

Configurations of Points and the Symplectic Berry–Robbins Problem

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Abstract. We present a new problem on configurations of points, which is a new version of a similar problem by Atiyah and Sutcliffe, except it is related to the Lie group $\mathrm{Sp}(n)$, instead of the Lie group $\mathrm{U}(n)$. Denote by \mathfrak{h} a Cartan algebra of $\mathrm{Sp}(n)$, and Δ the union of the zero sets of the roots of $\mathrm{Sp}(n)$ tensored with \mathbb{R}^3 , each being a map from $\mathfrak{h} \otimes \mathbb{R}^3 \rightarrow \mathbb{R}^3$. We wish to construct a map $(\mathfrak{h} \otimes \mathbb{R}^3) \setminus \Delta \rightarrow \mathrm{Sp}(n)/T^n$ which is equivariant under the action of the Weyl group W_n of $\mathrm{Sp}(n)$ (the symplectic Berry–Robbins problem). Here, the target space is the flag manifold of $\mathrm{Sp}(n)$, and T^n is the diagonal n -torus. The existence of such a map was proved by Atiyah and Bielawski in a more general context. We present an explicit smooth candidate for such an equivariant map, which would be a genuine map provided a certain linear independence conjecture holds. We prove the linear independence conjecture for $n = 2$.

Key words: configurations of points; symplectic; Berry–Robbins problem; equivariant map; Atiyah–Sutcliffe problem

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1 Introduction

We introduce the relevant manifolds.

$$C_n = \{(x_1, \dots, x_n) \in (\mathbb{R}^3 \setminus \{0\})^n; x_r \neq x_s \text{ and } x_r \neq -x_s \text{ for all } 1 \leq r < s \leq n\}.$$

We remark that $C_n = (\mathfrak{h} \otimes \mathbb{R}^3) \setminus \Delta$, where \mathfrak{h} is a Cartan algebra of $\mathrm{Sp}(n)$, and Δ the union of the zero sets of the roots of $\mathrm{Sp}(n)$ tensored with \mathbb{R}^3 , each being a map from $\mathfrak{h} \otimes \mathbb{R}^3 \rightarrow \mathbb{R}^3$. We denote by F_n the following flag manifold

$$F_n = \mathrm{Sp}(n)/T^n,$$

where T^n is the diagonal n -dimensional torus in $\mathrm{Sp}(n)$. Let W_n be the Weyl group of the Lie group $\mathrm{Sp}(n)$. It is well known that W_n is a semidirect product

$$W_n = (\mathbb{Z}/(2))^n \rtimes \Sigma_n,$$

where Σ_n is the symmetric group on n elements, and where we think of $\mathbb{Z}/(2)$ as $\{-1, 1\}$ with multiplication. The group W_n acts on C_n as follows. The element $(1, \dots, -1, \dots, 1) \in (\mathbb{Z}/(2))^n$, with a -1 in the r th position only, acts on (x_1, \dots, x_n) by replacing x_r with $-x_r$, and leaving all other x_s invariant. An element $\sigma \in \Sigma_n$ acts by permuting the n coordinates.

On the other hand, the action of W_n on F_n can be described as follows: an element in $(\mathbb{Z}/(2))^n$ having -1 only in the r th position, multiplies the r th column of each point in F_n by the quaternionic structure j (leaving the other columns invariant), while a permutation σ simply permutes the columns of each point $gT^n \in F_n$.

Having described the main players in our story, we consider the following question, which is a special case of a question asked and solved by Atiyah and Bielawski for an arbitrary Lie group in [3]. Another special case, for the unitary groups, was considered earlier by Berry and Robbins in [5].

Question. *Is there for each $n \geq 2$, a continuous map $f_n : C_n \rightarrow F_n$ which is equivariant for the action of W_n ?*

Actually, as we wrote earlier, Atiyah and Bielawski have already posed and solved in [3] a more general problem for any compact Lie group G (in our case, $G = \text{Sp}(n)$). But their solution is non-elementary, as it relies on an analysis of the Nahm equations. Here we propose, similar to Atiyah [1, 2]), and Atiyah and Sutcliffe [4], a more elementary construction in the same spirit as those papers, but for the case $G = \text{Sp}(n)$, instead of $G = \text{U}(n)$.

2 The main construction

The stereographic projection is a map $s : S^2 \rightarrow \mathbb{C} \cup \{\infty\}$. Denoting by N the point with coordinates $(0, 0, 1) \in S^2$, we define the stereographic projection $s(x, y, z)$ of a point $(x, y, z) \in S^2 \setminus \{N\}$ by

$$s(x, y, z) = \frac{x + iy}{1 - z}$$

and we define $s(N) = \infty$. We first associate to each configuration $\mathbf{x} \in C_n$, n polynomials p_1, \dots, p_n of $t \in \mathbb{C}$ of degree less than or equal to $2n - 1$, each defined up to a scalar factor only. Namely, we let p_r be a polynomial having as roots the stereographic projections of

$$-\frac{x_r}{\|x_r\|}, \quad \frac{-x_r + x_s}{\|-x_r + x_s\|} \quad \text{and} \quad \frac{-x_r - x_s}{\|-x_r - x_s\|}$$

for all $s \neq r$ ($1 \leq s \leq n$), where $\|-\|$ denotes the Euclidean norm on \mathbb{R}^3 . Similarly, we introduce n other polynomials q_1, \dots, q_n , with q_r having as roots the antipodals of the roots of p_r , namely the stereographic projections of $x_r/\|x_r\|$, $(x_r + x_s)/\|x_r + x_s\|$ and $(x_r - x_s)/\|x_r - x_s\|$, for $s \neq r$.

The space of complex polynomials of degree less than or equal to $2n - 1$ has a natural structure of a left vector space over the quaternions $\mathbb{H} = \mathbb{C} \oplus j\mathbb{C}$, where j acts as follows. Writing such a polynomial as

$$p(t) = \sum_{r=0}^{2n-1} a_r t^r$$

the quaternionic structure j maps p to jp , defined by

$$(jp)(t) = \sum_{r=0}^{2n-1} a'_r t^r,$$

where

$$a'_r = (-1)^{r+1} \bar{a}_{2n-1-r}.$$

Moreover, since the roots of q_r are the antipodals of those of p_r , it follows that q_r is a constant times jp_r .

If we think of the space of polynomials above with its quaternionic structure as \mathbb{H}^n , then the p_r define n column vectors in \mathbb{H}^n . In this way we assign to any point in C_n an n -tuple of elements of \mathbb{H}^n defined up to the diagonal action of $(\mathbb{C}^*)^n$.

Suppose now that for every $x \in C_n$ the polynomials p_1, \dots, p_n are \mathbb{H} -linearly independent. Then we get a map from C_n into $\mathrm{GL}(n, \mathbb{H})/(\mathbb{C}^*)^n$. Note that W_n acts on $\mathrm{GL}(n, \mathbb{H})/(\mathbb{C}^*)^n$ as follows. An element $(1, \dots, -1, \dots, 1)$ in the $(\mathbb{Z}/(2))^n$ subgroup of W_n , with -1 only in the r th position, has the effect of mapping the equivalence class of a matrix $A \in \mathrm{GL}(n, \mathbb{H})$ to the equivalence class of the matrix obtained from A by replacing its r th column by its image under j . On the other hand, an element σ in the Σ_n subgroup of W_n maps the equivalence class of A to the equivalence class of the matrix obtained from A by permuting its columns via σ . With this action, the map becomes W_n -equivariant, since replacing x_r by $-x_r$ has the effect of replacing p_r by jp_r , and a permutation of the n coordinates of x corresponds to the same permutation of the n polynomials p_1, \dots, p_n . If we follow this map by a W_n -equivariant map from $\mathrm{GL}(n, \mathbb{H})/(\mathbb{C}^*)^n$ into $\mathrm{Sp}(n)/T^n$, then this solves the symplectic Berry–Robbins problem (assuming that p_1, \dots, p_n are \mathbb{H} -linearly independent). Such a map can be obtained for example using the quaternionic polar decomposition. More specifically, the map from $\mathrm{GL}(n, \mathbb{H})$ into $\mathrm{Sp}(n)$ mapping A to $A(\sqrt{A^*A})^{-1}$, where $*$ denotes the quaternionic conjugate transpose, descends to a W_n -equivariant map from $\mathrm{GL}(n, \mathbb{H})/(\mathbb{C}^*)^n$ into $\mathrm{Sp}(n)/T^n$.

Motivated by the above discussion, we make the following conjecture.

Conjecture 1. *Given any $\mathbf{x} \in C_n$, the $2n$ polynomials p_r and q_r ($1 \leq r \leq n$) are linearly independent over \mathbb{C} .*

Note that the conjecture is equivalent to the \mathbb{H} -linear independence of p_1, \dots, p_n . We remark further that our construction is also naturally equivariant under the action of $\mathrm{SO}(3)$, which acts on \mathbb{R}^3 in the natural way (which is equivalent to the adjoint action of $\mathrm{SO}(3)$ on its Lie algebra $\mathfrak{so}(3)$), and acts on the polynomials p_r and q_r , which are only defined up to a (non-zero) scalar factor, via the induced action of its double cover $\mathrm{SU}(2)$ on $S^{2n-1}H$, where H is the natural irreducible complex two-dimensional representation space of $\mathrm{SU}(2)$. In the following section, we define a natural determinant function, and then, we prove the conjecture above for $n = 2$.

3 A determinant function

Let t_r^\pm and $t_{rs}^{\pm\pm} \in \mathbb{C}P^1$ be the stereographic projections of the normalizations of the following vectors, respectively

$$\pm x_r \quad (1 \leq r \leq n) \quad \text{and} \quad \pm x_r \pm x_s \quad (1 \leq r, s \leq n \quad \text{and} \quad r \neq s).$$

The Hopf map $h : \mathbb{C}^2 \setminus \{0\} \rightarrow \mathbb{C}P^1$ is the natural projection map mapping $v \in \mathbb{C}^2 \setminus \{0\}$ to its \mathbb{C}^* -orbit, where \mathbb{C}^* acts on $\mathbb{C}^2 \setminus \{0\}$ by scalar multiplication.

We then choose lifts $\mathbf{u}_r^\pm = (u_r^\pm, v_r^\pm)$ and $\mathbf{u}_{rs}^{\pm\pm} = (u_{rs}^{\pm\pm}, v_{rs}^{\pm\pm}) \in \mathbb{C}^2 \setminus \{0\}$ of these roots under the Hopf map h . Since $\mathbf{u}_{sr}^{-\sigma, -\tau}$ and $\mathbf{u}_{rs}^{\sigma, \tau}$ are both lifts of the same point, we require that they be equal. We then form the polynomials p_r and q_r as the following products

$$p_r(t) = (u_r^- t - v_r^-) \prod_{s \neq r} (u_{rs}^- t - v_{rs}^-) \prod_{s \neq r} (u_{rs}^- t - v_{rs}^-),$$

$$q_r(t) = (u_r^+ t - v_r^+) \prod_{s \neq r} (u_{rs}^+ t - v_{rs}^+) \prod_{s \neq r} (u_{rs}^+ t - v_{rs}^+).$$

Thus in particular, once the lifts are chosen, the polynomials p_r and q_r are determined uniquely, in other words, the scalar factor of each of them gets fixed. We now form the complex $2n$ by $2n$ matrix

$$M = (p_1, q_1, \dots, p_n, q_n)$$

having the coefficients of p_r and q_r as column vectors. One then defines the quantity

$$P = \prod_r \det(\mathbf{u}_r^-, \mathbf{u}_r^+) \prod_{r < s} (\det(\mathbf{u}_{rs}^-, \mathbf{u}_{rs}^+) \det(\mathbf{u}_{rs}^{--}, \mathbf{u}_{rs}^{++}))^2.$$

Then the determinant function

$$D(x_1, \dots, x_n) = \det(M)/P$$

is independent of the choices of lifts, and is thus well defined. Similar to the Atiyah–Sutcliffe determinant, D is actually invariant under the action of the Weyl group W_n on C_n , and is also invariant under scaling, and rotations in \mathbb{R}^3 . However, unlike the Atiyah–Sutcliffe determinant, it is not invariant under translations, because the origin in \mathbb{R}^3 plays here a special role, and it is always real-valued, because it is the determinant of a $2n$ by $2n$ complex matrix, which represents an n by n quaternionic matrix, and thus is always real (indeed, the complex conjugate of such a $2n$ by $2n$ complex matrix can be shown to be in the same conjugacy class as the complex matrix itself, so they must have equal determinants).

4 The case $n = 2$

We consider here the case $n = 2$. We have two points $x_1, x_2 \in \mathbb{R}^3$ such that $x_1 \neq x_2$ and $x_1 \neq -x_2$. Using a rotation in \mathbb{R}^3 , we can assume that they both lie on the xy -plane. We think of the xy -plane as the complex plane. Using a rotation in the xy -plane and scaling, we can further assume that $x_1 = 1$ and we then let z be the complex number representing x_2 in the xy -plane. Thus $z \neq 1$ and $z \neq -1$. We let

$$A = \frac{z-1}{|z-1|}, \quad B = -\frac{z+1}{|z+1|}, \quad g = -\frac{z}{|z|}.$$

We then have

$$-64D = \begin{vmatrix} AB & 1 & ABg & 1 \\ AB - A - B & \bar{A} + \bar{B} - 1 & -Ag + Bg - AB & -\bar{A} + \bar{B} + \bar{g} \\ 1 - A - B & \bar{A}\bar{B} - \bar{A} - \bar{B} & A - B - g & -\bar{A}\bar{g} + \bar{B}\bar{g} - \bar{A}\bar{B} \\ 1 & -\bar{A}\bar{B} & 1 & -\bar{A}\bar{B}\bar{g} \end{vmatrix}.$$

We then multiply the second column by $-AB$ and add it to the first column, and we multiply the second column by $-ABg$ and add it to the third column, and finally subtract the second column from the fourth one, and get, after expanding the determinant along the first row:

$$64D = \begin{vmatrix} 2(AB - A - B) & -2Ag + ABg - AB & -2\bar{A} + 1 + \bar{g} \\ 0 & -2g + Bg - B + Ag + A & -2\bar{A}\bar{B} + \bar{A}(1 - \bar{g}) + \bar{B}(1 + \bar{g}) \\ 2 & 1 + g & \bar{A}\bar{B}(1 - \bar{g}) \end{vmatrix}.$$

Taking a 2 out from the first column, and using elementary column operations using the first column in order to make the entries in the (3, 2) and (3, 3) positions vanish, we get

$$\begin{aligned} 32D &= \begin{vmatrix} AB - A - B & -2AB + A(1 - g) + B(1 + g) & 2\bar{g} - \bar{A}(1 + \bar{g}) + \bar{B}(1 - \bar{g}) \\ 0 & A(1 + g) - B(1 - g) - 2g & -2\bar{A}\bar{B} + \bar{A}(1 - \bar{g}) + \bar{B}(1 + \bar{g}) \\ 1 & 0 & 0 \end{vmatrix} \\ &= |-2AB + A(1 - g) + B(1 + g)|^2 + |A(1 + g) - B(1 - g) - 2g|^2 \\ &= 8 + 2|1 - g|^2 + 2|1 + g|^2 - 2B(1 - \bar{g}) - 2\bar{B}(1 - g) - 2A(1 + \bar{g}) - 2\bar{A}(1 + g) + \dots \\ &\quad + 2(\bar{A}\bar{B} - \bar{A}B)(\bar{g} - g) - 2A\bar{g}(1 + g) - 2\bar{A}g(1 + \bar{g}) + 2B\bar{g}(1 - g) + 2\bar{B}g(1 - \bar{g}). \end{aligned}$$

Using

$$|1 + g|^2 + |1 - g|^2 = 4$$

we get

$$16D = 8 - 2A(1 + \bar{g}) - 2B(1 - \bar{g}) + A(1 + \bar{g})\bar{B}(1 - g) - 2\bar{A}(1 + g) - 2\bar{B}(1 - g) + \bar{A}(1 + g)B(1 - \bar{g}).$$

If we let

$$(w_1, w_2) = \frac{1}{2}(w_1\bar{w}_2 + w_2\bar{w}_1), \quad \det(w_1, w_2) = \frac{i}{2}(w_1\bar{w}_2 - w_2\bar{w}_1),$$

we can then write

$$4D = 2 - (A, 1 + g) - (B, 1 - g) - \Im(g) \det(A, B),$$

where $\Im(g)$ denotes the imaginary part of g . Therefore, using the definitions of A , B and g in terms of z , we get

$$4D = 2 + \left(\frac{z-1}{|z-1|}, \frac{z}{|z|} - 1 \right) + \left(\frac{z+1}{|z+1|}, \frac{z}{|z|} + 1 \right) + 2 \frac{(\Im z)^2}{|z||z-1||z+1|}.$$

Writing $z = re^{i\theta}$, and after simplification, we get

$$4D = 2 + \frac{(1+r)(1-\cos(\theta))}{|z-1|} + \frac{(1+r)(1+\cos(\theta))}{|z+1|} + \frac{2r(1-\cos(\theta))(1+\cos(\theta))}{|z-1||z+1|}.$$

Using $1+r \geq |z+1|$ and $1+r \geq |z-1|$, and that $1+\cos(\theta)$ and $1-\cos(\theta)$ are both nonnegative,

$$4D \geq 4 + \frac{2r(1-\cos(\theta))(1+\cos(\theta))}{|z-1||z+1|}.$$

Thus

$$D \geq 1 + \frac{r \sin^2(\theta)}{2|z-1||z+1|}.$$

This proves the inequality $D \geq 1$, which in turns implies the linear independence conjecture, for $n = 2$. Moreover, it is not too difficult to see that equality $D = 1$ occurs if and only if $\sin(\theta) = 0$, or, in other words, if the two points x_1 and x_2 lie on the same line through the origin.

5 A stronger conjecture

Similar to Conjecture 2 in [4], we make the following conjecture

Conjecture 2. *For any $n \geq 2$ and for any $\mathbf{x} \in C_n$, we have $D(\mathbf{x}) \geq 1$.*

The author did some numerical testing for this conjecture for $n \leq 10$, by computing $D(x)$ for a number of pseudo-randomly generated configurations of points, and found that in all these cases, the conjecture was verified, thus gathering some numerical evidence for the above conjecture.

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