Continuity or even differentiability of a function on a closed interval of a non-Archimedean field are not sufficient for the function to assume all the intermediate values, a maximum, a minimum, or a unique primitive function on the interval. These problems are due to the total disconnectedness of the field in the order topology. In this paper, we show that differentiability (in the topological sense), together with some additional mild conditions, is indeed sufficient to guarantee that the function assumes all intermediate values and has a differentiable inverse function.

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1. Introduction. Let $K$ be a totally ordered non-Archimedean field extension of $\mathbb{R}$. We introduce the following terminology.

**Definition 1.1** $(\sim, \approx, \ll, H, \lambda)$. For $x, y \in K$, $x \sim y$ if there exist $n, m \in \mathbb{N}$ such that $n |x| > |y|$ and $m |y| > |x|$; for nonnegative $x, y \in K$, $x$ is infinitely smaller than $y$ and write $x \ll y$ if $nx < y$ for all $n \in \mathbb{N}$; and $x$ is infinitely small if $x \ll 1$ and $x$ is finite if $x \sim 1$. Finally, $x$ is approximately equal to $y$ and write $x \approx y$ if $x \sim y$ and $|x - y| \ll |x|$. We also set $\lambda(x) = [x]$, the class of $x$ under the equivalence relation $\sim$.

The set $H$ of equivalence classes under the relation $\sim$, which we call magnitudes, is naturally endowed with an addition via $[x] + [y] = [xy]$ and an order via $[x] < [y]$ if $|y| \ll |x|$ (or $|x| \gg |y|$), both of which are readily checked to be well defined. It follows that $(H, +, <)$ is a totally ordered group, often referred to as the Hahn group or skeleton group, whose neutral element is the class of 1. The projection $\lambda$ from $K$ to $H$ satisfies $\lambda(xy) = \lambda(x) + \lambda(y)$ and is a valuation.

The theorem of Hahn [5] provides a complete classification of any non-Archimedean extensions $K$ of $\mathbb{R}$ in terms of their skeleton group $H$. In fact, invoking the axiom of choice, it is shown that the elements of $K$ can be written as formal power series over the group $H$ with real coefficients, and the set of appearing “exponents” forms a well-ordered subset of $H$. The coefficient of the $q$th power in the Hahn representation of a given $x$ is denoted by $x[q]$, and the number $d$ is defined by $d[1] = 1$ and $d[q] = 0$ for $q \neq 1$. It is easy to check that $0 < d[q] \ll 1$ if and only if $q > 0$, and $d[q] \gg 1$ if and only if $q < 0$; moreover, $x \approx x[\lambda(x)]d^{\lambda(x)}$ for all $x \neq 0$.

From general properties of formal power series fields [9, 11], it follows that if $H$ is divisible then $K$ is real-closed. For a general overview of the algebraic properties of formal power series fields, we refer to the comprehensive overview by Ribenboim [12].
Throughout, $\mathcal{N}$ denotes any totally ordered non-Archimedean field extension of $\mathbb{R}$ that is complete in the order topology and whose skeleton group is Archimedean, that is, a subgroup of $\mathbb{R}$. The smallest such field is the field of the formal Laurent series whose skeleton group is $\mathbb{Z}$; and the smallest such field that is also real-closed is the field $\mathbb{R}$, first introduced by Levi-Civita [7, 8]. In this case $H = \mathbb{Q}$; and for any element $x \in \mathbb{R}$, the set of exponents in the Hahn representation of $x$ is a left-finite subset of $\mathbb{Q}$, that is, below any rational bound $r$ there are only finitely many exponents. For a detailed study of the Levi-Civita field $\mathbb{R}$, we refer the reader to [1, 2, 3, 13, 14, 15].

In this paper, we derive conditions under which a differentiable function assumes all intermediate values on a closed interval and has a differentiable inverse function. Previous versions of the intermediate value theorem were proved for the case of finite domain and range, and they were based on stronger smoothness criteria, namely equidifferentiability [3] and double derivative differentiability [1]. For the important class of locally analytic functions studied in detail in [13], we prove an intermediate value theorem (as well as a maximum theorem and a mean value theorem) without any requirements on the magnitude of the first derivative or the restriction of scaling into finite domains.

2. Review of continuity and differentiability. Like in any other metric space, continuity and differentiability at a point or on a domain of $\mathcal{N}$ are preserved under addition, multiplication, and composition of functions. We also have the following useful result.

**Proposition 2.1.** Let $D \subset \mathcal{N}$ be open, and let $f : D \to \mathcal{N}$ be differentiable on $D$ and have a local extremum (maximum or minimum) at $x_0 \in D$. Then $f''(x_0) = 0$.

**Proof.** Suppose not, then $|f''(x_0)| > 0$. Since $D$ is open and since $f$ is differentiable at $x_0$, there exists $\delta > 0$ in $\mathcal{N}$ such that $(x_0 - \delta, x_0 + \delta) \subset D$ and $|(f(x) - f(x_0))'/(x - x_0) - f''(x_0)| < |f''(x_0)|$ for all $x \neq x_0$ in $(x_0 - \delta, x_0 + \delta)$; which entails that $(f(x) - f(x_0))'/(x - x_0)$ has the same sign for all $x \neq x_0$ in $(x_0 - \delta, x_0 + \delta)$; and this contradicts the fact that $f$ has a local extremum at $x_0$. \hfill $\square$

However, contrary to the real case, the following examples show that continuity or differentiability of a function on a closed interval of $\mathcal{N}$ are not always sufficient for the function to assume all intermediate values, extrema, or even be bounded.

**Example 2.2.** Let $f : [0, 1] \to \mathcal{N}$ be given by

$$f(x) = \begin{cases} d^{-1} & \text{if } 0 \leq x < d, \\ d^{-1/\lambda(x)} & \text{if } d \leq x \ll 1, \\ 1 & \text{if } x \sim 1. \end{cases} \quad (2.1)$$

Then $f$ is continuous on $[0, 1]$; but for $d \leq x \ll 1$, $f(x)$ grows without bound.
Example 2.3. Let $f : [0, 1] \to \mathbb{R}$ be given by

$$f(x) = \begin{cases} 1 & \text{if } x \sim 1, \\ 0 & \text{if } 0 \leq x \ll 1. \end{cases} \quad (2.2)$$

Then $f$ is differentiable on $[0, 1]$, with derivative $f'(x) = 0$ for all $x$. However, $f$ does not assume the intermediate value $d$ on $[0, 1]$. Moreover, although $f'(x)$ is identically null, $f$ is not constant on $[0, 1]$.

Example 2.4. Let $f : [-1, 1] \to \mathbb{R}$ be given by $f(x) = x - x[0]$. Then $f$ is continuous on $[-1, 1]$. However, $f$ assumes neither a maximum nor a minimum on $[-1, 1]$. The set $f([-1, 1])$ is bounded above by any positive real number and below by any negative real number; but it has neither a least upper bound nor a greatest lower bound.

In the following section, we study a large class of differentiable functions and show that they assume all intermediate values on a closed interval and a differentiable inverse function.

3. Intermediate value theorem and inverse function theorem. First, we state the following result which will be used in the proof of Theorem 3.17, and we refer the reader to [3] for its proof.

**Theorem 3.1** (fixed point theorem). Let $q_{M} \in \mathbb{R}$ be given. Define $M \subset \mathbb{R}$ to be the set of all elements $x$ of $\mathbb{R}$ such that $\lambda(x) \geq q_{M}$. Let $f : M \to \mathbb{R}$ satisfy $f(M) \subset M$. Suppose that there exists $k > 0$ in $\mathbb{R}$ such that for all $x_1, x_2 \in M$, $\lambda(f(x_2) - f(x_1)) \geq k + \lambda(x_2 - x_1)$. Then there exists a unique solution $x \in M$ of the fixed point equation $x = f(x)$.

**Definition 3.2.** Let $a < b$ be given in $\mathbb{R}$, and let $f : [a, b] \to \mathbb{R}$ be differentiable. Then $f$ is an IVT-function on $[a, b]$ if there exists $n \in \mathbb{N}$ such that

$$\frac{f(y) - f(x)}{y - x} \sim \frac{f(b) - f(a)}{b - a}, \quad (3.1)$$

$$\left| \frac{f(y) - f(x) - f'(x)(y - x)}{(y - x)^2} \right| \leq n \cdot \left| \frac{f(b) - f(a) - f'(a)(b - a)}{(b - a)^2} \right| \quad (3.2)$$

for all $y \neq x$ in $[a, b]$.

The acronym IVT in Definition 3.2 stands for intermediate value theorem. As we will see in Theorem 3.17, an IVT-function on a closed interval $[a, b]$ assumes every intermediate value between $f(a)$ and $f(b)$; hence the name.

It follows immediately from Definition 3.2 that

$$f'(x) \sim \frac{f(b) - f(a)}{b - a} \quad \forall x \in [a, b]. \quad (3.3)$$

**Remark 3.3.** It is easy to check that the property introduced in Definition 3.2 is preserved under scaling and translation. That is, if $f : [a, b] \to \mathbb{R}$ is an IVT-function on $[a, b]$, then for all $c_1 \neq 0, c_2, c_3, c_4$ in $\mathbb{R}$, the function

$$g : \left[ \frac{a - c_2}{c_1}, \frac{b - c_2}{c_1} \right] \to \mathbb{R}, \quad (3.4)$$

...
given by \( g(x) = c_3 f(c_1 x + c_2) + c_4 \), is an IVT-function on \([a-c_2/c_1, (b-c_2)/c_1]\). In fact, replacing \( f \) by \( g \), \( a \) by \((a-c_2)/c_1\), and \( b \) by \((b-c_2)/c_1\) yields the same factor \( c_1 c_3 \) on both sides of (3.1), and the same factor \( c_1^2 c_3 \) on both sides of (3.2).

We show in Theorem 3.17 that if \( f \) is an IVT-function on \([a, b]\) then \( f \) assumes every intermediate value between \( f(a) \) and \( f(b) \) and has a differentiable inverse function. The two conditions in Definition 3.2 may seem strange, but the first condition means that the function is either constant or one-to-one with slope of uniform magnitude; when restricted to \( \mathbb{R} \), the uniformity of the magnitude is automatic. Also, when restricted to \( \mathbb{R} \), the second condition means merely that the difference quotient is bounded. Moreover, the following two examples show that one of the two conditions alone will not be sufficient.

**Example 3.4.** Let \( f : [0, 1] \to \mathbb{R} \) be given by

\[
f(x) = \begin{cases} 
3x[0] + (x-x[0]) + (x-x[0])^2 & \text{if } x[0] \text{ is rational,} \\
2x[0] + (x-x[0]) + (x-x[0])^2 & \text{if } x[0] \text{ is irrational.}
\end{cases}
\]

Then \( f \) is differentiable on \([0, 1]\) with derivative \( f'(x) = 1 \) for all \( x \). Clearly, \( f \) does not assume the value \( 3\pi/4 \) which lies between \( f(0) = 0 \) and \( f(1) = 3 \). Here, (3.1) is satisfied since

\[
\frac{|f(y) - f(x) - f'(x)(y-x)|}{|y-x|^2} \sim \frac{|f(1) - f(0) - f'(0)(1-0)|}{|1-0|^2} = 3 \quad \forall y \neq x \text{ in } [0, 1];
\]

but (3.2) does not hold. In this example, we even have that

\[
\frac{|f(y) - f(x) - f'(x)(y-x)|}{|y-x|^2} \sim \frac{|f(1) - f(0) - f'(0)(1-0)|}{|1-0|^2} = 3 \quad \forall y \neq x \text{ in } [0, 1].
\]

**Example 3.5.** Let \( f : [0, 1] \to \mathbb{R} \) be given by

\[
f(x) = \begin{cases} 
0 & \text{if } 0 \leq x \ll 1, \\
x & \text{if } x \sim 1.
\end{cases}
\]

Then \( f \) is differentiable on \([0, 1]\) with derivative \( f'(x) = 0 \) if \( 0 \leq x \ll 1 \) and \( f'(x) = 1 \) if \( x \sim 1 \). Clearly, \( f \) does not assume the value \( d \) which lies between \( f(0) = 0 \) and \( f(1) = 1 \). Here (3.2) is satisfied since

\[
\frac{|f(y) - f(x) - f'(x)(y-x)|}{|y-x|^2} < 3|f(1) - f(0) - f'(0)| = 3 \quad \forall y \neq x \text{ in } [0, 1];
\]
but (3.1) does not hold since
\[
\frac{f(y) - f(x)}{y - x} = 0 \neq 1 = f(1) - f(0) \quad \text{for infinitely small } x, y \in [0, 1].
\] (3.10)

**Remark 3.6.** Examples of IVT-functions on \([0, 1]\) are polynomials and power series with real coefficients and with finite first derivative throughout the interval, functions that are equidifferentiable on \([0, 1]\) as in [3], and functions that are twice differentiable on \([0, 1]\) in the derivative sense of [1] with finite first and second derivatives. Thus, the intermediate value theorem we prove below is a generalization of the previous two versions in [1, 3]; moreover, it will apply for functions on an interval of any size and not just intervals of finite length.

**Lemma 3.7.** Let \(a < b\) be given in \(\mathbb{N}\), and let \(f : [a, b] \to \mathbb{N}\) be an IVT-function. Then there exists \(m \in \mathbb{N}\) such that
\[
\left| \frac{f(y) - f(x)}{y - x} - f'(x) \right| \leq m \frac{|f(b) - f(a)|}{|b - x|} |y - x| \quad \forall y \neq x \text{ in } [a, b].
\] (3.11)

**Proof.** Let \(n \in \mathbb{N}\) be as in (3.2). Using (3.3), we have that
\[
f'(a) \sim \frac{f(b) - f(a)}{b - a};
\] and hence there exists \(k \in \mathbb{N}\) such that
\[
|f'(a)| \leq k \cdot |f(b) - f(a)|/(b - a).
\] Thus,
\[
\left| \frac{f(b) - f(a) - f'(a)(b - a)}{b - a} \right| \leq \frac{|f(b) - f(a)|}{b - a} + |f'(a)|
\]
\[
\leq (1 + k) \frac{|f(b) - f(a)|}{b - a}.
\] (3.12)

Hence
\[
\left| \frac{f(y) - f(x)}{y - x} - f'(x) \right| \leq n \frac{|f(b) - f(a) - f'(a)(b - a)|}{(b - a)^2} |y - x|
\]
\[
\leq n(1 + k) \frac{|f(b) - f(a)|}{(b - a)^2} |y - x|
\] (3.13)
for all \(y \neq x\) in \([a, b]\).

**Corollary 3.8** (remainder formula). Let \(a < b\) be given in \(\mathbb{N}\), and let \(f : [a, b] \to \mathbb{N}\) be an IVT-function. Then, for all \(x, y \in [a, b]\),
\[
f(y) = f(x) + f'(x)(y - x) + r(x, y)(y - x)^2,
\] (3.14)

with
\[
\lambda(r(x, y)) \geq \lambda \left( \frac{f(b) - f(a)}{(b - a)^2} \right).
\] (3.15)
**Proof.** For \( x, y \in [a, b] \), let

\[
r(x, y) = \begin{cases} 
  \frac{f(y) - f(x) - f'(x)(y - x)}{(y - x)^2} & \text{if } y \neq x, \\
  0 & \text{if } y = x.
\end{cases}
\] (3.16)

Then \( f(y) = f(x) + f'(x)(y - x) + r(x, y)(y - x)^2 \) for all \( x, y \in [a, b] \). Moreover, using **Lemma 3.7**, we obtain that \( \lambda(r(x, y)) \geq \lambda((f(b) - f(a))/(b - a)^2) \), as claimed. \( \square \)

**Remark 3.9.** The remainder formula here resembles that obtained in [1] as a result of the derivative differentiability, but we have the extra condition that \( \lambda(r(x, y)) \geq \lambda((f(b) - f(a))/(b - a)^2) \) which is useful for proving **Theorem 3.17**. 

**Lemma 3.10.** Let \( a < b \) be given in \( \mathcal{N} \), and let \( f : [a, b] \to \mathcal{N} \) be an IVT-function. Then \( f \) is continuously differentiable on \([a, b]\).

**Proof.** Let \( m \in \mathbb{N} \) be as in **Lemma 3.7**, and let \( x \neq y \) in \([a, b]\) be given. Then

\[
|f'(y) - f'(x)| \leq \left| \frac{f(y) - f(x)}{y - x} - f'(y) \right| + \left| \frac{f(y) - f(x)}{y - x} - f'(x) \right| 
\leq 2m \frac{|f(b) - f(a)|}{(b - a)^2} |y - x|. 
\] (3.17)

Hence \( f' \) is continuous on \([a, b]\). \( \square \)

**Corollary 3.11.** Let \( a < b \) be given in \( \mathcal{N} \), and let \( f : [a, b] \to \mathcal{N} \) be an IVT-function. Then, for all \( x, y \in [a, b] \),

\[
\lambda(f'(y) - f'(x)) \geq \lambda\left( \frac{f(b) - f(a)}{b - a} \right) + \lambda\left( \frac{y - x}{b - a} \right).
\] (3.18)

**Lemma 3.12.** Let \( a < b \) be given in \( \mathcal{N} \), and let \( f : [a, b] \to \mathcal{N} \) be an IVT-function. If \( f(a) = f(b) \), then \( f \) is constant on \([a, b]\).

**Proof.** Let \( x \in (a, b] \) be given. Then \( (f(x) - f(a))/(x - a) \sim (f(b) - f(a))/(b - a) = 0 \), which entails that \( f(x) = f(a) \). \( \square \)

**Lemma 3.13.** Let \( a < b \) be given in \( \mathcal{N} \), let \( f : [a, b] \to \mathcal{N} \) be a nonconstant IVT-function, and let \( g : [0, 1] \to \mathcal{N} \) be given by

\[
g(x) = \frac{f((b - a)x + a) - f(a)}{f(b) - f(a)}.
\] (3.19)

Then \( g \) is an IVT-function on \([0, 1]\), with \( \lambda(g(x)) = \lambda(x) \geq 0 \) and \( \lambda(g'(x)) = 0 \) for all \( x \in [0, 1] \).
Moreover, we have that 

\[ \lambda(g(x)) = \lambda\left(\frac{f((b-a)x+a)-f(a)}{(b-a)x} \right) \]

\[ = \lambda\left(\frac{f((b-a)x+a)-f(a)}{(b-a)x+a-a}\right) + \lambda\left(\frac{b-a}{f(b)-f(a)}\right) + \lambda(x) \quad (3.20) \]

Moreover, \( g'(x) = (b-a)/(f(b) - f(a)) \cdot f'((b-a)x+a) \sim 1 \), using (3.3).

\[ \square \]

The following result follows immediately from Lemma 3.13 and Corollary 3.11.

**Corollary 3.14.** Let \( a < b \) be given in \( N \), let \( f : [a,b] \rightarrow N \) be a nonconstant IVT-function, and let \( g : [0,1] \rightarrow N \) be as in Lemma 3.13. Then, for all \( x, y \in [0,1] \), \( \lambda(g'(y) - g'(x)) \geq \lambda(y-x) \).

**Lemma 3.15.** Let \( a < b \) be given in \( N \), let \( f : [a,b] \rightarrow N \) be a nonconstant IVT-function, and let \( g : [0,1] \rightarrow N \) be as in Lemma 3.13. Let \( g_R : [0,1] \cap \mathbb{R} \rightarrow \mathbb{R} \) be given by \( g_R(X) = g(X)[0] \). Then \( g_R \) is continuously differentiable on \( [0,1] \cap \mathbb{R} \) (in the real sense), with derivative \( (g_R)'(X) = g'(X)[0] \neq 0 \) for all \( X \in [0,1] \cap \mathbb{R} \).

**Proof.** Since \( g \) is an IVT-function on \([0,1] \) by Lemma 3.13, there exists \( m \in \mathbb{N} \) by Lemma 3.7 such that

\[ \left| \frac{g(y)-g(x)}{y-x} - g'(x) \right| \leq m|y-x| \quad \forall y \neq x \text{ in } [0,1]. \quad (3.21) \]

Now, let \( X \in [0,1] \cap \mathbb{R} \) be given. Then

\[ \left| \frac{g(Y)-g(X)}{Y-X} - g'(X) \right| \leq m|Y-X| \quad \forall Y \neq X \text{ in } [0,1] \cap \mathbb{R}. \quad (3.22) \]

Thus, for all \( Y \neq X \) in \([0,1] \cap \mathbb{R} \), we have that

\[ \left| \frac{g_R(Y)-g_R(X)}{Y-X} - g'(X)[0] \right| = \left| \frac{g(Y)-g(X)}{Y-X} - g'(X) \right|[0] \leq 2m|Y-X|, \quad (3.23) \]

which entails that \( g_R \) is differentiable (in the real sense) at \( X \) with derivative \( (g_R)'(X) = g'(X)[0] \neq 0 \), since \( \lambda(g'(X)) = 0 \) by Lemma 3.13.

Next, we show that \((g_R)'(X)\) is continuous on \([0,1] \cap \mathbb{R} \). As in the proof of Lemma 3.10, we have that \( |g'(y) - g'(x)| \leq 2m|y-x| \) for all \( x, y \in [0,1] \). In particular, \( |g'(Y) - g'(X)| \leq 2m|Y-X| \) for all \( X, Y \in [0,1] \cap \mathbb{R} \). It follows that

\[ |(g_R)'(Y) - (g_R)'(X)| = |g'(Y)[0] - g'(X)[0]| \leq 3m|Y-X| \quad (3.24) \]

for all \( X, Y \in [0,1] \cap \mathbb{R} \), which entails that \((g_R)'(\cdot)\) is (uniformly) continuous on \([0,1] \cap \mathbb{R} \). Thus, \( g_R \) is continuously differentiable on \([0,1] \cap \mathbb{R} \). \[ \square \]
**Lemma 3.16.** Let \( a < b \) be given in \( \mathcal{N} \), and let \( f : [a, b] \to \mathcal{N} \) be a nonconstant IVT-function. Then \( f \) is strictly monotone on \( [a, b] \).

**Proof.** Let \( g : [0, 1] \to \mathcal{N} \) be as in Lemma 3.13. We show that \( g \) is strictly increasing on \( [0, 1] \). Let \( g_R \) be as in Lemma 3.15. Then \( g_R \) is continuously differentiable on \( [0, 1] \cap \mathbb{R} \) and \( (g_R)'(X) \neq 0 \) for all \( X \in [0, 1] \cap \mathbb{R} \). Thus, \( g_R \) is strictly monotone on \( [0, 1] \cap \mathbb{R} \). Since \( g_R(0) = 0 < 1 = g_R(1) \), we obtain that \( g_R \) is strictly increasing on \( [0, 1] \cap \mathbb{R} \). Now let \( x, y \in [0, 1] \) be such that \( x < y \), and let \( X = x[0] \) and \( Y = y[0] \). As a first case, assume that \( X < Y \); then \( g_R(X) < g_R(Y) \). Hence

\[
g(y) - g(x) = (g_R(Y) - g_R(X)) + (g(y) - g(Y)) + (g(Y) - g_R(Y)) + (g_R(X) - g(X)) + (g(X) - g(x)),
\]

where the first term is positive and real. By Corollary 3.8, we have that \( g(y) - g(Y) = g'(Y)(y - Y) + r(Y, y)(y - Y)^2 \), where \( \lambda(g'(Y)) = 0, \lambda(y - Y) > 0 \), and \( \lambda(r(Y, y)) \geq 0 \). Hence \( |g(y) - g(Y)| \) is infinitely small. Similarly, \( |g(X) - g(x)| \) is infinitely small. Since \( \lambda(g(Y)) \geq 0 \) and \( g_R(Y) = g(0) \), we obtain that \( |g(Y) - g_R(Y)| \) is infinitely small. Similarly, \( |g_R(X) - g(x)| \) is infinitely small. So \( g(y) - g(x) \approx g_R(Y) - g_R(X) > 0 \); and hence \( g(x) < g(y) \).

As a second case, assume that \( X = Y \). Then \( y - x \ll 1 \), and hence

\[
g(y) - g(x) = g'(x)(y - x) + r(x, y)(y - x)^2 \approx g'(x)(y - x)
\]

since \( |r(x, y)| \) is at most finite and hence

\[
\lambda(r(x, y)(y - x)^2) = \lambda(r(x, y)) + 2\lambda(y - x) \geq 2\lambda(y - x) > \lambda(y - x)
= \lambda(g'(x)) + \lambda(y - x)
= \lambda(g'(x)(y - x)).
\]

By Corollary 3.14, we have that \( \lambda(g'(x) - g'(X)) \geq \lambda(x - X) > 0 \). Since \( g'(X) \sim 1 \), since \( g'(X) \sim 1 \) and since \( |g'(x) - g'(X)| \ll 1 \), we obtain that

\[
g'(x) \approx g'(X) \approx (g_R)'(X) > 0.
\]

From (3.26) and (3.28), we obtain that \( g(y) - g(x) > 0 \). Thus, \( g(x) < g(y) \) for all \( x < y \) in \([0, 1]\); and hence \( g \) is strictly increasing on \([0, 1]\). Since

\[
f(x) = (f(b) - f(a))g\left(\frac{x - a}{b - a}\right) + f(a) \quad \forall x \in [a, b]
\]

and since \( g \) is strictly increasing on \([0, 1]\), we obtain that \( f \) is strictly increasing on \([a, b]\) if \( f(a) < f(b) \), and \( f \) is strictly decreasing on \([a, b]\) if \( f(a) > f(b) \). \( \square \)

**Theorem 3.17** (intermediate value theorem). Let \( a < b \) be given in \( \mathcal{N} \), and let \( f : [a, b] \to \mathcal{N} \) be an IVT-function. Then \( f \) assumes every intermediate value between \( f(a) \) and \( f(b) \).

**Proof.** If \( f(a) = f(b) \), then \( f \) is constant on \([a, b]\) by Lemma 3.12, and there is nothing to prove. So we may assume that \( f(a) \neq f(b) \). Let \( g : [0, 1] \to \mathcal{N} \) be as in
Lemma 3.13. For all \( x \in [a, b] \), we have that
\[
f(x) = (f(b) - f(a)) \frac{x - a}{b - a} + f(a) = l_2 \circ g \circ l_1(x),
\]
where \( l_1 \) and \( l_2 \) are linear functions. Hence it suffices to show that \( g \) assumes every intermediate value between \( g(0) = 0 \) and \( g(1) = 1 \).

Let \( g_R \) be as in Lemma 3.15, let \( S \subseteq (0, 1) \) be given, and let \( S_R = S[0] \). Then \( S_R \subseteq [0, 1] \cap \mathbb{R} \). Since \( g_R \) is continuous on \([0, 1] \cap \mathbb{R} \) by Lemma 3.15, there exists \( X \in [0, 1] \cap \mathbb{R} \) such that \( g_R(X) = S_R \). If \( g(X) = S \) then the claim is proved; so we may assume that \( g(X) \neq S \). Thus, \(|S - g(X)| \leq |S - S_R| + |g_R(X) - g(X)| \) is infinitely small.

Now we proceed to find \( x \) such that \( 0 < |x| \ll 1, X + x \in [0, 1] \), and \( g(X + x) = S \). Since \( g \) is differentiable on \([0, 1] \), we have, using Corollary 3.8, that
\[
S = g(X + x) = g(X) + g'(X)x + r(X, X + x)x^2,
\]
where \(|r(X, X + x)| \) is at most finite.

Transforming (3.31) into a fixed point problem yields
\[
x = \frac{s}{g'(X)} - \frac{r(X, X + x)}{g'(X)} x^2 = h(x),
\]
where \( s = S - g(X) \), and \(|s| \) is infinitely small. Let \( M = \{ z \in \mathbb{N} : \lambda(z) \geq \lambda(s) \} \) and let \( x \in M \) be given. Since \(|r(X, X + x)| \) is at most finite and since \( g'(X) \sim 1 \), we have that
\[
\lambda \left( \frac{r(X, X + x)}{g'(X)} x^2 \right) \geq 2\lambda(x) > \lambda(x) \geq \lambda(s) = \lambda \left( \frac{s}{g'(X)} \right).
\]
Thus, \( h(x) \approx s/g'(X) \); and hence \( \lambda(h(x)) = \lambda(s) \) for all \( x \in M \). Hence \( h(M) \subseteq M \). Now let \( x_1 + x_2 \) be given in \( M \). Then
\[
|h(x_1) - h(x_2)| = \left| \frac{r(X, X + x_2)x_2^2 - r(X, X + x_1)x_1^2}{g'(X)} \right| = \left| \frac{g(X + x_2) - g(X + x_1)}{g'(X)} + x_1 - x_2 \right|.
\]
But \( g(X + x_2) = g(X + x_1) + g'(X + x_1)(x_2 - x_1) + r(X + x_1, X + x_2)(x_2 - x_1)^2 \), where \(|r(X + x_1, X + x_2)| \) is at most finite. Thus,
\[
|h(x_1) - h(x_2)|
= \left| \frac{g'(X + x_1)(x_2 - x_1) + r(X + x_1, X + x_2)(x_2 - x_1)^2}{g'(X)} + x_1 - x_2 \right|
= \left| \frac{g'(X + x_1) - g'(X)}{g'(X)}(x_2 - x_1) + \frac{r(X + x_1, X + x_2)}{g'(X)}(x_2 - x_1)^2 \right|
\leq |x_1 - x_2| \left( \left| \frac{g'(X + x_1) - g'(X)}{g'(X)} \right| + \left| \frac{r(X + x_1, X + x_2)}{g'(X)} \right| |x_1 - x_2| \right).
\]
Using Corollary 3.14 and the fact that $g'(X) \sim 1$, we have that

$$
\lambda\left(\left|\frac{g'(X + x_1) - g'(X)}{g'(X)}\right|\right) = \lambda(g'(X + x_1) - g'(X)) \geq \lambda(x_1) \geq \frac{\lambda(s)}{2}. \quad (3.36)
$$

Also

$$
\lambda\left(\left|\frac{r(X + x_1, X + x_2)}{g'(X)}\right|\right) \geq \lambda(x_1 - x_2) \geq \min\{\lambda(x_1), \lambda(x_2)\} > \frac{\lambda(s)}{2}. \quad (3.37)
$$

Hence $\lambda(h(x_1) - h(x_2)) > \lambda(s)/2 + \lambda(x_1 - x_2)$, where $\lambda(s) > 0$. So $h$ and $M$ satisfy the requirements of Theorem 3.1, and hence $h$ has a fixed point $x$ in $M$.

Finally, we show that $X + x \in (0, 1)$. First assume that $X = 0$; then $S > 0 = g(X)$ and hence $s = S - g(X) > 0$. Since $g'(0) \approx (g_R)'(0) > 0$, we obtain that $X + x = x \approx s/g'(0) > 0$. Moreover, $x \ll 1$; hence $X + x = x \in (0, 1)$. Now assume that $X = 1$, then $S < 1 = g(1)$ and hence $s < 0$. It follows that $x \approx s/g'(1) < 0$ and hence $X + x = 1 + x < 1$. Since $|x| \ll 1$, we obtain that $X + x = 1 + x \in (0, 1)$. Finally assume that $0 < X < 1$; then $X$ is finitely away from 0 and 1. Since $|x| \ll 1$, we obtain that $X + x \in (0, 1)$. \hfill \Box

Using Lemma 3.16 and Theorem 3.17, we readily obtain the following two results.

**Corollary 3.18.** Let $a < b$ be given in $\mathcal{N}$, and let $f: [a, b] \to \mathcal{N}$ be a nonconstant IVT-function. Let $m = \min\{f(a), f(b)\}$ and $M = \max\{f(a), f(b)\}$. Then $f([a, b]) = [m, M]$.

**Theorem 3.19** (closed mapping theorem). Let $a, b, f, m$, and $M$ be as in Corollary 3.18. Then for all $a_1 < b_1$ in $[a, b]$, there exist $m_1 < M_1$ in $[m, M]$ such that $f([a_1, b_1]) = [m_1, M_1]$. Conversely, for all $m_1 < M_1$ in $[m, M]$, there exist $a_1 < b_1$ in $[a, b]$ such that $f([a_1, b_1]) = [m_1, M_1]$.

We note here that even though the conditions in Definition 3.2 depend on the end points $a$ and $b$, the function $f$ assumes all intermediate values between $f(a)$ and $f(b)$ for any subinterval $[a_1, b_1]$ of $[a, b]$.

**Theorem 3.20** (inverse function theorem). Let $a < b$ be given in $\mathcal{N}$, and let $f: [a, b] \to \mathcal{N}$ be a nonconstant IVT-function. Let $m = \min\{f(a), f(b)\}$ and $M = \max\{f(a), f(b)\}$. Then the inverse function $f^{-1}: [m, M] \to [a, b]$ exists and is differentiable; moreover,

$$
(f^{-1})' = \frac{1}{(f \circ f^{-1})}. \quad (3.38)
$$

**Proof.** The proof that $f^{-1}$ exists follows from Lemma 3.16. To show that $f^{-1}$ is differentiable on $[m, M]$, let $y_0 \in [m, M]$ be given and let $x_0 = f^{-1}(y_0)$. Let $\epsilon > 0$ in $\mathcal{N}$ be given and let $\epsilon_1 \in (0, \epsilon)$ be such that $|f(x) - f(x_0)|/|x - x_0| - f'(x_0)| < \min\{|f'(x_0)|/2, 
\epsilon|f'(x_0)|^2/2\}$ for $x \in [a, b]$ satisfying $0 < |x - x_0| < \epsilon_1$. It follows that $|f(x) - f(x_0)| > |f'(x_0)||x - x_0|/2$ when $x \in [a, b]$ and $0 < |x - x_0| < \epsilon_1$. By Theorem 3.19,
Hence there exist $\delta_1, \delta_2 > 0$ such that $f([a, b] \cap [x_0 - \epsilon_1/2, x_0 + \epsilon_1/2]) = [y_0 - \delta_1, y_0 + \delta_2]$.

Let $\delta = \min\{\delta_1, \delta_2\}$. Then $f^{-1}((y_0 - \delta, y_0 + \delta)) \subset [a, b] \cap (x_0 - \epsilon_1, x_0 + \epsilon_1)$.

Now, let $y \in [m, M]$ be such that $0 < |y - y_0| < \delta$. Then

$$
\frac{|f^{-1}(y) - f^{-1}(y_0)|}{y - y_0} = \frac{1}{f'(x_0)} \Rightarrow \frac{1}{f'(x_0)} - \frac{1}{f'(x_0)} = \frac{x - x_0}{f(x) - f(x_0)} - \frac{x - x_0}{f(x) - f(x_0)}
$$

$$
= \frac{|x - x_0| \cdot |(f(x) - f(x_0))/(x - x_0) - f'(x_0)|}{|f'(x_0)| \cdot |f'(x) - f(x_0)|}
$$

$$
< \frac{|x - x_0| \cdot |f'(x_0)|^2/2}{|f'(x_0)| \cdot |f'(x) - f(x_0)|}
$$

$$
< \frac{|x - x_0| \cdot |f'(x_0)|^2/2}{|f'(x_0)| \cdot |f'(x_0)| \cdot |x - x_0|/2}
$$

$$
= \epsilon.
$$

Hence $f^{-1}$ is differentiable at $y_0$, and $(f^{-1})'(y_0) = 1/f'(x_0) = 1/f'(f^{-1}(y_0))$. \(\square\)

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Thinking about nonlinearity in engineering areas, up to the 70s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from “Qualitative Theory of Differential Equations,” allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the Mathematical Problems in Engineering aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

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