

4.2 Dihedral twisted sector

Let \mathcal{L} be a Lagrangian of a symplectic orbifold (\mathcal{X}, ω) associated to a local orientifold structure $(\widetilde{\mathcal{W}}, \omega, \varepsilon)$ on an open symplectic suborbifold (\mathcal{W}, ω) as in the previous subsection. Let $\mathcal{W} = (W_1 \rightrightarrows W_0)$. We introduce a notion of the dihedral twisted sectors of a Lagrangian in a symplectic orbifold.

Definition 4.1. For a Lagrangian $\mathcal{L} = (L_1 \rightrightarrows L_0)$ in a symplectic orbifold (\mathcal{X}, ω) as above, we have the following proper étale Lie groupoid $I_{\mathcal{X}}\mathcal{L}$ such that the space of objects is given by

$$(I_{\mathcal{X}}\mathcal{L})_0 = L_0 \times_{\widetilde{W}_0} L_0 = \bigsqcup_{\tau, \tau' \in \mathcal{I}} \widetilde{W}_0^{\tau} \cap \widetilde{W}_0^{\tau'}$$

and the space of morphisms is induced from the diagonal action of \mathcal{W} -action on $L_0 \times_{\widetilde{W}_0} L_0$ in the sense that for any point

$$(x, \tau, \tau') \in \widetilde{W}_0^{\tau} \cap \widetilde{W}_0^{\tau'} \subset L_0 \times_{\widetilde{W}_0} L_0$$

and $h \in s^{-1}(x) \subset W_1$, $h \cdot (x, \tau, \tau') = (t(h), h\tau h^{-1}, h\tau' h^{-1})$. Equivalently, for any pair (x, τ, τ') and $(y, \tilde{\tau}, \tilde{\tau}')$ in $(I_{\mathcal{X}}\mathcal{L})_0$,

$$\text{Mor}_{I_{\mathcal{X}}\mathcal{L}}((x, \tau, \tau'), (y, \tilde{\tau}, \tilde{\tau}')) = \{h \in \text{Mor}_{\mathcal{W}}(x, y) \mid \tilde{\tau} = h\tau h^{-1}, \tilde{\tau}' = h\tau' h^{-1} \in \widetilde{W}_1\}$$

with the obvious source and target maps. The other structure maps m, u, i are induced from the corresponding maps in \mathcal{W} . We call $I_{\mathcal{X}}\mathcal{L}$ the *dihedral twisted sector*⁷ of the Lagrangian \mathcal{L} in the symplectic orbifold \mathcal{X} .

⁷Let \mathbb{Z}_m, D_m be the cyclic group of order m and the dihedral group of order $2m$, respectively. Then the dihedral twisted sector of \mathcal{L} can be described as

$$\mathcal{W} \times \bigsqcup_{m \in \mathbb{N}} \text{IMor}(BD_m, \widetilde{\mathcal{W}}).$$

Here the symbol IMor in the notation indicates that the injectivity on the level of morphism spaces is required.

Recall the exact sequence $\{1\} \rightarrow W_1 \rightarrow \widetilde{W}_1 \xrightarrow{\varepsilon} \{\pm 1\} \rightarrow \{1\}$. For any pair $\tau, \tau' \in \text{Inv}(\widetilde{W}_1)$ with non-empty $\widetilde{W}_0^\tau \cap \widetilde{W}_0^{\tau'}$, then $\tau'\tau^{-1} = g \in W_1$ and $\tau g \tau = g^{-1}$. Pairs (τ, τ') of odd involutions is in one-to-one correspondence with pairs (τ, g) of odd involution and an element of W_1 such that $\tau \cdot g \cdot \tau = g^{-1}$. So we can rephrase the definition of the dihedral twisted sector using (x, τ, g) for $g \in W_1$ satisfying $\tau g \tau = g^{-1}$ (dihedral relation).⁸

Now, we discuss the case of the diagonal $\Delta_{\mathcal{X}}$ in Section 4.1. In fact, it motivated us to make the definition of the dihedral twisted sector. We first consider a holomorphic map $\Phi = (\Phi_0, \Phi_1)$ from a half infinite cylinder

$$[0, \infty) \times [-1, 1]/(\tau, -1) \sim (\tau, 1)$$

to a complex orbifold presented by $G \ltimes U$, the action groupoid of the action of a finite group G on U . Note that the half infinite cylinder is presented by the following groupoid $\mathcal{C} = (C_0, C_1)$ such that $C_0 = [0, \infty) \times [-1, 1]$ and C_1 is the disjoint union of $\{\text{id}_{(\tau, t)} | (\tau, t) \in [0, \infty) \times [-1, 1]\}$ and $\{a_{(\tau, 1)}: (\tau, 1) \rightarrow (\tau, -1)\}, \{a_{(\tau, -1)}: (\tau, -1) \rightarrow (\tau, 1)\}$. We define the structure maps s, t, m, u, i in an obvious way. This groupoid⁹ is a presentation of the equivalence relation \sim on C_0 . Then Φ is given by the pair of a holomorphic map $\Phi_0: [0, \infty) \times [-1, 1] \rightarrow U$, $\Phi_1: C_1 \rightarrow (G \ltimes U)_1$ such that $\Phi_1(\text{id}_{(\tau, t)}) = u(\Phi_0(\tau, t))$, $\Phi_1(a_{(\tau, -1)}) = (g(\tau), \Phi_0(\tau, -1))$ and $\Phi_1(a_{(\tau, 1)}) = (g(\tau)^{-1}, \Phi_0(\tau, 1))$ for some $g(\tau) \in G$. Since Φ_1 is continuous, Φ_1 is regarded as a locally constant function with values in G . We set $\gamma = \Phi_1(a_{(\tau, -1)})$. Here, the condition that $\Phi_0(\tau, 1) = \gamma \cdot \Phi_0(\tau, -1)$ is required. Since γ is of finite order, we obtain a holomorphic map from a finite cover of the half-infinite cylinder to U . If Φ_0 is a holomorphic map with finite energy, the limit

$$p = \lim_{\tau \rightarrow \infty} \Phi_0(\tau, t)$$

exists and is independent of t . Thus we find that $\gamma \cdot p = p$, i.e., $(\gamma, p) \in G \ltimes U$ belongs to the twisted sector. If we replace Φ by $\sigma \cdot \Phi = (\sigma \cdot \Phi_0, \sigma \cdot \Phi_1 \cdot \sigma^{-1})$, (γ, p) changes to $(\sigma \cdot \gamma \cdot \sigma^{-1}, \sigma \cdot p)$. It is compatible with the local description of the twisted sector of the action groupoid.

Next, we rewrite the above argument using a holomorphic map

$$\Psi(\tau, t) = (\Phi_0(\tau, -t), \Phi_0(\tau, t))$$

from $[0, \infty) \times [0, 1]$ to $(G \times G) \ltimes ((U, -J) \times (U, J))$. Then it satisfies the boundary condition Δ_{id} along $t = 0$ and Δ_γ along $t = 1$. Apply the Schwarz reflection principle to Ψ and the anti-holomorphic involution $\tau_{\text{id}}(x, x') = (x', x)$ which is the reflection with respect to Δ_{id} , we obtain an extension $\Psi^+: [0, \infty) \times [-1, 1] \rightarrow U \times U$. Note that the anti-holomorphic involution $\tau_\gamma = (1, \gamma) \circ \tau_{\text{id}} \circ (1, \gamma^{-1}) = (\gamma^{-1}, \gamma) \circ \tau_{\text{id}}$, the fixed point set of which is Δ_γ . Since $\Psi^+(\tau, 1) = \tau_{\text{id}} \circ \Psi^+(\tau, -1)$, we find that

$$\Psi^+(\tau, 1) = (\gamma^{-1}, \gamma) \cdot \Psi^+(\tau, -1).$$

In this way, we get the element $(\gamma^{-1}, \gamma) \in G \times G$ from Ψ and τ_{id} . Then we conclude that the object (γ, p) in the twisted sector, which is given by the behavior of Φ under $\tau \rightarrow \infty$ corresponds to the triple $((p, p), \tau_{\text{id}}, (\gamma^{-1}, \gamma))$ in the dihedral twisted sector, which is given by the behavior of Ψ under $\tau \rightarrow \infty$. This leads us to the notion of the dihedral twisted sector.

If we consider $\Psi_{\rho_1, \rho_2} = (\rho_1, \rho_2) \circ \Psi$, the boundary conditions along $t = 0$ and $t = 1$ are $\Delta_{\rho_2 \cdot \rho_1^{-1}}$ and $\Delta_{\rho_2 \cdot \gamma \cdot \rho_1^{-1}}$, respectively. Set $\sigma = \rho_2 \cdot \rho_1^{-1}$ and $\zeta = \rho_2 \cdot \gamma \cdot \rho_1^{-1}$. Applying the Schwarz reflection

⁸In the case of Floer theory for cleanly intersecting Lagrangians, the formulation using a pair of anti-symplectic involutions is better suited.

⁹This is not a étale groupoid. Take $[0, \infty) \times (-1 - \delta, 1 + \delta)$ instead of $[0, \infty) \times [-1, 1]$ and an equivalence relation $(\tau, t) \sim (\tau, t+2)$ for $t \in (-1 - \delta, -1 + \delta)$. Then the corresponding groupoid is a proper étale Lie groupoid representing the cylinder. For the argument here, both groupoid works.

to Ψ_{ρ_1, ρ_2} with respect to τ_σ , we obtain an extension $\Psi_{\rho_1, \rho_2}^+ : [0, \infty) \times [-1, 1] \rightarrow U \times U$. The boundary conditions for Ψ_{ρ_1, ρ_2}^+ are $\tau_\sigma \Delta_\zeta$ and Δ_ζ along $t = -1$ and $t = 1$, respectively. Note that

$$\tau_\zeta = (1, \zeta \cdot \sigma^{-1}) \circ \tau_\sigma \circ (1, \sigma \cdot \zeta^{-1}) = (\zeta^{-1} \cdot \sigma, \zeta \cdot \sigma^{-1}) \circ \tau_\sigma,$$

i.e.,

$$\tau_{\rho_2 \cdot \gamma \cdot \rho_1^{-1}} = (\rho_1 \cdot \gamma^{-1} \cdot \rho_1^{-1}, \rho_2 \cdot \gamma \cdot \rho_2^{-1}) \circ \tau_{\rho_2 \cdot \rho_1^{-1}}.$$

Then, for a point $x \in \Delta_\zeta$, we have $x = (\zeta^{-1} \cdot \sigma, \zeta \cdot \sigma^{-1}) \circ \tau_\sigma(x)$. Hence, we find that

$$\Psi_{\rho_1, \rho_2}^+(\tau, 1) = (\zeta^{-1} \cdot \sigma, \zeta \cdot \sigma^{-1}) \Psi_{\rho_1, \rho_2}^+(\tau, -1) = (\rho_1 \cdot \gamma^{-1} \cdot \rho_1^{-1}, \rho_2 \cdot \gamma \cdot \rho_2^{-1}) \Psi_{\rho_1, \rho_2}^+(\tau, -1).$$

We assign an object $((\rho_1 p, \rho_2 p), \tau_{\rho_2 \cdot \rho_1^{-1}}, (\rho_1 \cdot \gamma^{-1} \cdot \rho_1^{-1}, \rho_2 \cdot \gamma \cdot \rho_2^{-1}))$. Note that

$$\tau_{\rho_2 \cdot \rho_1^{-1}} = (\rho_1 \cdot \rho_2^{-1}, \rho_2 \cdot \rho_1^{-1}) \circ \tau_{\text{id}} = (\rho_1, \rho_2) \circ \tau_{\text{id}} \circ (\rho_1^{-1}, \rho_2^{-1}).$$

Thus we find that the action of $(\rho_1, \rho_2) \in G \times G$ on the object space of the dihedral twisted sector sends $((p, p), \tau_{\text{id}}, (\gamma^{-1}, \gamma))$ to

$$((\rho_1 p, \rho_2 p), \tau_{\rho_2 \cdot \rho_1^{-1}}, (\rho_1 \cdot \gamma^{-1} \cdot \rho_1^{-1}, \rho_2 \cdot \gamma \cdot \rho_2^{-1})).$$

Therefore, the object in the dihedral twisted sector determined by Ψ with boundary conditions $\Delta_{\text{id}}, \Delta_\gamma$ and the one determined by $(\rho_1, \rho_2)\Psi$ with boundary conditions

$$\begin{aligned} (\rho_1, \rho_2)\Delta_{\text{id}} &= \Delta_{\rho_2 \cdot \rho_1^{-1}} = \text{Fix}(\tau_{\rho_2 \cdot \rho_1^{-1}}), \\ (\rho_1, \rho_2)\Delta_\gamma &= \Delta_{\rho_2 \cdot \gamma \cdot \rho_1^{-1}} = \text{Fix}((\rho_1 \cdot \gamma^{-1} \cdot \rho_1^{-1}, \rho_2 \cdot \gamma \cdot \rho_2^{-1}) \circ \tau_{\rho_2 \cdot \rho_1^{-1}}) \end{aligned}$$

are equivalent in the sense of Definition 3.1.

5 Filtered A_∞ -structure associated with a Lagrangian

In this section, we give a brief description on the filtered A_∞ -algebra associated with a Lagrangian $\mathcal{L} = (L_1 \rightrightarrows L_0)$ in a closed symplectic orbifold X . A spin structure on \mathcal{L} is a spin structure on $L_0 = \{(x, \tau) \in W_0 \times \mathcal{I} \mid s(\tau) = t(\tau) = x\}$, which is invariant under the action of W_1 . On the dihedral twisted sector $I_{\mathcal{X}}\mathcal{L}$, we define a local system Θ . Recall that an object of the dihedral twisted sector is $(x, \tau, g) \in W_0 \times \mathcal{I} \times W_1$ such that $s(\tau) = t(\tau) = x$, $s(g) = t(g) = x$ and $\tau g \tau = g^{-1}$. This condition is equivalent to that $x \in \widetilde{W}_0^\tau \cap \widetilde{W}_0^{g\tau}$ for $\tau, g\tau \in \mathcal{I} \subset \text{Inv}(\widetilde{\mathcal{W}}_1)$. When we present $\mathcal{W} = (W_1 \rightrightarrows W_0)$ as a proper étale action Lie groupoid, we find that a connected component of $(I_{\mathcal{X}}\mathcal{L})_0$ is $\{x \in W_0 \mid s(\tau) = t(\tau) = x, s(g) = t(g) = x\} = \text{Fix}(\tau) \cap \text{Fix}(g\tau)$, which is a clean intersection of Lagrangian submanifolds in W_0 . Then we have an $O(1)$ -local system Θ given in [7, Proposition 8.1.1]. We find that Θ is a $O(1)$ -local system on $I_{\mathcal{X}}\mathcal{L}$ in the sense Definition 3.3 (3). Then the space $\Omega^*(I_{\mathcal{X}}\mathcal{L}; \Theta)$ of differential forms with coefficients in Θ is defined on the dihedral twisted sector $I_{\mathcal{X}}\mathcal{L}$.

The filtered A_∞ -algebra is defined on $\Omega^*(I_{\mathcal{X}}\mathcal{L}; \Theta) \hat{\otimes}_{\mathbb{C}} \Lambda_0$ by the same way as a spin Lagrangian submanifold as in Section 2:

$$\mathfrak{m}_k = \sum \mathfrak{m}_{k, \beta} T^{f_{\beta, \omega}},$$

where $\mathfrak{m}_{0,0} = 0$, $\mathfrak{m}_{1,0} = d$ and

$$\mathfrak{m}_{k, \beta}(\xi_1, \dots, \xi_k) = (-1)^*(\text{ev}_0)_!(\text{ev}_1^* \xi_1 \wedge \dots \wedge \text{ev}_k^* \xi_k), \quad \text{unless } (k, \beta) = (0, 0), (1, 0).$$

The arguments on sign and orientation bundles on the moduli spaces in [17] are extended to our setting straightforwardly. We consider pseudo-holomorphic maps from the unit disk with interior orbifold points and boundary punctures to \mathcal{X} such that the boundary is mapped to \mathcal{L} and the boundary punctures are mapped to the dihedral twisted sector in the following way. Take a strip-like coordinate $[R, \infty) \times [0, 1)$ around the puncture. Then there is $(x, \tau, g) \in (I_{\mathcal{X}}\mathcal{L})_0$, the pseudo-holomorphic map is described by $w: [R, \infty) \times [0, 1) \rightarrow W_0$ such that $w([R, \infty) \times \{0\}) \subset \text{Fix}(\tau)$, $w([R, \infty) \times \{1\}) \subset \text{Fix}(g\tau)$ and $\lim_{s \rightarrow \infty} w(s, t) = x$.

We adopt the argument in [9, 10] in the setting of [2] to construct Kuranishi structures on the moduli space of bordered orbifold stable maps. The notion of relative spin structures is generalized to a Lagrangian in a symplectic orbifold. We will have the orbifold version of Theorem 2.1, i.e., the orbifold quantum cohomology of a closed symplectic orbifold X is isomorphic to Lagrangian Floer cohomology of the diagonal equipped with the product structure given by $\pm \mathfrak{m}_2$. The construction of the filtered A_∞ -bimodule associated with a relative spin pair of cleanly intersecting Lagrangians is also generalized in the orbifold setting. The details will appear elsewhere.

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