The Bernstein-Walsh-Siciak Theorem for analytic hypersurfaces

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Abstract

As a first step towards a general set-theoretic counterpart of the remarkable Bernstein-Walsh-Siciak Theorem concerning the rapidity of polynomial approximation of a holomorphic function on polynomially convex compact sets in $\mathbb{C}^n$, we prove a version of this theorem for analytic hypersurfaces.

1 Preliminaries

The classical Bernstein-Walsh-Siciak Theorem, together with its converse, is the following result (due to Bernstein in the case of a real segment in $\mathbb{C}$, to Walsh for any compact subset of the complex plane and to Siciak in the general setting, see [8], [9]):

\textbf{Theorem 1.1.} Let $K \subset \mathbb{C}^n$ be a nonempty, compact set and $f : K \to \mathbb{C}$ a continuous function. Then

1. if $K$ is polynomially convex and $f$ is the restriction to $K$ of a holomorphic function defined in a neighbourhood of $K$ in $\mathbb{C}^n$, then

\[ \limsup_{d \to +\infty} \sqrt{\text{dist}_d(f, \mathcal{P}_d(\mathbb{C}^n))} < 1; \]

2. if (1) holds and in addition the Siciak extremal function $\Phi$ is continuous, then $f$ is the restriction to $K$ of a holomorphic function defined in a neighbourhood of $K$ in the ambient space. The neighbourhood can be taken of the form \( \{x \in \mathbb{C}^n | \Phi(x) < 1/R\} \) with $R = \limsup_{d \to +\infty} \sqrt{\text{dist}_d(f, \mathcal{P}_d(\mathbb{C}^n))}$.

Here we denote by $\mathcal{P}_d(\mathbb{C}^n)$ the space of complex polynomials in $m$ variables, of degrees $\leq d$. For any compact nonempty set $K \subset \mathbb{C}^n$ and a continuous function $f : K \to \mathbb{C}$ we put

\[ \text{dist}_d(f, \mathcal{P}_d(\mathbb{C}^n)) := \inf \{ ||f - P||_K | P \in \mathcal{P}_d(\mathbb{C}^n) \}, \]

where $||f||_K := \sup_{x \in K} |f(x)|$ is the usual Chebyshev norm. For the convenience of the reader we recall briefly that a nonempty compact set $K \subset \mathbb{C}^n$ is said to be polynomially convex if $f$ coincides with its polynomial hull $\overline{K} := \{ x \in \mathbb{C}^n | |P(x)| \leq ||P||_K, P \in \mathcal{P}(\mathbb{C}^n) \}$ where $\mathcal{P}(\mathbb{C}^n)$ is the space of all complex polynomials in $m$ variables, and the Siciak extremal function $\Phi$ of $K$ is defined to be $\Phi(x) = \sup \{|P(x)|^{1/\deg P} | P \in \mathcal{P}(\mathbb{C}^n) \} \subset \mathbb{C}$.

In other words, the Bernstein-Walsh-Siciak Theorem establishes an equivalence between holomorphicity and the geometric rate of polynomial approximation (recall that the possibility of such an approximation on polynomially convex compact sets is due to the famous Oka-Weil Theorem). It plays an important role in approximation theory and still inspires research, see e.g. [5], [6].

Recall that holomorphic functions are characterized among continuous functions by the analyticity of their graphs. Similarly, a continuous function defined on the whole of $\mathbb{C}^n$ is a polynomial if its graph is algebraic, by the Serre Theorem.

A natural question that arises in complex analytic geometry is whether a Bernstein-Walsh-Siciak-type result is true for the rate of polynomial approximation (recall that the possibility of such an approximation on polynomially convex compact sets is due to the Oka-Weil Theorem). It plays an important role in approximation theory and still inspires research, see e.g. [5], [6].

The first step towards a set-theoretic version of the Bernstein-Walsh-Siciak Theorem is given in the next section, Theorems 2.1 and 2.2 deal with the case of hypersurfaces.

Let us briefly recall the notion of the Kuratowski convergence. Let $\Omega \subset \mathbb{C}^n$ be a locally closed, nonempty set. We denote by $\mathcal{F}_\Omega$ the family of all its closed subsets. This space is endowed with a natural, metrizable convergence, called Painlevé-Kuratowski or Kuratowski convergence, which turns it into a compact metric space (see e.g. [13], the compactness is an old result of Zarankiewicz, more details can be found in [7]). Namely, if $F_\infty, F \in \mathcal{F}_\Omega$, then we will write $F_\infty \xrightarrow{\text{K}} F$ if and only if

1. Any point $x \in F$ is the limit of some sequence of points $x_n \in F_n$;
2. For all compact $K \subset \Omega \setminus F$ there is $K \cap F = \emptyset$, from some index $n_0$ onwards.

If $F$ is compact, then this convergence is given by the extended Hausdorff metric defined by

\[ d_\Omega(E, F) := \begin{cases} \max \{ \max_{x \in E} \text{dist}(x, F), \max_{x \in F} \text{dist}(x, E) \}, & \text{if } E, F \neq \emptyset; \\ 0, & \text{if } E = F = \emptyset; \\ \text{diam } \Omega + 1, & \text{otherwise.} \end{cases} \]
To fix the attention we may assume that all the distances are computed in the usual Euclidean norm. It is easy to see that if \( E \) and \( F \) are both nonempty, then

\[
d_{l}(E, F) = \inf\{r > 0 \mid E \subset F + B_{m}(r) \quad \text{and} \quad F \subset E + B_{m}(r)\},
\]

where \( B_{m}(r) \) is the open Euclidean ball of radius \( r \), centred at the origin.

Given a nonempty subset \( W \subset \mathbb{F}_{\theta} \) and \( E \subset \mathbb{F}_{\theta} \), we write

\[
d_{l}(E, W) = \inf\{d_{l}(E, W) \mid W \subset Y\}
\]

For more informations see [13], [14].

Finally, recall the Hölder continuity property of roots in the version of [10] (Theorem 2.1.2).

**Proposition 1.2.** For any \( a = (a_{1}, \ldots, a_{n}) \in \mathbb{C}^{n} \) let \( P_{k}(t) = r^{n} + a_{1}t^{n-1} + \ldots + a_{n} \) have \( \xi_{j}^{a}, \ldots, \xi_{j}^{a} \) as all roots (counted with multiplicities). Let \(| \cdot | \) be the maximum norm in \( \mathbb{C}^{n} \) and suppose that \( C > 1 \) is such that \( |a| \leq C. \) Then for any \( b \in \mathbb{C}^{n} \) with \( |b| \leq C \) one can renumber the roots of \( P_{k} \) in such a way that

\[
\forall j \in \{1, \ldots, n\}, \quad |\xi_{j}^{a} - \xi_{j}^{b}| \leq 4nC|a - b|^\alpha.
\]

**Remark 1.** It is useful to observe that the condition

\[
\limsup_{n \to \infty} \sqrt[n]{\alpha_{n}} < 1
\]

where \( \alpha_{n} \) is a sequence of non-negative real numbers, is equivalent to the existence of two constants \( M > 0, \theta \in (0, 1) \) such that

\[
\alpha_{n} \leq M\theta^{n}, \quad n = 0, 1, 2, \ldots
\]

## 2 The case of hypersurfaces

In this section we will prove a theorem of Bernstein-Walsh-Siciak type (and its converse) for analytic multifunctions as N. V. Sushchina [11] calls them. The special role played in geometry by the ‘multipographs’ we are considering here may be inferred from [2], [11], [12] and [3], [4].

### 2.1 The setting

Let \( \pi(x, t) = x \) for \( (x, t) \in \mathbb{C}^{m} \times \mathbb{C} \) and let \( K \subset \mathbb{C}^{n} \) be a nonempty compact set. Basically, we will be dealing with sets \( Y \subset K \times \mathbb{C} \subset \mathbb{C}^{m} \times \mathbb{C} \) such that \( \pi(Y) = K \) and the \( x \)-sections of \( Y \) are compact. The first step towards a general set-theoretic counter-part of the Bernstein-Walsh-Siciak Theorem is to consider sets \( Y \) that can be described as the zero-set of a single polynomial in \( t \) with coefficients that are continous in \( x \).

Since it is most convenient to treat such sets \( Y \) as finite, continuous (in the sense of the Hausdorff metric cf. Proposition 1.2) multifunctions \( K \to \mathcal{P}(\mathbb{C}) \), we refer the reader to [7] for details (chapters 4 and 5). Instead of directly using the Hausdorff metric, we will adopt a slightly different point of view, much closer in some sense to the classical Bernstein-Walsh-Siciak Theorem 1.1.1.

We denote by \( Y(x) \subset \mathbb{C} \) the value of the multifunction \( Y \) at \( x \in K \), i.e. the section of the set \( Y \) at the point \( x \). Given a nonempty family \( \mathcal{H}_{K} \) of compact-valued, continuous multifunctions \( K \to \mathcal{P}(\mathbb{C}) \), for any \( W \in \mathcal{H}_{K} \) we may consider

\[
\delta_{K}(Y, W) := \sup_{x \in K} d_{l}(Y(x), W(x))
\]

as a natural counterpart of the Chebyshev norm \(|f - P||_{K} \). Note that if we restrict ourselves e.g. to the space of all multifunctions \( K \to \mathcal{P}(\mathbb{C}) \) with compact graphs, \( \delta_{K} \) is indeed a metric. Moreover, it is easy to see that in this situation

\[
d_{l}(Y, W) \leq \delta_{K}(Y, W).
\]

Next, we put

\[
\text{dist}_{\mathcal{H}_{K}}(Y, \mathcal{H}_{K}) := \inf\{\delta_{K}(Y, W) \mid W \in \mathcal{H}_{K}\}.
\]

The main question is now what should we exactly replace \( \mathcal{P}_{d}(\mathbb{C}^{m}) \) with.

### 2.2 A generalization of Theorem 1.1 (1)

Consider a complex analytic set \( X \subset D \subset \mathbb{C} \) of pure codimension 1 (i.e. a hypersurface) with proper projection \( \pi(x, t) = x \) onto the domain \( D \subset \mathbb{C}^{m} \). Note that every analytic hypersurface admits locally a coordinate system in which it satisfies these assumptions.

For a nonempty set \( K \subset D \) we put \( X_{K} := X \cap (K \times \mathbb{C}) \).

For a given algebraic hypersurface \( V \subset \mathbb{C}^{m+1} \) we can find a reduced polynomial \( P \) (unique up to a unit) such that \( V = P^{-1}(0) \). Then the projective degree \( \deg V \) coincides with \( \deg P \).

If we assume, moreover, that \( \pi_{K} \) is proper, then we can choose \( P \) of the form \( P(x, t) = t^{d} + a_{1}(x)t^{d-1} + \ldots + a_{d}(x) \) with polynomial coefficients (and the leading coefficient is identically equal to 1) and all the degrees \( a_{i} \) and \( d \) do not exceed \( \deg V \).

Note that any algebraic subset of \( \mathbb{C}^{m+1} \) described by a polynomial that is monic in \( t \) has proper projection onto the first \( m \) coordinates. We refer the reader to [4] and [3] for details.

Consider now two families of sets:

\[
\mathcal{V}_{d}^{m} = \{V \subset \mathbb{C}^{m+1} \mid V \text{ is algebraic of pure dimension } m, \deg V \leq d\} \cup \{\emptyset\},
\]

together with

\[
\mathcal{H}^{m}_{d}(K) := \{V_{K} \mid V \in \mathcal{V}_{d}^{m} \setminus \{\emptyset\} : V \text{ has proper projection onto } \mathbb{C}^{m} \cup \{\emptyset\}\}.
\]

We also put \( \mathcal{V}_{d}^{m}(K) := \{V_{K} \mid V \in \mathcal{V}_{d}^{m}\} \).

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1 If \( P \) is not reduced, we have \( \deg V \leq \deg P \).
Remark 2. By the main result of [14], \( V_m \), is closed in the topology of the Kuratowski convergence. However, it is not the case for \( H^m(K) \). To see the latter consider the sequence of graphs

\[
W_{\epsilon} := \{(x, v(x^2-(1/4))) \mid |x| \leq 1\} \in H^2_B(\mathbb{T}_1);
\]

it converges to \( W = \{-1/2, 1/2\} \times C \notin H^2_B(\mathbb{T}_1) \).

Now we are ready to prove our first main result:

**Theorem 2.1.** In the setting introduced above assume that \( K \subset D \) is a nonempty, compact, polynomially convex set. Then

\[
\# \limsup_{d \to +\infty} \frac{1}{\sqrt{|d|}} \text{dist}_2(X_d, V_m(K)) < 1.
\]

In particular, if \( X = F^{-1}(0) \) where \( F(x, t) = t^n + a_1(x)t^{n-1} + \ldots + a_n(x) \in \mathcal{O}(D)[t] \), then there are constants \( M > 0, \theta \in (0, 1) \) and polynomials \( p_d(x, t) = t^n + a_{d1}(x)t^{n-1} + \ldots + a_{dn}(x) \) in \( m + 1 \) variables such that \( \deg p_d^{-1}(0) \leq d \), the polynomial coefficients \( a_{ij,d} \) converge uniformly to \( a_j \) on \( K \) and

\[
\delta_k(X_d, p_d^{-1}(0)x) \leq M\theta^d, \quad d = 0, 1, 2, \ldots
\]

**Proof.** Note that \( X_K \neq \emptyset \).

First, we use the classical Andreotti-Stoll results to describe \( X \) as the set of zeroes of a reduced pseudopolynomial (an optimal polynomial, i.e. with discriminant non identically equal to zero in \( D \)) \( F(x, t) = t^n + a_1(x)t^{n-1} + \ldots + a_n(x) \in \mathcal{O}(D)[t] \).

Next, we can apply the classical Bernstein-Walsh-Siciak Theorem in order to find polynomials \( a_{ij,d} \in P_d(C^m) \) such that for all \( d \in \mathbb{N} \),

\[
||a_j - a_{j,d}||_K \leq M\theta^d, \quad j = 1, \ldots, n,
\]

where the constants \( M > 0 \) and \( \theta \in (0, 1) \) are chosen independent of \( j \). Now, put

\[
P_d(x, t) := t^n + a_{d1}(x)t^{n-1} + \ldots + a_{dn}(x)
\]

and observe that \( \deg p_d^{-1}(0) \leq 2d - 1 \) for \( d \geq n \). Indeed, as noted earlier, \( \deg p_d^{-1}(0) \leq \deg p_d \leq \max\{n, \deg a_{1,d} + n - 1, \ldots, \deg a_{n,d}\} \). Then for \( V(d) := p_d^{-1}(0) \), we have certainly \( V(d) \in H^m_{2d-1}(K) \subset H^m_{2d}(K) \).

Fix \( x \in K \) and write \( t_1(x), \ldots, t_n(x) \) for the roots of \( F(x, \cdot) \) counted with multiplicities. The Hölder continuity of roots (Proposition 1.2) ensures us that after a suitable renumbering of the roots \( t_{1,x}(x) \) of \( p_d(x, \cdot) \) we have

\[
|t_i(x) - t_{1,x}(x)| \leq 4nC \max_{i=1}^n |a_i(x) - a_{i,d}(x)|^{1/n} \leq 4nC M^{1/n} \theta^{d/n}
\]

where \( C \) is an appropriate constant. For instance, \( C = \max_{i=1}^n ||a_i||_K + M \) is good for all \( d \) large enough, since \( ||a_i||_K \leq ||a_i - a_i||_K + ||a_i||_K \). It follows now that there is a constant \( \tilde{M} > 0 \) such that

\[
d_{\tilde{M}}(X(x), V(d)(x)) \leq \tilde{M} \theta^{d/n}, \quad x \in K,
\]

and so for \( \tilde{\theta} := \theta^{1/(2n)} \in (0, 1) \), we obtain eventually

\[
\text{dist}_2(X_K, V_m(K)) \leq \text{dist}_2(X_K, V_m(K)) \leq \delta_k(X_K, V(d)) \leq \tilde{M} \theta^{2d}.
\]

On the other hand, we have seen above that \( V(d) \in H^m_{2d-1}(K) \), too. Therefore, since \( \tilde{\theta} \in (0, 1) \), we obtain directly

\[
\text{dist}_2(X_K, V_m(K)) \leq \text{dist}_2(X_K, H^m_{2d-1}(K)) \leq \delta_k(X_K, V(d)) \leq \tilde{M} \theta^{2d} \leq \tilde{M} \theta^{2d-1}.
\]

and we are done (cf. Remark 1). Note that we do not make use of the fact that \( F \) was taken reduced.

**Remark 3.** In the course of the proof we obtain actually

\[
\limsup_{d \to +\infty} \frac{1}{\sqrt{|d|}} \text{dist}_2(X_d, V_m(K)) < 1.
\]

**Remark 4.** Since in our setting there is \( d_H \leq \delta_k \), the Theorem above holds true also for the Hausdorff metric, i.e.

\[
\limsup_{d \to +\infty} \frac{1}{\sqrt{|d|}} \text{dist}_H(X_d, V_m(K)) < 1.
\]
2.3 A generalization of Theorem 1.1 (2)

In order to prove a converse to the last Theorem, let us consider now the following setting. Put

\[ Y := \{(x, t) \in K \times \mathbb{C} \mid a_0(x)t^n + a_1(x)t^{n-1} + \ldots + a_n(x) = 0\} \]

where \( \emptyset \neq K \subset \mathbb{C}^m \) is compact, \( a_j : K \to \mathbb{C} \) are continuous and \( a_0 \neq 0 \). It is easy to see that assuming \( \pi(x, t) = x \) is proper on \( Y \) is equivalent to say that \( a_0^{-1}(0) = \emptyset \) (compare [12]). Thus, we may as well assume that \( a_0 \equiv 1 \). We will also assume that for some \( x_0 \in K \), there are exactly \( n \) different points in the fibre \( \pi^{-1}(x_0) \cap Y \). Let \( F(x, t) = t^n + a_1(x)t^{n-1} + \ldots + a_n(x) \) be the defining function of \( Y \).

We introduce a new family of sets:

\[ \mathcal{H}_{l}^{m;n}(K) := \{ V_k | V \in \mathcal{V}_K \setminus \{ \emptyset \} : V \text{ has proper projection onto } \mathbb{C}^m \text{ with covering number } \leq n \} \]

Necessarily, \( n \leq d \) (cf. [4], see also [12]).

Remark 5. It is obvious from the proof of Theorem 2.1 that we are actually dealing there with sets \( V_k^{(d)} \in \mathcal{H}_{l}^{m;n}(K) \) so that – in view of Remark 3 – we can replace (###) with

\[ \liminf_{d \to +\infty} \frac{1}{d} \sup \{ \frac{1}{d} \min_{t \in \partial \pi^{-1}(x)} \text{dist}_{d}(\delta_{\pi^{-1}(x)}, \mathcal{H}_{l}^{m;n}(K)) < 1 \}. \]

We can now prove a true converse to Theorem 2.1.

Theorem 2.2. In the setting introduced above, assume moreover that \( \Phi_k \) is continuous. Then the condition

\[ \liminf_{d \to +\infty} \frac{1}{d} \sup \{ \frac{1}{d} \min_{t \in \partial \pi^{-1}(x)} \text{dist}_{d}(\delta_{\pi^{-1}(x)}, \mathcal{H}_{l}^{m;n}(K)) < 1 \}, \]

implies that for some neighbourhood \( U \supset K \) there is an analytic set \( X \subset U \times \mathbb{C} \) of pure codimension 1, having proper projection onto \( U \) and such that \( X_0 = Y \).

In particular, as \( Y = F^{-1}(0) \) with \( F(x, t) = t^n + a_1(x)+\ldots+a_n(x) \in \mathcal{C}(K, \mathbb{C}[t]) \), each coefficient \( a_i \) admits a holomorphic extension \( \tilde{a}_i \in \mathcal{O}(U) \) and \( X = F^{-1}(0) \) for \( F(x, t) = t^n + \tilde{a}_1(x)t^{n-1} + \ldots + \tilde{a}_n(x) \in \mathcal{O}(U)[t] \). Moreover, in this case \( U \) can be taken of the form \( \{ x \in \mathbb{C}^m \mid \Phi_k(x) < 1/R \} \) with \( R = \max_{i \in I} \limsup_{d \to +\infty} \frac{1}{d} \text{dist}_{d}(\pi^{-1}(x), \mathcal{H}_{l}^{m;n}(\mathbb{C}^m)). \)

Before the proof let us note the following basic lemma.

Lemma 2.3. Let \( n \geq 1 \), \( r > 0 \) and take \( t_1, \ldots, t_n, s_1, \ldots, s_n \in \mathbb{C} \). Fix any \( R \geq \max_{i \in I} \{ \tau \mid \exists t_i \in \partial \pi^{-1}(x) \} \) and assume that \( \max_{i \in I} \{ t_i - s_i \} \leq r \). Then for any \( k \in \{ 1, \ldots, n \} \) and any set of indices \( 1 \leq i_1 < \cdots < i_k \leq n \), there is

\[ |t_{i_1} - \cdots - t_{i_k} - s_{i_1} \cdots - s_{i_k}| \leq C_k r \]

where \( C_k = 1 \) and \( C_k = R^{k-1} + (r + R)C_{k-1} \) with \( C_{k-1} \) denoting the constant for \( k - 1 \).

Proof. We proceed by induction on \( k \). Clearly, for \( k = 1 \) we can take \( C_1 = 1 \). Fix \( k > 1 \) and suppose we have the required inequality for \( k - 1 \) with the constant \( C_{k-1} \). Write

\[ |t_{i_1} \cdot \ldots \cdot t_{i_k} - s_{i_1} \cdot \ldots \cdot s_{i_k}| = |t_{i_1} \cdot \ldots \cdot t_{i_k} - s_{i_1} \cdot \ldots \cdot s_{i_k}| \leq |t_{i_1} - s_{i_1}| \cdot |t_{i_2} - s_{i_2}| + \ldots + |t_{i_k} - s_{i_k}| \leq k R^{k-1} + (r + R)C_{k-1} \]

with \( C_k := R^{k-1} + (r + R)C_{k-1} \).

Proof of Theorem 2.2. There are constants \( M > 0, \theta \in (0, 1) \) such that for each \( d \in \mathbb{N} \) we can find \( W_d \in \mathcal{H}_{l}^{m;n}(\mathbb{C}^m) \) satisfying

\[ \delta_{\pi^{-1}(x), W_d} \leq M \theta^d. \]

In particular, \( W_d \to Y \).

It follows from the definition of \( \mathcal{H}_{l}^{m;n}(K) \) that for each \( d \), there are polynomials \( a_{j,d} \), \( j = 1, \ldots, n_d \leq n \) such that \( W_d = P_{d}^{-1}(0) \), where \( P_d(x, t) = t^n + a_{1,d}(x)t^{n-1} + \ldots + a_{n_d,d}(x) \). Then \( \deg W_d \leq d \) implies \( \deg a_{j,d} \leq d - n_j + n \) and \( n \leq d \) (so that \( \deg a_{j,d} \leq 2d - 1 \)).

Take \( x_0 \in K \) for which there are \( n \) pairwise different points \( (x_0, t_i) \in Y, i = 1, \ldots, n \). Separate the points \( t_i \) by pairwise disjoint closed discs \( D_i := t_i + B_1(1) \). Then it is straightforward from the form of \( Y \) that there is a bounded (arbitrarily small), connected neighbourhood \( G \) of \( x_0 \) such that \( (\overline{G} \times \bigcup_{i=1}^{n} \partial D_i) \cap Y = \emptyset \). At the same time \( (\overline{G} \times \text{int}D_i) \cap Y \neq \emptyset \), for each \( i \). Therefore, by the convergence \( W_k \to Y \), we easily conclude that \( P_k(x_0, \cdot) \) has at least \( n \) different roots, whenever \( d \) is large enough, i.e. \( n_d \geq n \), \( d \gg 1 \). Indeed, for \( d \gg 1 \) and each \( i \), \( (\overline{G} \times \partial D_i) \cap W_d = \emptyset \), while \( (\overline{G} \times \text{int}D_i) \cap W_d \neq \emptyset \) which means that \( (\overline{G} \times D_i) \cap W_d \neq \emptyset \) has proper projection on \( G \) and thus by the Remetr Theorem \( r(G \times D_i) \cap W_d = G \), whence \( \{ x_0 \times D_i \} \cap W_d \neq \emptyset \). Summing up, we may assume that \( n_d = n, \) for all \( d \).

The next step consists in observing that each \( a_{j,d} \) converges uniformly to \( a_j \) on \( K \), and the rate of convergence is geometric. Indeed, \( \ast \) implies that for each \( x \in K \), renumbering the roots \( t_1(x), \ldots, t_n(x) \) of \( F(x, \cdot) \) and \( t_1^{(d)}(x), \ldots, t_n^{(d)}(x) \) of \( P_d(x, \cdot) \).
adately, we have \(|t_k(x) - t_k^{(d)}(x)| \leq M \theta^d\), for any \(x \in K\). On the other hand, since the coefficients \(a_i(x)\) and \(a_i^{(d)}(x)\) are expressed in terms of the elementary symmetric polynomials of the roots, a careful application of Lemma 2.3 (c) shows that there is a constant \(M > 0\) such that
\[
||a_k - a_{k,i}||_{k} \leq M \theta^d, \quad k = 1, \ldots, n; \quad d \in \mathbb{N}.
\]

It remains to observe that taking \(\tilde{\theta} := \sqrt{\theta} \in (0,1)\) together with the fact that \(\tilde{\theta}^{2d} < \tilde{\theta}^{2d+1}\) yields eventually
\[
\text{dist}_k(a_j, P_k(C^n)) \leq \tilde{M} \tilde{\theta}^k, \quad j = 1, \ldots, n.
\]

Applying the classical converse to the Bernstein-Walsh-Siciak Theorem, we obtain holomorphic extensions \(a_i \subset \tilde{a}_i\) onto a common neighbourhood \(U\) of \(K\), which implies that \(Y = X_k\) for \(X = F^{-1}(0)\) where \(F(x, t) = t^d + a_i(x)t^{m_i+1} + \ldots + \tilde{a}_i(x) \in \mathcal{O}(U)[x]\). This is the assertion sought after. The form we may take \(U\) in follows from Theorem 1.1 (2). \(\square\)

The situation here is not exactly as before and we do not have the conclusion from Remark 4. As a matter of fact there is no easy transition from \(\delta_k\) to \(d_{H}\) in the last Theorem. This is illustrated by the following Example for which we thank warmly an anonymous reader.

**Example 2.1.** Consider the sequences \(a_k = 0\) and \(a_k = a_{k-1} + (1/2^k)\) for \(k \geq 1\) on the one hand, while on the other, \(b_k = 0\), \(b_k = b_{k-1} + (1/k^2), k \geq 1\). Then \(a_k \to 1\), whereas \(b_k \to \pi^2/6\). Define \(f : [0,1] \to [0, \pi^2/6]\) to be the function whose graph is obtained from the segments \([a_k, b_k], [a_k+1, b_k+1]) \subset \mathbb{R}^2\) with \(f(1) = \pi^2/6\) for continuity.

Next, for \(k \geq 1\), let \(f_k\) be equal to \(f\) everywhere on \([0,1] \setminus [a_k, a_{k-1}]\), while on \([a_k, a_{k+1}]\) we define the graph of \(f_k\) to be the segment joining the points \((a_k, b_k), (a_k+1, b_k+1))\) over \([a_k+1, a_{k+1}/2]\), and \(f_k(x) = b_k+1\), whenever \(x \in [a_k+1, a_{k+1}]\).

Then it is apparent that the Hausdorff distance between the graphs of \(f\) and \(f_k\) is at most \(1/2^k\), while \(||f - f_k||_{[0,1]} = 1/(2k^2)\).

Therefore, even though the rate of the convergence of the graphs of \(f_k\) to the graph of \(f\) in the Hausdorff distance is geometric, the rate of uniform convergence of \(f_k\) to \(f\) is not \((t)\).

As a consequence, if we try to prove Theorem 2.2 along the same lines as before, but under the assumption
\[
\lim_{d \to +\infty} \left(\frac{1}{d} \text{dist}_d(Y, \mathcal{H}^{m_d}(K))\right) < 1,
\]
there seems to be no simple way of concluding that the rate of convergence of \(||a_j - a_{i,j}||_k\) to zero is geometric as we would like it to be. The point is that repeating the argument from the proof of Theorem 2.2, we see that now \(d_{H}\) \((0,1)\) implies that after a suitable renumbering of the roots \(t_k(x), \ldots, t_k^{(d)}(x)\) of \(F(x, \cdot)\) and \(t_k^{(d)}(x)\) \((0,1)\) of \(P_k(x, \cdot), \) we have \(|t_k(x) - t_k^{(d)}(x)| \leq C_d M \theta^d, \) for some constant \(C_d > 0\) independent of \(x\) \((t)\), but dependent on \(d\). Therefore, we are led to the inequality \(||a_k - a_{i,j}||_k \leq C_d M \theta^d\) and we do not now whether it is possible to replace \(C_d M\) by a constant \(M\) independent of \(d\).

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### References


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1Note that the roots \(t_k(x)\) are uniformly bounded from above and it is enough to estimate the differences \(t_k(x) - t_k^{(d)}(x)\) uniformly w.r.t. \(x \in K\), for any \(1 \leq i_1 < \ldots < i_k \leq n\), since the \(k\)-th coefficient \(a_k(x)\) is equal to \((-1)^k \sum_{i_1 < \ldots < i_k} t_k^{(d)}(x) - t_k^{(d)}(x)\) uniformly w.r.t. \(x \in K\), for any \(1 \leq i_1 < \ldots < i_k \leq n\), such that \(Y \subset K \times \mathcal{H}^{m_d}(K)\) yields \(||a_k - a_{k,i}||_k \leq D_k \theta^d\) with \(D_k = (||\theta^{-1} + (M + R)C_d||)\) for \(k = 2, \ldots, n\), and \(D_n = n\) (since \(\theta^d < 1\) we can replace \(M \theta^d\) in \(D_n\) and in all the \(C_s, j < k, \) with \(M\)).

2This is essentially due to the fact that computing the Hausdorff distance involves ‘looking in various directions’, while computing the Chebyshev norm restricts to a ‘vertical point of view’.

3This is a general statement about multiforms: if \(F, G : K \to \mathbb{R}^d\) are compact, continuous multiforms on a compact \(K \subset \mathbb{R}^d\) and \(d_{H}(\text{graph}(F), \text{graph}(G)) \leq r\), then for some \(C > 0\), \(d_{H}(F(x), G(x)) \leq C r\), for all \(x \in K\). Otherwise, we would find a sequence \(n_1 < n_2 < \ldots \in \mathbb{N}\) and points \(x_{n_1} \in K\) convergent to some \(x_0 \in K\) and such that \(d_{H}(F(x_{n_1}), G(x_{n_1})) \geq n_i r, \) for all \(i = 1,2, \ldots\), which yields a contradiction, since the left-hand side converges to \(d_{H}(F(x_0), G(x_0))\).


