

On ϕ -pseudo symmetric Kenmotsu manifolds with respect to quarter-symmetric metric connection

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Abstract. The object of the present paper is to study ϕ -pseudo symmetric and ϕ -pseudo Ricci symmetric Kenmotsu manifolds with respect to quarter-symmetric metric connection and obtain a necessary and sufficient condition of a ϕ -pseudo symmetric Kenmotsu manifold with respect to quarter symmetric metric connection to be ϕ -pseudo symmetric Kenmotsu manifold with respect to Levi-Civita connection.

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1 Introduction

In [48] Tanno classified connected almost contact metric manifolds whose automorphism groups possess the maximum dimension. For such a manifold, the sectional curvature of plane sections containing ξ is a constant, say c . He proved that they could be divided into three classes: (i) homogeneous normal contact Riemannian manifolds with $c > 0$, (ii) global Riemannian products of a line or a circle with a Kähler manifold of constant holomorphic sectional curvature if $c = 0$ and (iii) a warped product space $\mathbb{R} \times_f \mathbb{C}^n$ if $c < 0$. It is known that the manifolds of class (i) are characterized by admitting a Sasakian structure. The manifolds of class (ii) are characterized by a tensorial relation admitting a cosymplectic structure. Kenmotsu [29] characterized the differential geometric properties of the manifolds of class (iii) which are nowadays called Kenmotsu manifolds and later studied by several authors.

As a generalization of both Sasakian and Kenmotsu manifolds, Oubiña [34] introduced the notion of trans-Sasakian manifolds, which are closely related to the locally conformal Kähler manifolds. A trans-Sasakian manifold of type $(0, 0)$, $(\alpha, 0)$ and $(0, \beta)$ are called the cosymplectic, α -Sasakian and β -Kenmotsu manifolds respectively, α, β being scalar functions. In particular, if $\alpha = 0, \beta = 1$; and $\alpha = 1, \beta = 0$ then a trans-Sasakian manifold will be a Kenmotsu and Sasakian manifold respectively.

The study of Riemann symmetric manifolds began with the work of Cartan [6]. A Riemannian manifold (M^n, g) is said to be locally symmetric due to Cartan [6] if

its curvature tensor R satisfies the relation $\nabla R = 0$, where ∇ denotes the operator of covariant differentiation with respect to the metric tensor g .

During the last five decades the notion of locally symmetric manifolds has been weakened by many authors in several ways to a different extent such as recurrent manifold by Walker [55], semisymmetric manifold by Szabó [47], pseudosymmetric manifold in the sense of Deszcz [20], pseudosymmetric manifold in the sense of Chaki [7].

A non-flat Riemannian manifold (M^n, g) ($n > 2$) is said to be pseudosymmetric in the sense of Chaki [7] if it satisfies the relation

$$(1.1) \quad (\nabla_W R)(X, Y, Z, U) = 2A(W)R(X, Y, Z, U) + A(X)R(W, Y, Z, U) \\ + A(Y)R(X, W, Z, U) + A(Z)R(X, Y, W, U) \\ + A(U)R(X, Y, Z, W),$$

i.e.,

$$(1.2) \quad (\nabla_W R)(X, Y)Z = 2A(W)R(X, Y)Z + A(X)R(W, Y)Z \\ + A(Y)R(X, W)Z + A(Z)R(X, Y)W \\ + g(R(X, Y)Z, W)\rho$$

for any vector field X, Y, Z, U and W , where R is the Riemannian curvature tensor of the manifold, A is a non-zero 1-form such that $g(X, \rho) = A(X)$ for every vector field X . Such an n -dimensional manifold is denoted by $(PS)_n$.

Every recurrent manifold is pseudosymmetric in the sense of Chaki [7] but not conversely. Also the pseudosymmetry in the sense of Chaki is not equivalent to that in the sense of Deszcz [20]. However, pseudosymmetry by Chaki will be the pseudosymmetry by Deszcz if and only if the non-zero 1-form associated with $(PS)_n$, is closed. Pseudosymmetric manifolds in the sense of Chaki have been studied by Chaki and Chaki [9], Chaki and De [10], De [12], De and Biswas [14], De, Murathan and Özgür [17], Özen and Altay ([36], [37]), Tarafder ([51], [52]), Tarafder and De [53] and others.

A Riemannian manifold is said to be Ricci symmetric if its Ricci tensor S of type (0,2) satisfies $\nabla S = 0$, where ∇ denotes the Riemannian connection. During the last five decades, the notion of Ricci symmetry has been weakened by many authors in several ways to a different extent such as Ricci recurrent manifold [38], Ricci semisymmetric manifold [47], pseudo Ricci symmetric manifold by Deszcz [21], pseudo Ricci symmetric manifold by Chaki [8].

A non-flat Riemannian manifold (M^n, g) is said to be pseudo Ricci symmetric [8] if its Ricci tensor S of type (0,2) is not identically zero and satisfies the condition

$$(1.3) \quad (\nabla_X S)(Y, Z) = 2A(X)S(Y, Z) + A(Y)S(X, Z) + A(Z)S(Y, X)$$

for any vector field X, Y, Z , where A is a nowhere vanishing 1-form and ∇ denotes the operator of covariant differentiation with respect to the metric tensor g . Such an n -dimensional manifold is denoted by $(PRS)_n$. The pseudo Ricci symmetric manifolds have been also studied by Arslan et. al [3], Chaki and Saha [11], De and Mazumder [16], De, Murathan and Özgür [17], Özen [35] and many others.

The relation (1.3) can be written as

$$(1.4) \quad (\nabla_X Q)(Y) = 2A(X)Q(Y) + A(Y)Q(X) + S(Y, X)\rho,$$

where ρ is the vector field associated to the 1-form A such that $A(X) = g(X, \rho)$ and Q is the Ricci operator, i.e., $g(QX, Y) = S(X, Y)$ for all X, Y .

As a weaker version of local symmetry, the notion of locally ϕ -symmetric Sasakian manifolds was introduced by Takahashi [49]. Generalizing the notion of locally ϕ -symmetric Sasakian manifolds, De, Shaikh and Biswas [18] introduced the notion of ϕ -recurrent Sasakian manifolds. In this connection De [13] introduced and studied ϕ -symmetric Kenmotsu manifolds and in [19] De, Yildiz and Yaliniz introduced and studied ϕ -recurrent Kenmotsu manifolds. In this connection it may be mentioned that Shaikh and Hui studied locally ϕ -symmetric β -kenmotsu manifolds [43] and extended generalized ϕ -recurrent β -Kenmotsu Manifolds [44], respectively. Also in [39] Prakash studied concircularly ϕ -recurrent Kenmotsu Manifolds. In [46] Shukla and Shukla studied ϕ -Ricci symmetric Kenmotsu manifolds. Recently the present author [26] studied ϕ -pseudo symmetric and ϕ -pseudo Ricci symmetric Kenmotsu manifolds.

Definition 1.1. A Kenmotsu manifold $M^n(\phi, \xi, \eta, g)$ ($n > 3$) is said to be ϕ -pseudo symmetric [26] if the curvature tensor R satisfies

$$(1.5) \quad \begin{aligned} \phi^2((\nabla_W R)(X, Y)Z) &= 2A(W)R(X, Y)Z + A(X)R(W, Y)Z \\ &+ A(Y)R(X, W)Z + A(Z)R(X, Y)W \\ &+ g(R(X, Y)Z, W)\rho \end{aligned}$$

for any vector field X, Y, Z and W , where A is a non-zero 1-form. In particular, if $A = 0$ then the manifold is said to be ϕ -symmetric [13].

Definition 1.2. A Kenmotsu manifold $M^n(\phi, \xi, \eta, g)$ ($n > 3$) is said to be ϕ -pseudo Ricci symmetric [26] if the Ricci operator Q satisfies

$$(1.6) \quad \phi^2((\nabla_X Q)(Y)) = 2A(X)QY + A(Y)QX + S(Y, X)\rho$$

for any vector field X, Y , where A is a non-zero 1-form.

In particular, if $A = 0$, then (1.6) turns into the notion of ϕ -Ricci symmetric Kenmotsu manifold introduced by Shukla and Shukla [46].

In [22] Friedmann and Schouten introduced the notion of semisymmetric linear connection on a differentiable manifold. Then in 1932 Hayden [24] introduced the idea of metric connection with torsion on a Riemannian manifold. A systematic study of the semisymmetric metric connection on a Riemannian manifold has been given by Yano in 1970 [56]. In 1975, Golab introduced the idea of a quarter symmetric linear connection in differentiable manifolds.

A linear connection $\bar{\nabla}$ in an n -dimensional differentiable manifold M is said to be a quarter symmetric connection [23] if its torsion tensor τ of the connection $\bar{\nabla}$ is of the form

$$(1.7) \quad \begin{aligned} \tau(X, Y) &= \bar{\nabla}_X Y - \bar{\nabla}_Y X - [X, Y] \\ &= \eta(Y)\phi X - \eta(X)\phi Y, \end{aligned}$$

where η is a 1-form and ϕ is a tensor of type (1,1). In particular, if $\phi X = X$ then the quarter symmetric connection reduces to the semisymmetric connection. Thus the

notion of quarter symmetric connection generalizes the notion of the semisymmetric connection. Again if the quarter symmetric connection $\bar{\nabla}$ satisfies the condition

$$(1.8) \quad (\bar{\nabla}_X g)(Y, Z) = 0$$

for all $X, Y, Z \in \chi(M)$, where $\chi(M)$ is the Lie algebra of vector fields on the manifold M , then $\bar{\nabla}$ is said to be a quarter symmetric metric connection. Quarter symmetric metric connection have been studied by many authors in several ways to a different extent such as [1], [2], [4], [25], [27], [28], [30], [31], [32], [33], [41], [42], [45], [50], [54]. Recently Prakasha [40] studied ϕ -symmetric Kenmotsu manifolds with respect to quarter symmetric metric connection.

Motivated by the above studies the present paper deals with the study of ϕ -pseudo symmetric and ϕ -pseudo Ricci symmetric Kenmotsu manifolds with respect to quarter symmetric metric connection. The paper is organized as follows. Section 2 is concerned with preliminaries. Section 3 is devoted to the study of ϕ -pseudo symmetric Kenmotsu manifolds with respect to quarter symmetric metric connection and obtain a necessary and sufficient condition of a ϕ -pseudo symmetric Kenmotsu manifold with respect to quarter symmetric metric connection to be ϕ -pseudo symmetric Kenmotsu manifold with respect to Levi-Civita connection. In section 4, we have studied ϕ -pseudo Ricci symmetric Kenmotsu manifolds with respect to quarter symmetric metric connection.

2 Preliminaries

A smooth manifold (M^n, g) ($n = 2m + 1 > 3$) is said to be an almost contact metric manifold [5] if it admits a (1,1) tensor field ϕ , a vector field ξ , an 1-form η and a Riemannian metric g which satisfy

$$(2.1) \quad \phi\xi = 0, \quad \eta(\phi X) = 0, \quad \phi^2 X = -X + \eta(X)\xi,$$

$$(2.2) \quad g(\phi X, Y) = -g(X, \phi Y), \quad \eta(X) = g(X, \xi), \quad \eta(\xi) = 1,$$

$$(2.3) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y)$$

for all vector fields X, Y on M .

An almost contact metric manifold $M^n(\phi, \xi, \eta, g)$ is said to be Kenmotsu manifold if the following condition holds [29]:

$$(2.4) \quad \nabla_X \xi = X - \eta(X)\xi,$$

$$(2.5) \quad (\nabla_X \phi)(Y) = g(\phi X, Y)\xi - \eta(Y)\phi X,$$

where ∇ denotes the Riemannian connection of g .

In a Kenmotsu manifold, the following relations hold [29]:

$$(2.6) \quad (\nabla_X \eta)(Y) = g(X, Y) - \eta(X)\eta(Y),$$

$$(2.7) \quad R(X, Y)\xi = \eta(X)Y - \eta(Y)X,$$

$$(2.8) \quad R(\xi, X)Y = \eta(Y)X - g(X, Y)\xi,$$

$$(2.9) \quad \eta(R(X, Y)Z) = \eta(Y)g(X, Z) - \eta(X)g(Y, Z),$$

$$(2.10) \quad S(X, \xi) = -(n-1)\eta(X),$$

$$(2.11) \quad S(\xi, \xi) = -(n-1), \quad \text{i.e., } Q\xi = -(n-1)\xi,$$

$$(2.12) \quad S(\phi X, \phi Y) = S(X, Y) + (n-1)\eta(X)\eta(Y),$$

$$(2.13) \quad (\nabla_W R)(X, Y)\xi = g(X, W)Y - g(Y, W)X - R(X, Y)W$$

for any vector field X, Y, Z on M and R is the Riemannian curvature tensor and S is the Ricci tensor of type $(0,2)$ such that $g(QX, Y) = S(X, Y)$.

Let M be an n -dimensional Kenmotsu manifold and ∇ be the Levi-Civita connection on M . A quarter symmetric metric connection $\bar{\nabla}$ in a Kenmotsu manifold is defined by ([23], [40])

$$(2.14) \quad \bar{\nabla}_X Y = \nabla_X Y + H(X, Y),$$

where H is a tensor of type $(1,1)$ such that

$$(2.15) \quad H(X, Y) = \frac{1}{2}[\tau(X, Y) + \tau'(X, Y) + \tau'(Y, X)]$$

and

$$(2.16) \quad g(\tau'(X, Y), Z) = g(\tau(Z, X), Y).$$

From (1.7) and (2.16), we get

$$(2.17) \quad \tau'(X, Y) = g(\phi Y, X)\xi - \eta(X)\phi Y.$$

Using (1.7) and (2.17) in (2.15), we obtain

$$(2.18) \quad H(X, Y) = -\eta(X)\phi Y.$$

Hence a quarter symmetric metric connection $\bar{\nabla}$ in a Kenmotsu manifold is given by

$$(2.19) \quad \bar{\nabla}_X Y = \nabla_X Y - \eta(X)\phi Y.$$

If R and \bar{R} are respectively the curvature tensor of Levi-Civita connection ∇ and the quarter symmetric metric connection $\bar{\nabla}$ in a Kenmotsu manifold then we have [40]

$$(2.20) \quad \begin{aligned} \bar{R}(X, Y)Z &= R(X, Y)Z - 2d\eta(X, Y)\phi Z \\ &+ [\eta(X)g(\phi Y, Z) - \eta(Y)g(\phi X, Z)]\xi \\ &+ [\eta(Y)\phi X - \eta(X)\phi Y]\eta(Z). \end{aligned}$$

From (2.20) we have

$$(2.21) \quad \bar{S}(Y, Z) = S(Y, Z) - 2d\eta(\phi Z, Y) + g(\phi Y, Z) + \psi\eta(Y)\eta(Z),$$

where \bar{S} and S are respectively the Ricci tensor of a Kenmotsu manifold with respect to the quarter symmetric metric connection and Levi-Civita connection and $\psi = tr.\omega$, where $\omega(X, Y) = g(\phi X, Y)$. From (2.21) it follows that the Ricci tensor with respect to quarter symmetric metric connection is not symmetric.

Also from (2.21), we have

$$(2.22) \quad \bar{r} = r + 2(n - 1),$$

where \bar{r} and r are the scalar curvatures with respect to quarter symmetric metric connection and Levi-Civita connection respectively.

From (2.1), (2.2), (2.5), (2.13), (2.19) and (2.20), we get

$$(2.23) \quad \begin{aligned} (\bar{\nabla}_W \bar{R})(X, Y)\xi &= g(X, W)Y - g(Y, W)X - R(X, Y)W \\ &+ [\eta(Y)g(\phi W, X) - \eta(X)g(\phi W, Y)]\xi \\ &- \eta(W)[\eta(X)Y - \eta(Y)X \\ &+ \eta(X)\phi Y - \eta(Y)\phi X]. \end{aligned}$$

Again from (2.19) and (2.20), we have

$$(2.24) \quad g((\bar{\nabla}_W \bar{R})(X, Y)Z, U) = -g((\bar{\nabla}_W \bar{R})(X, Y)U, Z).$$

Definition 2.1. A Kenmotsu manifold M is said to be η -Einstein if its Ricci tensor S of type (0,2) is of the form

$$(2.25) \quad S = ag + b\eta \otimes \eta,$$

where a, b are smooth functions on M .

3 ϕ -pseudo symmetric Kenmotsu manifolds with respect to quarter symmetric metric connection

Definition 3.1. A Kenmotsu manifold $M^n(\phi, \xi, \eta, g)$ ($n = 2m + 1 > 3$) is said to be ϕ -pseudo symmetric with respect to quarter symmetric metric connection if the curvature tensor \bar{R} with respect to quarter symmetric metric connection satisfies

$$(3.1) \quad \begin{aligned} \phi^2((\bar{\nabla}_W \bar{R})(X, Y)Z) &= 2A(W)\bar{R}(X, Y)Z + A(X)\bar{R}(W, Y)Z \\ &+ A(Y)\bar{R}(X, W)Z + A(Z)\bar{R}(X, Y)W \\ &+ g(\bar{R}(X, Y)Z, W)\rho, \end{aligned}$$

for any vector field X, Y, Z and W , where A is a non-zero 1-form.

In particular, if $A = 0$ then the manifold is said to be ϕ -symmetric Kenmotsu manifold with respect to quarter symmetric metric connection [40].

We now consider a Kenmotsu manifold $M^n(\phi, \xi, \eta, g)$ ($n = 2m + 1 > 3$), which is ϕ -pseudo symmetric with respect to quarter symmetric metric connection. Then by virtue of (2.1), it follows from (3.1) that

$$(3.2) \quad \begin{aligned} & -(\bar{\nabla}_W \bar{R})(X, Y)Z + \eta((\bar{\nabla}_W \bar{R})(X, Y)Z)\xi \\ & = 2A(W)\bar{R}(X, Y)Z + A(X)\bar{R}(W, Y)Z + A(Y)\bar{R}(X, W)Z \\ & + A(Z)\bar{R}(X, Y)W + g(\bar{R}(X, Y)Z, W)\rho \end{aligned}$$

from which it follows that

$$(3.3) \quad \begin{aligned} & -g((\bar{\nabla}_W \bar{R})(X, Y)Z, U) + \eta((\bar{\nabla}_W \bar{R})(X, Y)Z)\eta(U) \\ & = 2A(W)g(\bar{R}(X, Y)Z, U) + A(X)g(\bar{R}(W, Y)Z, U) + A(Y)g(\bar{R}(X, W)Z, U) \\ & + A(Z)g(\bar{R}(X, Y)W, U) + g(\bar{R}(X, Y)Z, W)A(U). \end{aligned}$$

Taking an orthonormal frame field and then contracting (3.3) over X and U and then using (2.1) and (2.2), we get

$$(3.4) \quad \begin{aligned} & -(\bar{\nabla}_W \bar{S})(Y, Z) + g((\bar{\nabla}_W \bar{R})(\xi, Y)Z, \xi) \\ & = 2A(W)\bar{S}(Y, Z) + A(Y)\bar{S}(W, Z) + A(Z)\bar{S}(Y, W) \\ & + A(\bar{R}(W, Y)Z) + A(\bar{R}(W, Z)Y). \end{aligned}$$

Using (2.8), (2.23) and (2.24), we have

$$(3.5) \quad \begin{aligned} g((\bar{\nabla}_W \bar{R})(\xi, Y)Z, \xi) & = -g((\bar{\nabla}_W \bar{R})(\xi, Y)\xi, Z) \\ & = g(\phi W, Y)\eta(Z) + g(\phi Y, Z)\eta(W) \\ & + [g(Y, Z) - \eta(Y)\eta(Z)]\eta(W). \end{aligned}$$

By virtue of (3.5) it follows from (3.4) that

$$(3.6) \quad \begin{aligned} (\bar{\nabla}_W \bar{S})(Y, Z) & = -2A(W)\bar{S}(Y, Z) - A(Y)\bar{S}(W, Z) - A(Z)\bar{S}(Y, W) \\ & - A(\bar{R}(W, Y)Z) - A(\bar{R}(W, Z)Y) - g(\phi W, Y)\eta(Z) \\ & - g(\phi Y, Z)\eta(W) - [g(Y, Z) - \eta(Y)\eta(Z)]\eta(W). \end{aligned}$$

This leads to the following:

Theorem 3.1. *A ϕ -pseudo symmetric Kenmotsu manifold with respect to quarter symmetric metric connection is pseudo Ricci symmetric with respect to quarter symmetric metric connection if and only if*

$$\begin{aligned} & A(\bar{R}(W, Y)Z) + A(\bar{R}(W, Z)Y) + g(\phi W, Y)\eta(Z) \\ & + g(\phi Y, Z)\eta(W) + [g(Y, Z) + \eta(Y)\eta(Z)]\eta(W) = 0. \end{aligned}$$

Setting $Z = \xi$ in (3.4) and using (3.5), we get

$$(3.7) \quad \begin{aligned} & -(\bar{\nabla}_W \bar{S})(Y, \xi) + g(\phi W, Y) \\ & = 2A(W)\bar{S}(Y, \xi) + A(Y)\bar{S}(W, \xi) + A(\xi)\bar{S}(Y, W) \\ & + A(\bar{R}(W, Y)\xi) + A(\bar{R}(W, \xi)Y). \end{aligned}$$

By virtue of (2.7), (2.8), we have from (2.20) that

$$(3.8) \quad \bar{R}(X, Y)\xi = \eta(X)[Y - \phi Y] - \eta(Y)[X - \phi X],$$

$$(3.9) \quad \bar{R}(X, \xi)Y = [g(X, Y) - g(\phi X, Y)]\xi - \eta(Y)[X - \phi X].$$

Also in view of (2.10) we get from (2.21) that

$$(3.10) \quad \bar{S}(Y, \xi) = [\psi - (n - 1)]\eta(Y).$$

We know that

$$(3.11) \quad (\bar{\nabla}_W \bar{S})(Y, \xi) = \bar{\nabla}_W \bar{S}(Y, \xi) - \bar{S}(\bar{\nabla}_W Y, \xi) - \bar{S}(Y, \bar{\nabla}_W \xi).$$

Using (2.4), (2.10), (2.19) and (2.21) in (3.11) we get

$$(3.12) \quad (\bar{\nabla}_W \bar{S})(Y, \xi) = -S(Y, W) + 2d\eta(\phi Y, W) - g(\phi Y, W) \\ + [\psi - (n - 1)]g(Y, W) - \psi\eta(Y)\eta(W).$$

In view of (2.3), (2.21) and (3.8)-(3.10), we have from (3.12) that

$$(3.13) \quad [1 - A(\xi)]S(Y, W) = [\psi - (n - 1) - A(\xi)]g(Y, W) \\ + 2A(\xi)g(\phi Y, W) + [\psi - (n - 1)][2A(W)\eta(Y) \\ + A(Y)\eta(W)] - [1 - A(\xi)]\psi\eta(Y)\eta(W) \\ + [A(Y) - A(\phi Y)]\eta(W) \\ - 2[A(W) - A(\phi W)]\eta(Y).$$

Contracting (3.13) over Y and W , we obtain

$$(3.14) \quad [1 - A(\xi)]r = (n - 1)(\psi - n) + 2(3\psi - 2n + 1)A(\xi).$$

This leads to the following:

Theorem 3.2. *In a ϕ -pseudo symmetric Kenmotsu manifold with respect to quarter symmetric metric connection the Ricci tensor and the scalar curvature are respectively given by (3.13) and (3.14).*

In particular, if $A = 0$ then (3.13) reduces to

$$S(Y, W) = [\psi - (n - 1)]g(Y, W) - \psi\eta(Y)\eta(W),$$

which implies that the manifold under consideration is η -Einstein.

This leads to the following:

Corollary 3.3. *A ϕ -symmetric Kenmotsu manifold with respect to quarter symmetric metric connection is an η -Einstein manifold.*

Using (2.24) in (3.2), we get

$$(3.15) \quad (\bar{\nabla}_W \bar{R})(X, Y)Z = -g((\bar{\nabla}_W \bar{R})(X, Y)\xi, Z)\xi - 2A(W)\bar{R}(X, Y)Z \\ - A(X)\bar{R}(W, Y)Z - A(Y)\bar{R}(X, W)Z \\ - A(Z)\bar{R}(X, Y)W - g(\bar{R}(X, Y)Z, W)\rho.$$

In view of (2.20) and (2.23) it follows from (3.15) that

$$\begin{aligned}
(3.16) \quad (\bar{\nabla}_W \bar{R})(X, Y)Z &= [R(X, Y, W, Z) \\
&+ g(X, Z)g(Y, W) - g(X, W)g(Y, Z) \\
&+ \eta(X)g(\phi W, Y) - \eta(Y)g(\phi W, X) \\
&+ \{g(Y, Z) + g(\phi Y, Z)\}\eta(W)\eta(X) \\
&- \{g(X, Z) + g(\phi X, Z)\}\eta(W)\eta(Y)]\xi \\
&- 2A(W)[R(X, Y)Z - 2d\eta(X, Y)\phi Z \\
&+ \{\eta(X)g(\phi Y, Z) - \eta(Y)g(\phi X, Z)\}\xi \\
&+ \{\eta(Y)\phi X - \eta(X)\phi Y\}\eta(Z)] \\
&- A(X)[R(W, Y)Z - 2d\eta(W, Y)\phi Z \\
&+ \{\eta(W)g(\phi Y, Z) - \eta(Y)g(\phi W, Z)\}\xi \\
&+ \{\eta(Y)\phi W - \eta(W)\phi Y\}\eta(Z)] \\
&- A(Y)[R(X, W)Z - 2d\eta(X, W)\phi Z \\
&+ \{\eta(X)g(\phi W, Z) - \eta(W)g(\phi X, Z)\}\xi \\
&+ \{\eta(W)\phi X - \eta(X)\phi W\}\eta(Z)] \\
&- A(Z)[R(X, Y)W - 2d\eta(X, Y)\phi W \\
&+ \{\eta(X)g(\phi Y, W) - \eta(Y)g(\phi X, W)\}\xi \\
&+ \{\eta(Y)\phi X - \eta(X)\phi Y\}\eta(W)] \\
&- [R(X, Y, Z, W) - 2d\eta(X, Y)g(\phi Z, W) \\
&+ \{\eta(X)g(\phi Y, Z) - \eta(Y)g(\phi X, Z)\}\eta(W) \\
&+ \{\eta(Y)g(\phi X, W) - \eta(X)g(\phi Y, W)\}\eta(Z)]\rho
\end{aligned}$$

for arbitrary vector fields X, Y, Z and W .

This leads to the following:

Theorem 3.4. *A Kenmotsu manifold is ϕ -pseudo symmetric with respect to quarter symmetric metric connection if and only if the relation (3.16) holds.*

Let us take a ϕ -pseudo symmetric Kenmotsu manifold with respect to Levi-Civita connection. Then the relation (1.5) holds. By virtue of (2.1), (2.13) and the relation $g((\nabla_W R)(X, Y)Z, U) = -g((\nabla_W R)(X, Y)U, Z)$ it follows from (1.5) that

$$\begin{aligned}
(3.17) \quad (\nabla_W R)(X, Y)Z &= [R(X, Y, W, Z) + g(X, Z)g(Y, W) \\
&- g(X, W)g(Y, Z)]\xi - 2A(W)R(X, Y)Z \\
&- A(X)R(W, Y)Z - A(Y)R(X, W)Z \\
&- A(Z)R(X, Y)W - g(R(X, Y)Z, W)\rho.
\end{aligned}$$

From (3.16) and (3.17), we can state the following:

Theorem 3.5. *A ϕ -pseudo symmetric Kenmotsu manifold is invariant under quarter*

symmetric metric connection if and only if the relation

$$\begin{aligned}
& [\eta(X)g(\phi W, Y) - \eta(Y)g(\phi W, X) + \{g(Y, Z) + g(\phi Y, Z)\}\eta(W)\eta(X) \\
& - \{g(X, Z) + g(\phi X, Z)\}\eta(W)\eta(Y)]\xi + 2A(W)[2d\eta(X, Y)\phi Z \\
& - \{\eta(X)g(\phi Y, Z) - \eta(Y)g(\phi X, Z)\}\xi - \{\eta(Y)\phi X - \eta(X)\phi Y\}\eta(Z)] \\
& + A(X)[2d\eta(W, Y)\phi Z - \{\eta(W)g(\phi Y, Z) - \eta(Y)g(\phi W, Z)\}\xi \\
& - \{\eta(Y)\phi W - \eta(W)\phi Y\}\eta(Z)] + A(Y)[2d\eta(X, W)\phi Z \\
& - \{\eta(X)g(\phi W, Z) - \eta(W)g(\phi X, Z)\}\xi - \{\eta(W)\phi X - \eta(X)\phi W\}\eta(Z)] \\
& + A(Z)[2d\eta(X, Y)\phi W - \{\eta(X)g(\phi Y, W) - \eta(Y)g(\phi X, W)\}\xi \\
& - \{\eta(Y)\phi X - \eta(X)\phi Y\}\eta(W)] + [2d\eta(X, Y)g(\phi Z, W) \\
& - \{\eta(X)g(\phi Y, Z) - \eta(Y)g(\phi X, Z)\}\eta(W) \\
& - \{\eta(Y)g(\phi X, W) - \eta(X)g(\phi Y, W)\}\eta(Z)]\rho = 0
\end{aligned}$$

holds for arbitrary vector fields X, Y, Z and W .

4 ϕ -pseudo Ricci symmetric Kenmotsu manifolds with respect to quarter symmetric metric connection

Definition 4.1. A Kenmotsu manifold $M^n(\phi, \xi, \eta, g)$ ($n = 2m + 1 > 3$) is said to be ϕ -pseudo Ricci symmetric with respect to quarter symmetric metric connection if the Ricci operator Q satisfies

$$(4.1) \quad \phi^2((\bar{\nabla}_X \bar{Q})(Y)) = 2A(X)\bar{Q}Y + A(Y)\bar{Q}X + \bar{S}(Y, X)\rho.$$

for any vector field X, Y , where A is a non-zero 1-form.

In particular, if $A = 0$, then (4.1) turns into the notion of ϕ -Ricci symmetric Kenmotsu manifold with respect to quarter symmetric metric connection.

Let us take a Kenmotsu manifold $M^n(\phi, \xi, \eta, g)$ ($n = 2m + 1 > 3$), which is ϕ -pseudo Ricci symmetric with respect to quarter symmetric metric connection. Then by virtue of (2.1) it follows from (4.1) that

$$-(\bar{\nabla}_X \bar{Q})(Y) + \eta((\bar{\nabla}_X \bar{Q})(Y))\xi = 2A(X)\bar{Q}Y + A(Y)\bar{Q}X + \bar{S}(Y, X)\rho$$

from which it follows that

$$\begin{aligned}
(4.2) \quad & -g(\bar{\nabla}_X \bar{Q}(Y), Z) + \bar{S}(\bar{\nabla}_X Y, Z) + \eta((\bar{\nabla}_X \bar{Q})(Y))\eta(Z) \\
& = 2A(X)\bar{S}(Y, Z) + A(Y)\bar{S}(X, Z) + \bar{S}(Y, X)A(Z).
\end{aligned}$$

Putting $Y = \xi$ in (4.2) and using (2.4), (2.10), (2.19), (2.21) and (3.10), we get

$$\begin{aligned}
(4.3) \quad [1 - A(\xi)]S(X, Z) & = [\psi - (n - 1) - 2A(\xi)]g(X, Z) \\
& + A(\xi)g(\phi X, Z) + [(\psi + 2)A(\xi) - \psi]\eta(X)\eta(Z) \\
& + [\psi - (n - 1)][2A(X)\eta(Z) + A(Z)\eta(X)].
\end{aligned}$$

This leads to the following:

Theorem 4.1. *In a ϕ -pseudo Ricci symmetric Kenmotsu manifold with quarter symmetric metric connection the Ricci tensor is of the form (4.3).*

In particular, if $A = 0$ then from (4.3), we get

$$(4.4) \quad S(X, Z) = \{\psi - (n - 1)\}g(X, Z) - \psi\eta(X)\eta(Z),$$

which implies that the manifold under consideration is η -Einstein. This leads the following:

Corollary 4.2. *A ϕ -Ricci symmetric Kenmotsu manifold with quarter symmetric metric connection is an η -Einstein manifold.*

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