

ON THE Γ -CONVERGENCE OF LAPLACE–BELTRAMI OPERATORS IN THE PLANE

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Abstract. We show here that if f_h is a sequence of mappings of finite distortion K_h , uniformly bounded in some exponential norm, weakly converging to f in $W^{1,2}(\Omega)$, $\Omega \subset \mathbf{R}^2$, then the matrices $A(x, f_h)$ in the Beltrami operators associated to each f_h , Γ -converge, in the sense of De Giorgi, to the matrix $A(x, f)$ in the Beltrami operator associated to f .

1. Introduction

For Ω an open subset of \mathbf{R}^2 we shall study mappings $f = (f^1, f^2): \Omega \rightarrow \mathbf{R}^2$ in the Sobolev space $W^{1,2}(\Omega, \mathbf{R}^2)$. We say that f has *finite distortion* if

$$(1.1) \quad |Df(x)|^2 \leq \mathcal{K}(x)J(x, f) \quad \text{a.e.}$$

Here $|Df(x)|$ stands for the Hilbert–Schmidt norm of the differential matrix $Df(x) \in \mathbf{R}^{2 \times 2}$ and $J(x, f) = \det Df(x)$. That is,

$$|Df(x)|^2 = \sum_{i,j=1}^2 \left| \frac{\partial f^i}{\partial x_j} \right|^2 \quad \text{and} \quad J(x, f) = \frac{\partial f^1}{\partial x_1} \frac{\partial f^2}{\partial x_2} - \frac{\partial f^1}{\partial x_2} \frac{\partial f^2}{\partial x_1}.$$

The function $\mathcal{K} = \mathcal{K}(x)$ is assumed to be measurable with values in the interval $[2, \infty)$. It will be advantageous to write \mathcal{K} as

$$(1.2) \quad \mathcal{K}(x) = K(x) + \frac{1}{K(x)} \quad \text{where} \quad 1 \leq K(x) < \infty.$$

We refer to the smallest such $K(x)$ for which (1.1) holds as the *distortion function* of f . If $K(x)$ is bounded by a constant, say $1 \leq K(x) \leq K$ a.e., then we say that f is K -quasiregular. An important quantity associated to a mapping with finite distortion is the so called *distortion tensor* $G(\cdot, f): \Omega \rightarrow \mathbf{R}^{2 \times 2}$, defined by

$$(1.3) \quad G(x, f) = \begin{cases} \frac{D^t f(x) Df(x)}{J(x, f)} & \text{if } J(x, f) \neq 0, \\ I & \text{if } J(x, f) = 0, \end{cases}$$

where $D^t f(x)$ stands for the transposed differential.

The distortion inequality (1.1) reads as

$$(1.4) \quad \frac{|\xi|^2}{K(x)} \leq \langle G(x, f)\xi, \xi \rangle \leq K(x)|\xi|^2$$

and we have $\det G(x, f) = 1$ a.e.

The symmetric matrix function $G(\cdot, f)$ can be viewed as a Riemannian metric on Ω , the pullback of the Euclidean structure via the mapping f . It is obvious that f is conformal with respect to this new metric. This raises an important question: how does $G(\cdot, f)$ change with f ? We are particularly concerned with the continuity property of the map $f \rightarrow G(\cdot, f)$, since many constructions in quasiconformal geometry and elliptic PDE's rely on limiting processes. The natural convergence of the mapping $f_h: \Omega \rightarrow \mathbf{R}^2$ with finite distortion is that of the weak topology in $W^{1,2}(\Omega, \mathbf{R}^2)$. This, however, does not guarantee convergence of the matrices $G(x, f_h)$ to $G(x, f)$ in any familiar sense (compare with Example 6.1 here and also [LV]). Note that the condition $\det G(x, f_h) = 1$ is not necessarily preserved under the weak convergence of $G(x, f)$.

S. Spagnolo [S2] first realized that the proper way to overcome this difficulty is by considering the Γ -convergence of the inverse matrices

$$A(x, f) = G(x, f)^{-1}.$$

This matrix clearly verifies the bounds at (1.4) as well. See Section 3 for the definition of Γ -convergence.

Spagnolo's result dealt with the special case of K -quasiregular mappings in which $A(x, f)$ were bounded and uniformly elliptic matrices. In that case Γ -convergence is equivalent to the L^2 -convergence of solutions of the Dirichlet problem. More precisely, given a sequence $\{A_h\}$ of 2×2 matrices satisfying

$$\frac{|\xi|^2}{K} \leq \langle A_h(x)\xi, \xi \rangle \leq K|\xi|^2, \quad K \geq 1,$$

we consider the elliptic operators on a bounded open set $\Omega \subset \mathbf{R}^2$

$$\mathcal{L}_h = \operatorname{div} [A_h(x)\nabla]: W_0^{1,2}(\Omega) \rightarrow W^{-1,2}(\Omega).$$

They are certainly invertible. Following [S1], we say that $\{A_h\}$ Γ -converges to A if for every $\varphi \in W^{-1,2}(\Omega)$, $\mathcal{L}_h^{-1}(\varphi) \rightharpoonup \mathcal{L}^{-1}(\varphi)$ in $L^2(\Omega)$, where $\mathcal{L} = \operatorname{div} [A(x)\nabla]$. Later these results were generalized to the n -dimensional case by [DD].

In the present paper we extend Spagnolo's result to sequences of mappings with pointwise unbounded distortion. Our only assumption will be that the distortion functions stay bounded in the $\operatorname{EXP}_\alpha$ class for a certain $\alpha > 1$, see Section 2, for the definitions.

The main result is as follows (see Section 5):

Theorem. Let f_h converge weakly in $W^{1,2}(\Omega, \mathbf{R}^2)$ to a mapping f , and suppose that their distortion functions K_h converge to K weakly in $L^1(\Omega)$ and satisfy

$$\int_{\Omega} \exp\left(\frac{K_h(x)}{\lambda}\right)^{\alpha} dx \leq c$$

for some $\alpha > 1$, $\lambda > 0$ and $c > 0$. Then f has distortion K and

$$A(x, f_h) \xrightarrow{\Gamma_{\alpha}} A(x, f).$$

For the notion of Γ_{α} -convergence, we refer to the definition in Section 3.

In Section 6 we will relate our results to some known convergence theorems for quasiregular mappings [GMRV], [IK], [Bo].

2. Some Orlicz spaces

Let Ω be a bounded open set in \mathbf{R}^n . An Orlicz function is a nonnegative continuously increasing function $P: \mathbf{R}_+ \rightarrow \mathbf{R}_+$, verifying $P(0) = 0$ and $P(\infty) = \infty$. The Orlicz space $L^P(\Omega)$ consists of all measurable functions $\varphi: \Omega \rightarrow \mathbf{R}$ such that

$$\int_{\Omega} P(\lambda^{-1}|\varphi|) < \infty$$

for some $\lambda = \lambda(\varphi) > 0$ (see [RR]).

For $\alpha > 1$, we denote by $\text{EXP}_{\alpha}(\Omega)$ the Orlicz space with the defining function $P(t) = \exp(t^{\alpha}) - 1$. It consists of all measurable functions φ on Ω such that

$$\|\varphi\|_{\text{EXP}_{\alpha}(\Omega)} = \inf \left\{ \lambda > 0 : \int_{\Omega} \exp\left(\frac{|\varphi(x)|}{\lambda}\right)^{\alpha} dx \leq 2 \right\} < \infty.$$

Here

$$\int_{\Omega} \psi = \frac{1}{|\Omega|} \int_{\Omega} \psi = \psi_{\Omega},$$

and $\|\varphi\|_{\text{EXP}_{\alpha}(\Omega)}$ provides a norm of φ . Another space of interest to us will be the Zygmund space $L^p \log^{\beta} L(\Omega)$, with $p \geq 1$ and $\beta \geq 0$, with the defining function $P(t) = t^p \log^{\beta}(e + t)$. It consists of all measurable functions φ on Ω such that

$$\int_{\Omega} |\varphi|^p \log^{\beta} \left(e + \frac{|\varphi|}{|\varphi|_{\Omega}} \right) dx < \infty.$$

Observe that both are Banach spaces and $\text{EXP}_{\alpha}(\Omega)$ is the dual to $L^1 \log^{\beta} L$, when $\beta = 1/\alpha$.

The Luxemburg norm of a function $\varphi \in L^p \log^{\beta} L(\Omega)$ is given by

$$\|\varphi\|_{L^p \log^{\beta} L(\Omega)} = \inf \left\{ \lambda > 0 : \int_{\Omega} \left(\frac{|\varphi|}{\lambda} \right)^p \log^{\beta} \left(e + \frac{|\varphi|}{\lambda} \right) dx \leq 1 \right\}.$$

Proposition 2.1 (Generalized Hölder inequality). *Let $\alpha \geq 1$. Let $K(x) \in \text{EXP}_\alpha(\Omega)$, $\varphi \in L^2 \log^{1/\alpha} L$, and $\psi \in L^2 \log^{1/\alpha} L$. Then*

$$\left| \int_{\Omega} K(x)\varphi(x)\psi(x) \, dx \right| \leq c \|K\|_{\text{EXP}_\alpha} \|\varphi\|_{L^2 \log^{1/\alpha} L} \|\psi\|_{L^2 \log^{1/\alpha} L}.$$

For $P(t) = t^2 \log^\beta(e + t)$ we denote by $W^{1,P}(\Omega)$ the Orlicz–Sobolev space of functions $\varphi \in L^2 \log^\beta L$ whose gradient belongs to the Zygmund space $L^2 \log^\beta L$. We supply this space with the norm

$$(2.1) \quad \|\varphi\|_{W^{1,P}(\Omega)} = \|\varphi\|_{L^2 \log^\beta L(\Omega)} + \|\nabla\varphi\|_{L^2 \log^\beta L(\Omega)}.$$

3. The Γ -convergence

We denote by $\mathbf{R}_+^{2 \times 2}$ the set of symmetric 2×2 matrices A , such that $\langle A\xi, \xi \rangle \geq 0$ for all $\xi \in \mathbf{R}^2$. Consider measurable functions $A: \Omega \rightarrow \mathbf{R}_+^{2 \times 2}$ on $\Omega \subset \mathbf{R}^2$ satisfying

$$(3.1) \quad \frac{|\xi|^2}{K(x)} \leq \langle A(x)\xi, \xi \rangle \leq K(x)|\xi|^2$$

for some $1 \leq K(x) < \infty$ a.e. The smallest $K(x)$, for which the above holds, denoted by $K_A(x)$, is called the distortion function of A .

The present paper is concerned with mappings whose distortion belongs to the exponential class $\text{EXP}_\alpha(\Omega)$, $1 < \alpha \leq \infty$. For the purpose of this work, we adopt the following variant of De Giorgi’s notion of Γ -convergence ([DF]).

Definition 3.1. Let A and A_h ($h = 1, 2, \dots$) be matrix functions whose distortions K_A and K_{A_h} are uniformly bounded in the norm of $\text{EXP}_\alpha(\Omega)$. We say that $\{A_h\}$ Γ_α -converges to A if the following two conditions are verified:

(1) The inequality

$$(3.2) \quad \int_{\Omega} \langle A(x)\nabla u, \nabla u \rangle \, dx \leq \liminf_{h \rightarrow \infty} \int_{\Omega} \langle A_h(x)\nabla u_h, \nabla u_h \rangle \, dx$$

holds whenever $|\nabla u_h|, |\nabla u| \in L^2 \log^{1/\alpha} L(\Omega)$ and $u_h \rightarrow u$ in $L^2 \log^{1/\alpha} L$.

(2) For every $v \in L^2 \log^{1/\alpha} L(\Omega)$ with $|\nabla v| \in L^2 \log^{1/\alpha}(\Omega)$ there exists a sequence $v_h \in L^2 \log^{1/\alpha} L(\Omega)$ with $|\nabla v_h| \in L^2 \log^{1/\alpha} L$ such that $v_h \rightarrow v$ in $L^2 \log^{1/\alpha} L(\Omega)$ and

$$(3.3) \quad \int_{\Omega} \langle A(x)\nabla v, \nabla v \rangle = \lim_h \int_{\Omega} \langle A_h \nabla v_h, \nabla v_h \rangle.$$

Remark. The assumption that K_A and K_{A_h} belong to $\text{EXP}_\alpha(\Omega)$ is needed to guarantee that the above integrals are finite. This follows from the inequality

$$(3.4) \quad \begin{aligned} \int_{\Omega} \langle A(x)\nabla u, \nabla u \rangle \, dx &\leq \int_{\Omega} K_A(x) |\nabla u|^2 \, dx \\ &\leq c \|K_A\|_{\text{EXP}_\alpha(\Omega)} \|\nabla u\|_{L^2 \log^{1/\alpha} L(\Omega)}^2. \end{aligned}$$

If one merely assumes that K_A and $K_{A_h} \in L^1$ then one must be confined to Lipschitz functions. In this case we speak of Γ -convergence. We say that a sequence A_h of matrix functions $A_h \in L^1(\Omega, \mathbf{R}_+^{2 \times 2})$ Γ -converges to A if:

- (1) Inequality (3.2) holds whenever $u, u_h \in \text{Lip}(\Omega)$ and $u_h \rightarrow u$ in $L^2(\Omega)$;
- (2) For every $v \in \text{Lip}(\Omega)$ one can find a sequence $v_h \in \text{Lip}(\Omega)$ converging to v in $L^2(\Omega)$ satisfying (3.3).

Actually, by the general properties of Γ -convergence, conditions (1) and (2) remain true if we replace Ω by any of its open subsets.

We report here the fundamental compactness result concerning Γ -convergence [MS].

Theorem 3.1. *Let A_h be a sequence of symmetric 2×2 matrices satisfying*

$$0 \leq \langle A_h(x)\xi, \xi \rangle \leq K_h(x)|\xi|^2 \quad \text{for a.e. } x \in \Omega \text{ and } \xi \in \mathbf{R}^2.$$

Assume that $K_h \rightharpoonup K$ weakly in $L^1(\Omega)$. Then there exists a subsequence A_{h_r} Γ -converging to a symmetric matrix A . Moreover, this matrix A also satisfies

$$0 \leq \langle A(x)\xi, \xi \rangle \leq K(x)|\xi|^2.$$

In this connection it is appropriate to mention another important notion of convergence of matrix functions $A_h: \Omega \rightarrow \mathbf{R}_+^{2 \times 2}$, the so-called G -convergence. For simplicity we confine ourselves to bounded domains and to sequences such that

$$(3.5) \quad 1 \leq K_{A_h}(x) \leq K \quad \text{a.e.}$$

for $h = 1, 2, \dots$, and

$$1 \leq K_A(x) \leq K \quad \text{a.e.}$$

We recall from the introduction the elliptic operators and their inverse

$$\begin{aligned} \mathcal{L}_h &= \text{div}[A_h(x)\nabla]: W_0^{1,2}(\Omega) \rightarrow W^{-1,2}(\Omega), & \mathcal{L}_h^{-1}: W^{-1,2}(\Omega) &\rightarrow W_0^{1,2}(\Omega), \\ \mathcal{L} &= \text{div}[A(x)\nabla]: W_0^{1,2}(\Omega) \rightarrow W^{-1,2}(\Omega), & \mathcal{L}^{-1}: W^{-1,2}(\Omega) &\rightarrow W_0^{1,2}(\Omega). \end{aligned}$$

Following Spagnolo [S1], $\{A_h\}$ G -converges to A if $\mathcal{L}_h^{-1}(\varphi) \rightharpoonup \mathcal{L}^{-1}(\varphi)$ weakly in $W_0^{1,2}(\Omega)$, for every $\varphi \in W^{-1,2}(\Omega)$. We emphasize that under condition (3.5) all the above notions of convergence are equivalent, though we shall not pursue this matter here, see [MS].

4. Mappings of finite distortion and the Laplace–Beltrami operators

Let Ω be a bounded open set in \mathbf{R}^2 and $f = (f^1, f^2) \in W^{1,2}(\Omega, \mathbf{R}^2)$ be a mapping of finite distortion $K: \Omega \rightarrow [1, \infty)$, i.e. satisfying, for a.e. $x \in \Omega$,

$$(4.1) \quad |Df(x)|^2 \leq [K(x) + K^{-1}(x)]J(x, f),$$

where $J(x, f)$ is the Jacobian determinant of f . The distortion tensor $G(x, f)$ of f at x is defined in (1.3). It is easy to check that G is a symmetric matrix with $\det G(x, f) = 1$ and that (1.4) is equivalent to (4.1). In fact, for any 2×2 -matrix F with $\det F > 0$, we can consider

$$G = \frac{F^t F}{\det F}.$$

Then, obviously

$$\det G = 1.$$

Moreover, recalling the Hilbert–Schmidt norm of F ,

$$|F|^2 = \operatorname{tr} F^t F$$

the distortion inequality

$$|F|^2 \leq \left(K + \frac{1}{K} \right) \det F$$

is equivalent to

$$\operatorname{tr} G \leq K + \frac{1}{K}.$$

Let λ and $1/\lambda$ be the eigenvalues of G . Then the last inequality means that

$$\lambda + \frac{1}{\lambda} \leq K + \frac{1}{K};$$

hence $1/K \leq \lambda \leq K$.

Now we consider the inverse matrix

$$A(x, f) = G(x, f)^{-1}$$

which obviously satisfies the ellipticity condition

$$\frac{|\xi|^2}{K(x)} \leq \langle A(x, f)\xi, \xi \rangle \leq K(x)|\xi|^2.$$

Connections between mappings of finite distortion and PDEs are established via the Laplace–Beltrami operator $\mathcal{L} = \operatorname{div} [A(x, f)\nabla]$. Note that the components f^i ($i = 1, 2$) solve the equations

$$(4.2) \quad \begin{cases} \mathcal{L}[f^i] = 0, \\ \langle A(x, f)\nabla f^i, \nabla f^j \rangle = \delta_{ij}J(x, f), \end{cases}$$

see for example [BI] and [HKM]. Planar mappings with unbounded distortion have been recently studied by [D], [IS] and most recently by [MM], [BJ], [RSY], [IS]. In particular in [MM] the following higher integrability result, which will be useful to us, was established.

Theorem 4.1. *If $f \in W^{1,2}(\Omega)$ satisfies (4.1) with $K \in \text{EXP}_\alpha(\Omega)$, for certain $\alpha > 1$, then $|Df|$ belongs to $L^2 \log^{1/\alpha} L(\Omega_1)$ for any $\Omega_1 \subset\subset \Omega$ and the following inequality holds:*

$$(4.3) \quad \|Df\|_{L^2 \log^{1/\alpha} L(\Omega_1)} \leq c(\Omega_1) \|K\|_{\text{EXP}_\alpha(\Omega)} \|Df\|_{L^2(\Omega)}.$$

This is true in all dimensions, provided the exponent 2 is replaced by the dimension n .

In view of Hadamard’s inequality

$$\langle A(x, f) \nabla f^i, \nabla f^i \rangle = J(x, f) \leq \frac{1}{2} |Df(x)|^2,$$

we deduce by (4.3)

$$(4.4) \quad \|\langle A(x, f) \nabla f^i, \nabla f^i \rangle\|_{L^1 \log^{1/\alpha} L(\Omega_1)} \leq c(\Omega_1) \|K\|_{\text{EXP}_\alpha(\Omega)} \int_{\Omega} |Df|^2 dx.$$

We show here that the limit mapping f of a weakly convergent sequence of mappings f_h with finite distortion also has finite distortion. Our arguments are based on the weak continuity of the Jacobian determinant [R], [Mü] and the concept of polyconvexity. General n -dimensional results of this type have been recently obtained by F.W. Gehring and T. Iwaniec in [GI]. They adopted slightly different definition of the distortion, which for $n = 2$ reduces to

$$|Df(x)|^2 \leq 2K(x)J(x, f).$$

Theorem 4.2. *Let $f_h: \Omega \rightarrow \mathbf{R}^2$ be mappings of finite distortion $K_h(x)$:*

$$(4.5) \quad |Df_h(x)|^2 \leq \left[K_h(x) + \frac{1}{K_h(x)} \right] J(x, f_h).$$

Assume that K_h are integrable and converge weakly to K in $L^1(\Omega)$, while $f_h \rightharpoonup f$ weakly in $W^{1,2}(\Omega, \mathbf{R}^2)$. Then the above inequality remains valid for the limit map.

Proof. Let us first introduce some useful notation. Set $F = (B, E)$ where the vectors B, E are defined by

$$E = \nabla f^1, \quad B = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \nabla f^2$$

and let

$$F^+ = \frac{1}{2}(E + B), \quad F^- = \frac{1}{2}(E - B).$$

It is obvious that

$$\begin{aligned} J(x, f) &= \langle B, E \rangle = |F^+|^2 - |F^-|^2 := J(F), \\ |F|^2 &= 2(|F^+|^2 + |F^-|^2). \end{aligned}$$

Hence the distortion inequality

$$|F|^2 \leq \left(K + \frac{1}{K}\right) J(F)$$

is easily seen to be equivalent to

$$|F^-| \leq \frac{K-1}{K+1} |F^+|.$$

This, in turn, is equivalent to

$$(4.6) \quad \|F\|^2 \leq KJ(F),$$

where we have used another norm of F defined by $\|F\| = |F^+| + |F^-|$.

Now, assume that $F_h \rightharpoonup F$ weakly in L^2 and

$$\frac{\|F_h\|^2}{J(F_h)} \leq K_h$$

with $K_h \rightharpoonup K$ weakly in L^1 . The desired conclusion

$$(4.7) \quad \frac{\|F\|^2}{J(F)} \leq K$$

follows by applying the inequality

$$(4.8) \quad \frac{\|F\|^2}{J(F)} \leq \frac{\|F_h\|^2}{J(F_h)} + \frac{2\|F\|}{J(F)} (\|F\| - \|F_h\|) - \frac{\|F\|^2}{J(F)^2} [J(F) - J(F_h)].$$

The latter is immediate from the convexity of the function $(x, y) \rightarrow x^2/y$. The well-known weak continuity property of the Jacobians [R], together with the lower semicontinuity of the norm $\|\cdot\|$, imply (4.7). Here, for simplicity, we have assumed $J(F) > 0$ and $J(F_h) > 0$. To get rid of this redundant assumption one must replace $J(F)$ by the expression $J(F) + \varepsilon\|F\|$, $J(F_h)$ and then pass to the limit as $\varepsilon \rightarrow 0$.

5. The convergence theorem

In this section we consider a sequence $f_h = (f_h^1, f_h^2) \in W^{1,2}(\Omega, \mathbf{R}^2)$ of non-constant mappings with distortion $1 \leq K_h(x) < \infty$, that is

$$(5.1) \quad |Df_h(x)|^2 \leq [K_h(x) + K_h^{-1}(x)]J(x, f_h).$$

Our basic assumptions are:

(i) *There exists $\alpha > 1$ and $c_0 > 0$ such that*

$$\|K_h\|_{\text{EXP}_\alpha(\Omega)} \leq c_0 \quad \text{for } h = 1, 2, \dots$$

(ii) *$K_h \rightharpoonup K$ weakly in $L^1(\Omega)$.*

(iii) *$f_h \rightharpoonup f = (f^1, f^2)$ weakly in $W^{1,2}(\Omega, \mathbf{R}^2)$.*

By virtue of Theorem 3.1 there exists a subsequence $A_r(x) = A(x, f_{h_r})$, $r = 1, 2, \dots$, such that

$$(5.2) \quad A(x, f_{h_r}) \xrightarrow{\Gamma} A(x)$$

where $A(x)$ is a symmetric matrix field satisfying

$$(5.3) \quad 0 \leq \langle A(x)\xi, \xi \rangle \leq K(x)|\xi|^2.$$

Our aim here is to prove that $A(x)$ can be identified with $A(x, f)$, which is the inverse of the distortion tensor of f :

$$(5.4) \quad A(x, f) = [D^t f(x) Df(x)]^{-1} J(x, f).$$

As a byproduct of our proof, we improve the lower bound at (5.3)

$$K^{-1}(x)|\xi|^2 \leq \langle A(x)\xi, \xi \rangle$$

and show that actually the entire sequence $\{A(x, f_h)\}$ Γ -converges to $A(x, f)$.

Theorem 5.1. *Under the above assumptions*

$$(5.5) \quad \int_{\Omega_1} \langle A(x) \nabla f^i, \nabla f^i \rangle dx = \lim_{r \rightarrow \infty} \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla f_{h_r}^i, \nabla f_{h_r}^i \rangle dx$$

on compact subdomains $\Omega_1 \subset \Omega$, for $i = 1, 2$.

Proof. In fact, we have

$$(5.6) \quad \int_{\Omega} \langle A(x, f_h) \nabla u, \nabla u \rangle \leq \int_{\Omega} K_h |\nabla u|^2 dx \leq c \|K_h\|_{\text{EXP}_\alpha(\Omega)} \|\nabla u\|_{L^2 \log^{1/\alpha} L(\Omega)}^2 \\ \leq cc_0 \|u\|_{W^{1, L^2 \log^{1/\alpha} L}(\Omega)}^2.$$

It then follows that the functionals $(\int_{\Omega} \langle A(x, f_h) \nabla u, \nabla u \rangle dx)^{1/2}$ are equilipschitz in $W^{1, P}(\Omega)$ with $P(t) = t^2 \log^{1/\alpha}(e + t)$, a legitimate reason for passing from Γ -convergence to the stronger one

$$(5.7) \quad A(x, f_{h_r}) \xrightarrow{\Gamma_\alpha} A(x);$$

see [MS] for details.

For $i = 1, 2$ fixed, set for simplicity $u_r = f_{h_r}^i$ and $u = f^i$. Note that $u_r \rightarrow u$ in $L^2 \log^{1/\alpha} L(\Omega_1)$. Let now (v_r) be a sequence in $W^{1, P}(\Omega_1)$ such that $v_r \rightarrow u$ in $L^2 \log^{1/\alpha} L(\Omega_1)$ and

$$\lim_{r \rightarrow \infty} \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla v_r, \nabla v_r \rangle dx = \int_{\Omega_1} \langle A(x) \nabla u, \nabla u \rangle dx.$$

Let Ω' be an arbitrary compact subdomain of Ω_1 and $\varphi \in C_0^\infty(\Omega_1)$ be such that $0 \leq \varphi \leq 1$, $\varphi \equiv 1$ in Ω' ; then for every $t \in]0, 1[$

$$\begin{aligned}
& \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla u_r, \nabla u_r \rangle dx \\
& \leq \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla(\varphi v_r + (1 - \varphi)u_r), \nabla(\varphi v_r + (1 - \varphi)u_r) \rangle dx \\
& = \int_{\Omega_1} \left\langle A(x, f_{h_r}) \left\{ \frac{t}{t}(\nabla \varphi)(v_r - u_r) + \frac{1-t}{1-t}(\varphi \nabla v_r + (1 - \varphi) \nabla u_r) \right\}, \right. \\
& \quad \left. \left\{ \frac{t}{t}(\nabla \varphi)(v_r - u_r) + \frac{1-t}{1-t}(\varphi \nabla v_r + (1 - \varphi) \nabla u_r) \right\} \right\rangle dx \\
& \leq t \int_{\Omega_1} \left\langle A(x, f_{h_r}) \left\{ \frac{1}{t}(\nabla \varphi)(v_r - u_r) \right\}, \left\{ \frac{1}{t}(\nabla \varphi)(v_r - u_r) \right\} \right\rangle dx \\
& \quad + (1 - t) \int_{\Omega_1} \left\langle A(x, f_{h_r}) \left\{ \frac{1}{1-t}(\varphi \nabla v_r + (1 - \varphi) \nabla u_r) \right\}, \right. \\
& \quad \left. \left\{ \frac{1}{1-t}(\varphi \nabla v_r + (1 - \varphi) \nabla u_r) \right\} \right\rangle dx \\
& \leq \frac{1}{t} \int_{\Omega_1} K |D\varphi|^2 |v_r - u_r|^2 dx + \frac{1}{1-t} \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla v_r, \nabla v_r \rangle \varphi dx \\
& \quad + \frac{1}{1-t} \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla u_r, \nabla u_r \rangle (1 - \varphi) dx.
\end{aligned}$$

This yields

$$\begin{aligned}
(1 - t) \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla u_r, \nabla u_r \rangle dx & \leq \frac{1-t}{t} c \|v_r - u_r\|_{L^2 \log^{1/\alpha} L}^2 \cdot \|D\varphi\|_{L^\infty(\Omega_1)}^2 \\
& \quad + \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla v_r, \nabla v_r \rangle \varphi dx \\
& \quad + \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla u_r, \nabla u_r \rangle (1 - \varphi) dx.
\end{aligned}$$

The final estimate reads as

$$\begin{aligned}
\int_{\Omega_1} \langle A(x, f_{h_r}) \nabla v_r, \nabla v_r \rangle \varphi dx & \geq \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla u_r, \nabla u_r \rangle (1 - t - 1 + \varphi) dx \\
& \quad - \frac{1-t}{t} c \|D\varphi\|_{L^\infty(\Omega_1)}^2 \cdot \|v_r - u_r\|_{L^2 \log^{1/\alpha} L}^2.
\end{aligned}$$

Now, passing to the limit as $r \rightarrow \infty$, we obtain

$$\int_{\Omega_1} \langle A(x) \nabla u, \nabla u \rangle dx \geq \limsup_{r \rightarrow \infty} \int_{\Omega_1} \langle A(x, f_{h_r}) \nabla u_r, \nabla u_r \rangle (\varphi - t) dx.$$

We let the parameter t go to zero

$$\begin{aligned} \int_{\Omega_1} \langle A(x)\nabla u, \nabla u \rangle &\geq \limsup_{r \rightarrow \infty} \int_{\Omega_1} \langle A(x, f_{h_r})\nabla u_r, \nabla u_r \rangle \varphi \\ &\geq \liminf_{r \rightarrow \infty} \int_{\Omega'} \langle A(x, f_{h_r})\nabla u_r, \nabla u_r \rangle \geq \int_{\Omega'} \langle A(x)\nabla u, \nabla u \rangle. \end{aligned}$$

Since Ω' was arbitrary, we get (5.5). \square

Now we are in a position to rigorously state and prove our main result.

Theorem 5.2. *Under the conditions (i), (ii), and (iii), the limit mapping f is either constant or, if not, has finite distortion $K(x)$ and*

$$(5.8) \quad A(x, f_h) \xrightarrow{\Gamma_\alpha} A(x, f).$$

Proof. That f has finite distortion $K(x)$ was already established in Section 4. Since we wish to identify the Γ_α -limit of $A(x, f_h)$, we can assume that in (5.2) and (5.5) the convergence of the entire sequence holds.

As in the proof of Theorem 5.1, set $u_h = f_h^i$, $u = f^i$, for $i = 1, 2$ and $A_h(x) = A(x, f_h)$.

For the compact subdomain $\Omega_1 \subset \Omega$ consider step functions

$$(5.9) \quad \varphi = \sum_{j=1}^{\nu} \lambda_j \chi_{B_j}, \quad \lambda_j \geq 0,$$

where B_j are pairwise disjoint open subsets of Ω_1 such that $|\Omega_1 \setminus \bigcup_{j=1}^{\nu} B_j| = 0$.

From (5.5) it follows that

$$(5.10) \quad \liminf_{h \rightarrow \infty} \int_{\Omega_1} \langle A_h(x)\nabla u_h, \nabla u_h \rangle \varphi \, dx \geq \int_{\Omega_1} \langle A(x)\nabla u, \nabla u \rangle \varphi \, dx.$$

Moreover, by an approximation, this also holds if φ is a nonnegative continuous function on $\overline{\Omega_1}$.

Let us now prove more, namely, that (5.10) holds as equality for every continuous function φ in $\overline{\Omega_1}$, not necessarily nonnegative.

Applying (4.4), we infer that the sequence $J(x, f_h) = \langle A_h(x)\nabla u_h, \nabla u_h \rangle$ admits a subsequence weakly converging in $L^1(\Omega_1)$ to a function $E(x)$. Thus

$$(5.11) \quad \lim_{r \rightarrow \infty} \int_{\Omega_1} \langle A_{h_r}(x)\nabla u_{h_r}(x), \nabla u_{h_r}(x) \rangle \varphi(x) \, dx = \int_{\Omega_1} E(x)\varphi(x) \, dx$$

for any $\varphi \in C^0(\overline{\Omega_1})$. By (5.10) it follows

$$(5.12) \quad \int_{\Omega_1} \langle A(x)\nabla u, \nabla u \rangle \varphi(x) \, dx \leq \int_{\Omega_1} E(x)\varphi(x) \, dx.$$

Let S be a measurable subset of Ω_1 and let $(\varphi_k) \subset C^0(\overline{\Omega_1})$ be such that $\varphi_k(x) \rightarrow \chi_S(x)$ a.e. in Ω_1 . Then from the previous relation and the Lebesgue theorem it follows that

$$(5.13) \quad \int_S \langle A(x) \nabla u, \nabla u \rangle \leq \int_S E(x) dx.$$

On the other hand we deduce from (5.11) and Theorem 5.1 that

$$(5.14) \quad \int_{\Omega_1} \langle A(x) \nabla u, \nabla u \rangle dx = \int_{\Omega_1} E(x) dx.$$

Hence

$$E(x) = \langle A(x) \nabla u, \nabla u \rangle \quad \text{a.e. in } \Omega_1.$$

Therefore, we have for the whole sequence

$$(5.15) \quad \lim_{h \rightarrow \infty} \int_{\Omega_1} \langle A(x, f_h) \nabla u_h, \nabla u_h \rangle \varphi dx = \int_{\Omega_1} \langle A(x) \nabla u, \nabla u \rangle \varphi dx$$

for every $\varphi \in C^0(\overline{\Omega_1})$.

Now we recall from (4.2) that

$$(5.16) \quad \langle A(x, f_h) \nabla f_h^i(x), \nabla f_h^j(x) \rangle = J(x, f_h) \delta_{ij} \quad \text{a.e. on } \Omega, \quad i, j = 1, 2.$$

By the symmetry of the matrix $A(x, f_h)$, (5.15), (5.16) and the weak continuity property of Jacobian ([R]) we have

$$(5.17) \quad \begin{aligned} \int_{\Omega_1} \langle A(x) \nabla f^i, \nabla f^j \rangle \varphi dx &= \lim_{h \rightarrow \infty} \int_{\Omega_1} \langle A(x, f_h) \nabla f_h^i, \nabla f_h^j \rangle \varphi dx \\ &= \lim_{h \rightarrow \infty} \int_{\Omega_1} J(x, f_h) \delta_{ij} \varphi dx = \int_{\Omega_1} J(x, f) \delta_{ij} \varphi dx, \end{aligned}$$

where $\varphi \in C_0^\infty(\Omega_1)$, $i, j = 1, 2$. Since φ was arbitrary, it follows that

$$(5.18) \quad \langle A(x) \nabla f^i(x), \nabla f^j(x) \rangle = J(x, f) \delta_{ij} \quad \text{a.e. in } \Omega_1, \quad i, j = 1, 2,$$

and consequently, as $J(x, f)$ is a.e. positive,

$$(5.19) \quad A(x) = J(x, f) [Df(x)^t \cdot Df(x)]^{-1} \quad \text{a.e. in } \Omega_1.$$

Since Ω_1 was arbitrary, (5.18) holds a.e. in Ω . Hence (5.8) holds. \square

6. The Bers–Bojarski theorem

For the sake of brevity we will now confine ourselves to the particular case $K(x) = K \geq 1$ and relate our results to some classical convergence theorems for quasiregular mappings.

Let $G(x, f)$ be defined as in (1.3). No natural continuity result can be traced for the map

$$(6.1) \quad f \rightarrow G(x, f)$$

of the type obtained in the present paper for the map

$$f \rightarrow A(x, f)$$

unless we consider a convergence $f_h \rightarrow f$ stronger than weak- $W^{1,2}$; see also [LV], [D].

Example 6.1. Let $\psi_h: \mathbf{R} \rightarrow \mathbf{R}$ be a sequence of bounded measurable functions such that $0 < K^{-1} \leq \psi_h(t) \leq K$ and

$$\psi_h \rightharpoonup 1, \quad \frac{1}{\psi_h} \rightharpoonup \frac{1}{c} \quad (c \neq 1),$$

in $\sigma(L^\infty, L^1)$; for example, let us choose

$$\psi_h(t) = 1 + \delta \frac{\sin ht}{|\sin ht|} \quad (0 < \delta < 1).$$

Then, the sequence of K -quasiregular mappings

$$f_h(x_1, x_2) = \left(\int_0^{x_1} \psi_h(t) dt, x_2 \right)$$

converges locally uniformly to the identity mapping $f(x_1, x_2) = (x_1, x_2)$.

It is immediate that the distortion tensor of f_h is

$$G(x, f_h) = \begin{pmatrix} \psi_h(x_1) & 0 \\ 0 & (\psi_h(x_1))^{-1} \end{pmatrix}$$

and the distortion tensor of the limit f is

$$G(x, f) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

The sequence $G(x, f_h)$ does not converge weakly nor does it Γ -converge to the identity matrix $G(x, f)$. Actually

$$G(x, f_h) \rightharpoonup \begin{pmatrix} 1 & 0 \\ 0 & c^{-1} \end{pmatrix} \quad \text{weakly in } L^1(\Omega, \mathbf{R}^{2 \times 2}).$$

Moreover it can be proved that

$$G(x, f_h) \xrightarrow{\Gamma} \begin{pmatrix} c & 0 \\ 0 & c^{-1} \end{pmatrix}.$$

Thus, of the two matrices $A(x, f)$, $G(x, f)$ only the first one exhibits a suitable continuity behaviour as a function of f .

In the following we deduce by our results a well-known theorem of Bers–Bojarski for planar K -quasiregular mappings whose n -dimensional version has been recently proved in [GMRV] (see also [IK]). The result states that if $f_h: \Omega \subset \mathbf{R}^2 \rightarrow \mathbf{R}^2$ verify a.e. in Ω ($K \geq 1$)

$$|Df_h(x)|^2 \leq \left(K + \frac{1}{K} \right) J(x, f_h);$$

if $f_h \rightarrow f$ locally uniformly and the distortion tensors $G(x, f_h)$ defined as in (1.3) converge a.e. to $G_0(x)$ then $G_0(x) = G(x, f)$. Namely we have the following

Theorem 6.1. *Let f_h be a sequence of mappings of finite distortion $K \geq 1$ on Ω such that*

- (i) $f_h \rightharpoonup f$ in $W^{1,2}(\Omega)$,
- (ii) $G(x, f_h) \rightarrow G_0(x)$ a.e. in Ω .

Then

$$G_0(x) = G(x, f) \quad \text{a.e. in } \Omega.$$

We start with

Lemma 6.1. *Let A_h be a sequence of symmetric 2×2 matrices satisfying*

$$\frac{|\xi|^2}{K} \leq \langle A_h(x)\xi, \xi \rangle \leq K|\xi|^2 \quad \text{for a.e. } x \in \Omega.$$

If

$$A_h^{-1} \rightarrow A_0^{-1} \quad \text{in } L^1(\Omega, \mathbf{R}^{2 \times 2})$$

and

$$(6.2) \quad A_h \xrightarrow{\Gamma} A$$

then

$$A = A_0.$$

Proof. It is easy to check that

$$A_h - A_0 = A_h(A_0^{-1} - A_h^{-1})A_0.$$

So by our assumptions we deduce

$$A_h \rightarrow A_0 \quad \text{in } L^1(\Omega, \mathbf{R}^{2 \times 2}).$$

Since it is well known that strong L^1 convergence of coefficients matrices imply Γ -convergence [S1], we get

$$A_h \xrightarrow{\Gamma} A_0$$

and therefore, by (6.2)

$$A = A_0.$$

Proof of Theorem 6.1. Theorem 5.2 implies that $A(x, f_h) \xrightarrow{\Gamma} A(x, f)$. By (ii) and Vitali’s theorem we deduce

$$G(x, f_h) = A(x, f_h)^{-1} \xrightarrow{L^1} G_0(x) = A_0^{-1}(x)$$

so Lemma 6.1 implies $A(x, f) = A_0(x) = G_0^{-1}(x)$ and this means $A^{-1}(x, f) = G_0(x)$, that is $G(x, f) = G_0(x)$.

Actually, L^1 -convergence of the coefficient matrix A_h to A implies strong convergence in $W_{\text{loc}}^{1,2}$ of local solutions u_h of the equation

$$\operatorname{div} A_h(x) \nabla u_h = 0$$

to local solutions u of

$$\operatorname{div} A(x) \nabla u = 0$$

(see [S1, Theorem 5]). So, in particular, under our assumptions we deduce $f_h^i \rightarrow f^i$ in $W_{\text{loc}}^{1,2}$, for $i = 1, 2$, due to the fact that $\operatorname{div} A_h(x, f_h) \nabla f_h^i = 0$.

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