



Existence of entire radial solutions to a class of quasilinear elliptic equations and systems

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Abstract. In this paper, by a monotone iterative method and the Arzelà–Ascoli theorem, we obtain the existence of entire positive radial solutions to the following quasilinear elliptic equations

$$\operatorname{div}(\phi_1(|\nabla u|)\nabla u) + a_1(|x|)\phi_1(|\nabla u|)|\nabla u| = b_1(|x|)f(u), \quad x \in \mathbb{R}^N,$$

and systems

$$\begin{cases} \operatorname{div}(\phi_1(|\nabla u|)\nabla u) + a_1(|x|)\phi_1(|\nabla u|)|\nabla u| = b_1(|x|)f_1(u, v), & x \in \mathbb{R}^N, \\ \operatorname{div}(\phi_2(|\nabla v|)\nabla v) + a_2(|x|)\phi_2(|\nabla v|)|\nabla v| = b_2(|x|)f_2(u, v), & x \in \mathbb{R}^N, \end{cases}$$

under simple conditions on f , f_i , a_i and b_i ($i = 1, 2$).

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1 Introduction

The purpose of this paper is to investigate the existence of entire positive radial solutions to the following quasilinear elliptic equation


$$\operatorname{div}(\phi_1(|\nabla u|)\nabla u) + a_1(|x|)\phi_1(|\nabla u|)|\nabla u| = b_1(|x|)f(u), \quad x \in \mathbb{R}^N, \quad (1.1)$$

and system

$$\begin{cases} \operatorname{div}(\phi_1(|\nabla u|)\nabla u) + a_1(|x|)\phi_1(|\nabla u|)|\nabla u| = b_1(|x|)f_1(u, v), & x \in \mathbb{R}^N, \\ \operatorname{div}(\phi_2(|\nabla v|)\nabla v) + a_2(|x|)\phi_2(|\nabla v|)|\nabla v| = b_2(|x|)f_2(u, v), & x \in \mathbb{R}^N, \end{cases} \quad (1.2)$$

where a_i, b_i, f, f_i ($i = 1, 2$) satisfy

(S₁) $a_i, b_i : \mathbb{R}^N \rightarrow [0, \infty)$ are continuous;

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(S₂) $f : [0, \infty) \rightarrow [0, \infty)$ is continuous and increasing, $f_i : [0, \infty) \times [0, \infty) \rightarrow [0, \infty)$ are continuous and increasing (i.e., $f_i(s_2, t_2) \geq f_i(s_1, t_1)$, $\forall s_2 \geq s_1 \geq 0$ and $t_2 \geq t_1 \geq 0$),

and $\phi_i \in C^1((0, \infty), (0, \infty))$ satisfy:

(S₃) $(t\phi_i(t))' > 0$, $\forall t > 0$;

(S₄) there exist $p_i, q_i > 1$ such that

$$p_i \leq \frac{t\Psi_i'(t)}{\Psi_i(t)} \leq q_i, \quad \forall t > 0,$$

where $\Psi_i(t) = \int_0^t s\phi_i(s)ds$, $t > 0$;

(S₅) there exist $k_i, l_i > 0$ such that

$$k_i \leq \frac{t\Psi_i''(t)}{\Psi_i'(t)} \leq l_i, \quad \forall t > 0.$$

$\Delta_{\phi_1} u = \operatorname{div}(\phi_1(|\nabla u|)\nabla u)$ is called the ϕ_1 -Laplacian operator, which includes special cases appearing in mathematical models in nonlinear elasticity, plasticity, generalized Newtonian fluids, and in quantum physics, see e.g., Benci, Fortunato and Pisani [5], Cencelj, Repovš and Virk [6], Fuchs and Li [9], Fuchs and Osmolovski [10], Fukagai and Narukawa [11] and [12] and the references therein.

Some basic examples of ϕ_1 -Laplacian operators are

- (1) when $\phi_1(t) \equiv 2$, $\Psi_1(t) = t^2$, $t > 0$, $\Delta_{\phi_1} u = \Delta u$ is the Laplacian operator. In this case, $p_1 = q_1 = 2$ in (S₄), and $k_1 = l_1 = 1$ in (S₅);
- (2) when $\phi_1(t) = pt^{p-2}$, $\Psi_1(t) = t^p$, $t > 0$, $p > 1$, $\Delta_{\phi_1} u = \Delta_p u$ is the p -Laplacian operator. In this case, $p_1 = q_1 = p$ in (S₄), and $k_1 = l_1 = p - 1$ in (S₅);
- (3) when $\phi_1(t) = pt^{p-2} + qt^{q-2}$, $\Psi_1(t) = t^p + t^q$, $t > 0$, $1 < p < q$, $\Delta_{\phi_1} u = \Delta_p u + \Delta_q u$ is called as the $(p + q)$ -Laplacian operator, $p_1 = p$, $q_1 = q$ in (S₄), and $k_1 = p - 1$, $l_1 = q - 1$ in (S₅);
- (4) when $\phi_1(t) = 2p(1 + t^2)^{p-1}$, $\Psi_1(t) = (1 + t^2)^p - 1$, $t > 0$, $p > 1/2$, $p_1 = \min\{2, 2p\}$, $q_1 = \max\{2, 2p\}$ in (S₄), and $k_1 = \min\{1, 2p - 1\}$, $l_1 = \max\{1, 2p - 1\}$ in (S₅);
- (5) when $\phi_1(t) = \frac{p(\sqrt{1+t^2}-1)^{p-1}}{\sqrt{1+t^2}}$, $\Psi_1(t) = (\sqrt{1+t^2}-1)^p$, $t > 0$, $p > 1$, $p_1 = p$, $q_1 = 2p$ in (S₄), and $k_1 = p - 1$, $l_1 = 2p - 1$ in (S₅);
- (6) when $\phi_1(t) = pt^{p-2}(\ln(1+t))^q + \frac{qt^{p-1}(\ln(1+t))^{q-1}}{1+t}$, $\Psi_1(t) = t^p(\ln(1+t))^q$, $t > 0$, $p > 1$, $q > 0$, $p_1 = p$, $q_1 = p + q$ in (S₄), and $k_1 = p - 1$, $l_1 = p + q - 1$ in (S₅).

We say that $u \in C^1(\mathbb{R}^N)$ is a solution to equation (1.1) if for each $\psi \in C_0^\infty(\mathbb{R}^N)$, it holds

$$\int_{\mathbb{R}^N} \phi_1(|\nabla u|)\nabla u \nabla \psi dx - \int_{\mathbb{R}^N} a_1(x)(\phi_1(|\nabla u|)\nabla u)\psi dx = - \int_{\mathbb{R}^N} b_1(x)f(u)\psi dx.$$

Moreover, when $\lim_{|x| \rightarrow \infty} u(x) = +\infty$, we say that u is a large solution to equation (1.1).

For convenience, for $i = 1, 2$, we denote by

$$h_i^{-1} \quad \text{the inverses of } h_i(t) = t\phi_i(t), \quad t > 0; \tag{1.3}$$

$$I_{i,\rho,g}(\infty) := \lim_{r \rightarrow \infty} I_{i,\rho,g}(r), \quad I_{i,\rho,g}(r) := \int_0^r h_i^{-1}(\Lambda_{\rho,g}(t)) dt, \quad r \geq 0, \quad (1.4)$$

where $\rho, g \in C([0, \infty), [0, \infty))$ and

$$\Lambda_{\rho,g}(t) := \frac{1}{\Phi_g(t)} \int_0^t \Phi_g(s) \rho(s) ds, \quad t > 0; \quad (1.5)$$

$$\Phi_g(t) := t^{N-1} \exp\left(\int_0^t g(\tau) d\tau\right), \quad t > 0; \quad (1.6)$$

$$\theta_i(t) := \min\{t^{p_i}, t^{q_i}\}, \quad \Theta_i(t) := \max\{t^{p_i}, t^{q_i}\}, \quad t \geq 0; \quad (1.7)$$

$$\theta_i^{-1}(t) := \min\{t^{1/p_i}, t^{1/q_i}\}, \quad \Theta_i^{-1}(t) := \max\{t^{1/p_i}, t^{1/q_i}\}, \quad t \geq 0; \quad (1.8)$$

and, for an arbitrary $\alpha > 0$ and $t \geq \alpha$,

$$Y_{1,\alpha}(\infty) := \lim_{t \rightarrow \infty} Y_{1,\alpha}(t), \quad Y_{1,\alpha}(t) := \int_\alpha^t \frac{d\tau}{\Theta_1^{-1}(f(\tau))}; \quad (1.9)$$

$$Y_{2,\alpha}(\infty) := \lim_{t \rightarrow \infty} Y_{2,\alpha}(t), \quad Y_{2,\alpha}(t) := \int_\alpha^t \frac{d\tau}{\Theta_1^{-1}(f_1(\tau, \tau)) + \Theta_2^{-1}(f_2(\tau, \tau))}. \quad (1.10)$$

We see that for $t > \alpha$

$$Y'_{1,\alpha}(t) = \frac{1}{\Theta_1^{-1}(f(t))} > 0,$$

$$Y'_{2,\alpha}(t) = \frac{1}{\Theta_1^{-1}(f_1(t, t)) + \Theta_2^{-1}(f_2(t, t))} > 0,$$

and $Y_{1,\alpha}, Y_{2,\alpha}$ have the inverse functions $Y_{1,\alpha}^{-1}$ and $Y_{2,\alpha}^{-1}$ on $[0, Y_{1,\alpha}(\infty))$ and $[0, Y_{2,\alpha}(\infty))$, respectively.

First, let us review the following model

$$\Delta u = b_1(|x|)f(u), \quad x \in \mathbb{R}^N. \quad (1.11)$$

For $b_1(x) \equiv 1$ on \mathbb{R}^N : when f satisfies (S_2) , Keller [14] and Osserman [19] first supplied a necessary and sufficient condition

$$\int_1^\infty \frac{dt}{\sqrt{2F(t)}} = \infty, \quad F(t) = \int_0^t f(s) ds, \quad (1.12)$$

for the existence of entire positive radial large solutions to equation (1.11).

For $N \geq 3$, $f(u) = u^\gamma$, $\gamma \in (0, 1]$, and b_1 satisfies (S_1) with $b_1(x) = b_1(|x|)$, Lair and Wood [16] first showed that equation (1.11) has infinitely many entire positive radial large solutions if and only if

$$\int_0^\infty r b_1(r) dr = \infty. \quad (1.13)$$

The above results have been extended by many authors and in many contexts, see, for instance, [1–3, 8, 21–23] and the references therein.

Next let us review the system

$$\begin{cases} \Delta u = b_1(|x|)v^{\gamma_1}, & x \in \mathbb{R}^N, \\ \Delta v = b_2(|x|)u^{\gamma_2}, & x \in \mathbb{R}^N. \end{cases} \quad (1.14)$$

When $N \geq 3$ and $0 < \gamma_1 \leq \gamma_2$, Lair and Wood [17] have considered the existence and nonexistence of entire positive radial solutions to system (1.14).

For the further results, see, for instance, [4, 7, 13, 15, 18, 24] and the references therein.

Now let us return to equation (1.1). Recently, C. A. Santos, J. Zhou, J. A. Santos [20] considered the existence of entire positive radial and nonradial large solutions to equation

$$\operatorname{div}(\phi_1(|\nabla u|)\nabla u) = b_1(x)f(u), \quad x \in \mathbb{R}^N.$$

A basic result in [20] is the following.

Lemma 1.1 ([20, Corollary 1.2]). *Let (S₃)–(S₅) hold, f satisfy (S₂), and b_1 satisfy (S₁) with $b_1(x) = b_1(|x|)$, $x \in \mathbb{R}^N$. If*

$$I_{1,b_1,0}(\infty) = \infty,$$

then equation (1.1) admits a sequence of symmetric radial large solutions $u_m(|x|) \in C^1(\mathbb{R}^N)$ with $u_m(0) \rightarrow \infty$ as $m \rightarrow \infty$ if and only if f satisfies

$$\int_1^\infty \frac{dt}{\Psi_1^{-1}(F(t))} = \infty,$$

where Ψ_1^{-1} is the inverse of Ψ_1 which is given as in (S₄), and F is given as in (1.12).

Recently, when $a_i \equiv 0$ in \mathbb{R}^N , $f_1(u, v) = f(v)$, $f_2(u, v) = g(u)$, and g satisfies (S₂), Zhang [25] showed existence of entire positive radial solutions to (1.1) and system (1.2).

In this paper, we extend the results of [25] and show existence of entire positive radial solutions to (1.1) and (1.2) for more general a_i and f_i .

Our main results for equation (1.1) are as follows.

Theorem 1.2. *Let the hypotheses (S₁)–(S₅) hold. If*

$$(S_6) \quad Y_{1,\alpha}(\infty) = \infty,$$

then equation (1.1) has one entire positive radial solution $u \in C^1(\mathbb{R}^N)$. Moreover, when $I_{1,a_1,b_1}(\infty) < \infty$, u is bounded, and $\lim_{r \rightarrow \infty} u(r) = \infty$ provided $I_{1,a_1,b_1}(\infty) = \infty$, where I_{1,a_1,b_1} is given as in (1.4).

Theorem 1.3. *Under the hypotheses (S₁)–(S₅) and*

$$(S_7) \quad I_{1,a_1,b_1}(\infty) < Y_{1,\alpha}(\infty) < \infty,$$

equation (1.1) has one entire positive radial bounded solution $u \in C^1(\mathbb{R}^N)$ satisfying

$$\alpha + \theta_1^{-1}(f(\alpha))I_{1,a_1,b_1}(r) \leq u(r) \leq Y_{1,\alpha}^{-1}(I_{1,a_1,b_1}(r)), \quad \forall r \geq 0,$$

where θ_1^{-1} is given as in (1.8).

Remark 1.4. When $\int_0^1 \frac{d\tau}{\Theta_1^{-1}(f(\tau))} = \infty$, one can see that there is $\alpha > 0$ sufficiently small such that (S₇) holds provided $I_{1,a_1,b_1}(\infty) < \infty$ and $Y_{1,\alpha}(\infty) < \infty$.

Remark 1.5. For $f(s) = s^{\gamma_1}$, $s \geq 0$, $\gamma_1 > 0$, since $\Theta_1^{-1}(t) = t^{1/p_1}$, $t \geq 1$, one can see that when $\gamma_1 > p_1$, $Y_{1,\alpha}(\infty) < \infty$, and $Y_{1,\alpha}(\infty) = \infty$ provided $\gamma_1 \leq p_1$, where p_1 is given as in (S₄).

Remark 1.6. For $f(s) = (1+s)^{\gamma_1}(\ln(1+s))^{\mu_1}$, $s \geq 0$, $\mu_1, \gamma_1 > 0$, one can see that when $\gamma_1 > p_1$ or $\gamma_1 = p_1$ and $\mu_1 > p_1$, $Y_{1,\alpha}(\infty) < \infty$, and $Y_{1,\alpha}(\infty) = \infty$ provided $\gamma_1 < p_1$ or $\gamma_1 = p_1$ and $\mu_1 \leq p_1$.

Remark 1.7. For $f(s) = \exp(c_1 s)$, $s \geq 0$, $c_1 > 0$, one can see that $Y_{1,\alpha}(\infty) < \infty$.

Our main results for system (1.2) are as follows.

Theorem 1.8. *Let the hypotheses (S₁)–(S₅) hold. If*

$$(S_8) \quad Y_{2,\alpha}(\infty) = \infty,$$

then system (1.2) has one entire positive radial solution (u, v) in $C^1(\mathbb{R}^N) \times C^1(\mathbb{R}^N)$. Moreover, when $I_{1,a_1,b_1}(\infty) + I_{2,a_2,b_2}(\infty) < \infty$, u and v are bounded; when $I_{1,a_1,b_1}(\infty) = I_{2,a_2,b_2}(\infty) = \infty$, $\lim_{r \rightarrow \infty} u(r) = \lim_{r \rightarrow \infty} v(r) = \infty$.

Theorem 1.9. *Under the hypotheses (S₁)–(S₅) and*

$$(S_9) \quad I_{1,a_1,b_1}(\infty) + I_{2,a_2,b_2}(\infty) < Y_{2,\alpha}(\infty) < \infty,$$

system (1.2) has one entire positive radial bounded solution (u, v) in $C^1(\mathbb{R}^N) \times C^1(\mathbb{R}^N)$ satisfying

$$\alpha/2 + \theta_1^{-1}(f_1(\alpha/2, \alpha/2))I_{1,a_1,b_1}(r) \leq u(r) \leq Y_{2,\alpha}^{-1}(I_{1,a_1,b_1}(r) + I_{2,a_2,b_2}(r)), \quad \forall r \geq 0;$$

$$\alpha/2 + \theta_2^{-1}(f_2(\alpha/2, \alpha/2))I_{2,a_2,b_2}(r) \leq v(r) \leq Y_{2,\alpha}^{-1}(I_{1,a_1,b_1}(r) + I_{2,a_2,b_2}(r)), \quad \forall r \geq 0.$$

Remark 1.10. For $f_1(s, s) = s^{\gamma_1}$, $f_2(s, s) = s^{\gamma_2}$, $s \geq 0$, $\gamma_1, \gamma_2 > 0$, when $\gamma_1 > p_1$ or $\gamma_2 > p_2$, $Y_{2,\alpha}(\infty) < \infty$, and $Y_{2,\alpha}(\infty) = \infty$ provided $\gamma_1 \leq p_1$ and $\gamma_2 \leq p_2$, where p_1 and p_2 are given as in (S₄).

Remark 1.11. For $f_1(s, s) = (1 + s)^{\gamma_1}(\ln(1 + s))^{\mu_1}$, $f_2(s, s) = (1 + s)^{\gamma_2}(\ln(1 + s))^{\mu_2}$, $s \geq 0$, $\gamma_i, \mu_i > 0$ ($i = 1, 2$), when $\gamma_1 > p_1$ or $\gamma_2 > p_2$; or $\gamma_1 = p_1$ and $\mu_1 > p_1$; or $\gamma_2 = p_2$ and $\mu_2 > p_2$, $Y_{2,\alpha}(\infty) < \infty$, and $Y_{2,\alpha}(\infty) = \infty$ provided $\gamma_1 < p_1$ and $\gamma_2 < p_2$; or $\gamma_1 = p_1$, $\mu_1 \leq p_1$ and $\gamma_2 = p_2$, $\mu_2 \leq p_2$.

Remark 1.12. For $f_1(s, s) = \exp(c_1 s)$ or $f_2(s, s) = \exp(c_2 s)$, $s \geq 0$, $c_1, c_2 > 0$, one can see that $Y_{2,\alpha}(\infty) < \infty$.

Remark 1.13. We note that the paper [26] by X. Zhang et al. studied the nonexistence and existence of positive radial large solutions to system (1.2). But, since their basic assumption is that $\phi_i \in C^1((0, \infty), [0, \infty))$ ($i = 1, 2$) are nondecreasing and for any $c \in (0, 1)$, there exist constants $\sigma_i \in (0, 1)$ such that

$$\phi_i(cs) \leq c^{\sigma_i} \phi_i(s), \quad \forall s > 0, \quad (1.15)$$

it is $c^{\sigma_i} < 1$, hence (1.15) can not be set up when $\phi_i \equiv 1$ on $(0, \infty)$ (in this case, $\Delta_{\phi_1} u = \Delta u$ is the Laplacian operator).

2 Proof of Theorems 1.2 and 1.3

In this section we prove Theorems 1.2 and 1.3.

Lemma 2.1 ([20, Lemma 2.2]). *Let (S₃)–(S₅) hold, θ_i, Θ_i and $\theta_i^{-1}, \Theta_i^{-1}$ ($i = 1, 2$) be given as in (1.7) and (1.8). We have*

(i) $\theta_i, \Theta_i, \theta_i^{-1}$ and Θ_i^{-1} are strictly increasing on $(0, \infty)$;

(ii) $\theta_i^{-1}(\beta)h_i^{-1}(t) \leq h_i^{-1}(\beta t) \leq \Theta_i^{-1}(\beta)h_i^{-1}(t)$, $\forall \beta, t > 0$.

Let us consider the following initial value problem

$$(\Phi_{a_1}(r)\phi_1(u'(r))u'(r))' = b_1(r)\Phi_{a_1}(r)f(u), \quad r > 0, \quad u(0) = \alpha, \quad u'(0) = 0, \quad (2.1)$$

where $\Phi_{a_1}(r)$ is given as in (1.6).

By a simple calculation,

$$u'(r) = h_1^{-1} \left(\frac{1}{\Phi_{a_1}(r)} \int_0^r b_1(s)\Phi_{a_1}(s)f(u(s))ds \right), \quad r > 0, \quad u(0) = \alpha, \quad (2.2)$$

and thus

$$u(r) = \alpha + \int_0^r h_1^{-1} \left(\frac{1}{\Phi_{a_1}(t)} \int_0^t b_1(s)\Phi_{a_1}(s)f(u(s))ds \right) dt, \quad r \geq 0. \quad (2.3)$$

Note that solutions in $C[0, \infty)$ to problem (2.3) are solutions in $C^1[0, \infty)$ to problem (2.1).

Let $\{u_m\}_{m \geq 1}$ be the sequence of positive continuous functions defined on $[0, \infty)$ by

$$\begin{cases} u_0(r) = \alpha, \\ u_m(r) = \alpha + \int_0^r h_1^{-1} \left(\frac{1}{\Phi_{a_1}(t)} \int_0^t b_1(s)\Phi_{a_1}(s)f(u_{m-1}(s))ds \right) dt, \quad r \geq 0. \end{cases} \quad (2.4)$$

Obviously,

$$u'_m(r) = h_1^{-1} \left(\frac{1}{\Phi_{a_1}(r)} \int_0^r b_1(s)\Phi_{a_1}(s)f(u_{m-1}(s))ds \right), \quad r > 0, \quad (2.5)$$

and, for all $r \geq 0$ and $m \in \mathbb{N}$, $u_m(r) \geq \alpha$, and $u_0 \leq u_1$. Then (\mathbf{S}_1) – (\mathbf{S}_3) and Lemma 2.1 yield $u_1(r) \leq u_2(r)$, $\forall r \geq 0$. Continuing this line of reasoning, we obtain that the sequence $\{u_m\}$ is non-decreasing on $[0, \infty)$. Moreover, we obtain by (\mathbf{S}_1) – (\mathbf{S}_3) and Lemma 2.1 that for each $r > 0$

$$\begin{aligned} u'_m(r) &= h_1^{-1} \left(\frac{1}{\Phi_{a_1}(r)} \int_0^r b_1(s)\Phi_{a_1}(s)f(u_{m-1}(s))ds \right) \\ &\leq h_1^{-1} \left(f(u_m(r)) \frac{1}{\Phi_{a_1}(r)} \int_0^r b_1(s)\Phi_{a_1}(s)ds \right) \\ &\leq \Theta_1^{-1}(f(u_m(r))) h_1^{-1} \left(\frac{1}{\Phi_{a_1}(r)} \int_0^r b_1(s)\Phi_{a_1}(s)ds \right), \end{aligned}$$

and

$$\int_a^{u_m(r)} \frac{d\tau}{\Theta_1^{-1}(f(\tau))} \leq I_{1,a_1,b_1}(r).$$

Consequently, for an arbitrary $R > 0$,

$$Y_{1,\alpha}(u_m(r)) \leq I_{1,a_1,b_1}(r) \leq I_{1,a_1,b_1}(R), \quad \forall r \in [0, R]. \quad (2.6)$$

(i) When (\mathbf{S}_6) holds, we see that

$$Y_{1,\alpha}^{-1}(\infty) = \infty \quad \text{and} \quad u_m(r) \leq Y_{1,\alpha}^{-1}(I_{1,a_1,b_1}(r)) \leq Y_{1,\alpha}^{-1}(I_{1,a_1,b_1}(R)), \quad \forall r \in [0, R], \quad (2.7)$$

i.e., the sequence $\{u_m\}$ is bounded on $[0, R]$ for an arbitrary $R > 0$.

It follows by (2.5) that $\{u'_m\}$ is bounded on $[0, R]$. By the Arzelà–Ascoli theorem, $\{u_m\}$ has a subsequence converging uniformly to u on $[0, R]$. Since $\{u_m\}$ is non-decreasing on $[0, \infty)$, we see that $\{u_m\}$ itself converges uniformly to u on $[0, R]$. By the arbitrariness of R , we see

that u is an entire positive radial solution to equation (1.1). Moreover, when $I_{1,a_1,b_1}(\infty) < \infty$, we see by (2.7) that

$$u(r) \leq Y_{1,\alpha}^{-1}(I_{1,a_1,b_1}(\infty)), \quad \forall r \geq 0.$$

Moreover, when $I_{1,a_1,b_1}(\infty) = \infty$, we see by (S₂) and Lemma 2.1 that

$$u(r) \geq \alpha + \theta_1^{-1}(f(\alpha))I_{1,a_1,b_1}(r), \quad \forall r \geq 0.$$

Thus $\lim_{r \rightarrow \infty} u(r) = \infty$.

(ii) When (S₇) holds, we see by (2.6) that

$$Y_{1,\alpha}(u_m(r)) \leq I_{1,a_1,b_1}(\infty) < Y_{1,\alpha}(\infty) < \infty. \quad (2.8)$$

Since $Y_{1,\alpha}^{-1}$ is strictly increasing on $[0, Y_{1,\alpha}(\infty))$, we have

$$u_m(r) \leq Y_{1,\alpha}^{-1}(I_{1,a_1,b_1}(\infty)) < \infty, \quad \forall r \geq 0. \quad (2.9)$$

The rest part of the proof follows from (i). The proof is finished.

3 Proof of Theorems 1.8 and 1.9

In this section we prove Theorems 1.8 and 1.9.

Let us consider the following initial value problem

$$\begin{cases} (\Phi_{a_1}(r)\phi_1(u'(r))u'(r))' = b_1(r)\Phi_{a_1}(r)f_1(u,v), & r > 0, \\ (\Phi_{a_2}(r)\phi_2(v'(r))v'(r))' = b_2(r)\Phi_{a_2}(r)f_2(u,v), & r > 0, \\ u(0) = v(0) = \alpha/2, \quad u'(0) = v'(0) = 0, \end{cases}$$

which is equivalent to

$$\begin{cases} u(r) = \alpha/2 + \int_0^r h_1^{-1}\left(\frac{1}{\Phi_{a_1}(t)} \int_0^t b_1(s)\Phi_{a_1}(s)f_1(u(s),v(s))ds\right)dt, & r \geq 0, \\ v(r) = \alpha/2 + \int_0^r h_2^{-1}\left(\frac{1}{\Phi_{a_2}(t)} \int_0^t b_2(s)\Phi_{a_2}(s)f_2(u(s),v(s))ds\right)dt, & r \geq 0. \end{cases}$$

Let $\{u_m\}_{m \geq 1}$ and $\{v_m\}_{m \geq 0}$ be the sequences of positive continuous functions defined on $[0, \infty)$ by

$$\begin{cases} u_0(r) = v_0(r) = \alpha/2, \\ u_m(r) = \alpha/2 + \int_0^r h_1^{-1}\left(\frac{1}{\Phi_{a_1}(t)} \int_0^t b_1(s)\Phi_{a_1}(s)f_1(u_{m-1}(s),v_{m-1}(s))ds\right)dt, & r \geq 0, \\ v_m(r) = \alpha/2 + \int_0^r h_2^{-1}\left(\frac{1}{\Phi_{a_2}(t)} \int_0^t b_2(s)\Phi_{a_2}(s)f_2(u_{m-1}(s),v_{m-1}(s))ds\right)dt, & r \geq 0. \end{cases}$$

Obviously, for all $r \geq 0$ and $m \in \mathbb{N}$, $u_m(r) \geq \alpha/2$, $v_m(r) \geq \alpha/2$ and $u_0 \leq u_1$, $v_0 \leq v_1$. (S₁)–(S₃) and Lemma 2.1 yield $u_1(r) \leq u_2(r)$ and $v_1(r) \leq v_2(r)$ on $[0, \infty)$. Continuing this

line of reasoning, we obtain that the sequences $\{u_m\}$ and $\{v_m\}$ are increasing on $[0, \infty)$. Moreover, we obtain by (S₁)–(S₃) and Lemma 2.1 that for each $r > 0$

$$\begin{aligned} u'_m(r) &= h_1^{-1} \left(\frac{1}{\Phi_{a_1}(r)} \int_0^r b_1(s) \Phi_{a_1}(s) f_1(u_{m-1}(s), v_{m-1}(s)) ds \right) \\ &\leq h_1^{-1} \left(f_1(u_{m-1}(r), v_{m-1}(r)) \frac{1}{\Phi_{a_1}(t)} \int_0^t b_1(s) \Phi_{a_1}(s) ds \right) \\ &\leq \Theta_1^{-1}(f_1(u_m(r), v_m(r))) h_1^{-1} \left(\frac{1}{\Phi_{a_1}(r)} \int_0^r b_1(s) \Phi_{a_1}(s) ds \right) \\ &\leq \Theta_1^{-1}(f_1(u_m(r) + v_m(r), u_m(r) + v_m(r))) (h_1^{-1}(\Lambda_{b_1, a_1}(r)) + h_2^{-1}(\Lambda_{b_2, a_2}(r))), \end{aligned}$$

where $\Lambda_{b_1, a_1}(r)$ and $\Lambda_{b_2, a_2}(r)$ are given as in (1.5).

In a similar way, we can show that

$$\begin{aligned} v'_m(r) &= h_2^{-1} \left(\frac{1}{\Phi_{a_2}(t)} \int_0^t b_2(s) \Phi_{a_2}(s) f_2(u_{m-1}(s), v_{m-1}(s)) ds \right) dt \\ &\leq \Theta_2^{-1}(f_2(u_m(r), v_m(r))) h_2^{-1} \left(\frac{1}{\Phi_{a_2}(t)} \int_0^t b_2(s) \Phi_{a_2}(s) ds \right) \\ &\leq \Theta_2^{-1}(f_2(u_m(r) + v_m(r), u_m(r) + v_m(r))) (h_1^{-1}(\Lambda_{b_1, a_1}(r)) + h_2^{-1}(\Lambda_{b_2, a_2}(r))). \end{aligned}$$

Consequently,

$$\begin{aligned} u'_m(r) + v'_m(r) &\leq \left(\Theta_1^{-1}(f_1(v_m(r) + u_m(r), v_m(r) + u_m(r))) \right. \\ &\quad \left. + \Theta_2^{-1}(f_2(v_m(r) + u_m(r), v_m(r) + u_m(r))) \right) \\ &\quad \times (h_1^{-1}(\Lambda_{b_1, a_1}(r)) + h_2^{-1}(\Lambda_{b_2, a_2}(r))), \quad r > 0, \end{aligned}$$

and

$$\begin{aligned} \int_a^{u_m(r)+v_m(r)} \frac{d\tau}{\Theta_1^{-1}(f_1(\tau, \tau)) + \Theta_2^{-1}(f_2(\tau, \tau))} &\leq I_{1, b_1, a_1}(r) + I_{2, b_2, a_2}(r), \quad r > 0, \\ Y_{2, \alpha}(u_m(r) + v_m(r)) &\leq I_{1, b_1, a_1}(r) + I_{2, b_2, a_2}(r), \quad \forall r \geq 0. \end{aligned}$$

The remaining proofs are similar to that for Theorems 1.2 and 1.3. Here we omit their proof.

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