

($m+1$)-DIMENSIONAL SPACELIKE PARALLEL p_i -EQUIDISTANT RULED SURFACES IN THE MINKOWSKI SPACE R_1^n

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Abstract. In this paper, spacelike parallel p_i -equidistant ruled surfaces in 3-dimensional Minkowski space $R_1^3, [1]$ are generalized to n -dimensional Minkowski space R_1^n . Then some characteristic results related with algebraic invariants of shape operator of the $(m+1)$ -dimensional spacelike parallel p_i -equidistant ruled surfaces are given in the Minkowski space R_1^n .

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1. Introduction

We shall assume throughout that all manifolds, maps, vector fields, etc... are differentiable of class C^∞ . First of all, we give some properties of a general submanifold M in R_1^n , [2]. Suppose that \bar{D} is the Levi-Civita connection of R_1^n , while D is the Levi-Civita connection of M . If X and Y are vector fields of M and if V is the second fundamental tensor of M , then we find by decomposing $\bar{D}_X Y$ into a tangent and normal component

$$(1.1) \quad \bar{D}_X Y = D_X Y + V(X, Y).$$

The equation (1.1) is called *Gauss Equation*.

If ξ is a normal vector field on M , we find the *Weingarten Equation* by decomposing $\bar{D}_X \xi$ in a tangent and a normal component as

$$(1.2) \quad \bar{D}_X \xi = -A_\xi(X) + D_X^\perp \xi.$$

A_ξ determines at each point a self-adjoint linear map and D^\perp is a metric connection in the normal bundle $\chi^\perp(M)$. We use the same notation A_ξ for the linear map and the matrix of the linear map.

If the metric tensor of R_1^n is denoted by \langle, \rangle , we have

$$(1.3) \quad \langle V(X, Y), \xi \rangle = \langle Y, A_\xi(X) \rangle.$$

Let M be an m -dimensional semi-Riemannian manifold in R_1^n and A_ξ be a linear map. If $\zeta \in \chi^\perp(M)$ is a normal unit vector at the point $P \in M$, then

$$(1.4) \quad G(P; \zeta) = \det A_\zeta$$

is called the *Lipschitz-Killing curvature* of M at P in the direction ζ .

If $\xi_1, \xi_2, \dots, \xi_{n-m}$ constitute an orthonormal base field of the normal bundle $\chi^\perp(M)$, then the *mean curvature* H is given by

$$(1.5) \quad H = \sum_{j=1}^{n-m} \frac{\text{tr} A_{\xi_j}}{\dim M} \xi_j.$$

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For every $X_i \in \chi(M)$, $1 \leq i \leq 4$ the 4th order covariant tensor field defined by R as

$$(1.6) \quad R(X_1, X_2, X_3, X_4) = \langle X_1, R(X_3, X_4)X_2 \rangle$$

is called the *Riemannian curvature tensor field* and its value at a point $P \in M$ is called *Riemannian curvature* of M at P.

Let Π be a tangent plane of M at P. For all $X_P, Y_P \in \Pi$, the real valued function K defined by

$$(1.7) \quad K(X_P, Y_P) = \frac{\langle R(X_P, Y_P)X_P, Y_P \rangle}{\langle X_P, X_P \rangle \langle Y_P, Y_P \rangle - \langle X_P, Y_P \rangle^2}$$

is called the *sectional curvature function*. $K(X_P, Y_P)$ is called the *sectional curvature* of M at P.

Let R be the Riemannian curvature tensor of M. The *Ricci curvature tensor field* S of M is by

$$(1.8) \quad S(X, Y) = \sum_{i=1}^m \varepsilon_i \langle R(e_i, X)Y, e_i \rangle,$$

where $\{e_1, e_2, \dots, e_m\}$ is a system of orthonormal base of $T_M(P)$ and the value of $S(X, Y)$ at $P \in M$ is called *the Ricci curvature*, where

$$\varepsilon_i = \langle e_i, e_i \rangle = \begin{cases} -1, & \text{if } e_i \text{ timelike} \\ 1, & \text{if } e_i \text{ spacelike} \end{cases}$$

The *scalar curvature* r_{sk} of M is given by

$$(1.9) \quad r_{sk} = \sum_{i \neq j} K(e_i, e_j) = 2 \sum_{i < j} K(e_i, e_j).$$

Let $\{\xi_1, \xi_2, \dots, \xi_{n-m}\}$ be an orthonormal base field of $\chi^\perp(M)$. Then the *scalar normal curvature* K_N of M is given by

$$(1.10) \quad K_N = \sum_{i,j=1}^{n-m} \overline{M} (A_{\xi_i} A_{\xi_j} - A_{\xi_j} A_{\xi_i}),$$

where \overline{M} is defined as $\overline{M}(A) = \sum_{i,j} (a_{ij})^2$, $A = [a_{ij}]$.

2. The Curvatures Of (m+1)-Dimensional Spacelike Parallel p_i -Equidistant Ruled Surfaces in the Minkowski Space R_1^n

I

Let α and α^* be two unit-speed spacelike curves in R_1^n and let $\{V_1, V_2, \dots, V_k\}$ and $\{V_1^*, V_2^*, \dots, V_k^*\}$, $k \leq n$, be their Frenet frames at the points $\alpha(t)$ and $\alpha^*(t^*)$, respectively. Let \mathbf{M} and \mathbf{M}^* be (m+1)-dimensional generalized spacelike ruled surfaces in R_1^n and $E_m(t)$ and $E_m(t^*)$, $1 \leq m \leq k-2$, be spacelike generating spaces of \mathbf{M} and \mathbf{M}^* , respectively. Then \mathbf{M} and \mathbf{M}^* can be given by the following parametric form:

$$(2.1) \quad M : X(t, u_1, \dots, u_m) = \alpha(t) + \sum_{i=1}^m u_i V_i(t),$$

$$\text{rank} \{X_t, X_{u_1}, \dots, X_{u_m}\} = m + 1,$$

$$(2.2) \quad M^* : X^*(t^*, u_1^*, \dots, u_m^*) = \alpha^*(t^*) + \sum_{i=1}^m u_i^* V_i^*(t^*),$$

$$\text{rank} \left\{ X_{t^*}^*, X_{u_1^*}^*, \dots, X_{u_m^*}^* \right\} = m + 1,$$

where $\{V_1, V_2, \dots, V_m\}$ and $\{V_1^*, V_2^*, \dots, V_m^*\}$ are the orthonormal basis of $E_m(t)$ and $E_m(t^*)$, respectively.

Definition 2.1. Let M and M^* be (m+1)-dimensional two spacelike ruled surfaces and p_i be the distances between the (k-1)-dimensional osculator planes obtained by the vanishing the i^{th} term from

$$Sp \{V_1, V_2, \dots, V_i, \dots, V_k\} \text{ and } Sp \{V_1^*, V_2^*, \dots, V_i^*, \dots, V_k^*\}.$$

If

1) V_1 and V_1^* are parallel,

2) the distances $p_i, 1 \leq i \leq k$, between the (k-1)-dimensional osculator planes at the corresponding points of α and α^* are constant, then the pair of ruled surfaces M and M^* are called the (m+1)-dimensional spacelike parallel p_i -equidistant ruled surfaces.

From now on M and M^* will be assumed (m+1)-dimensional spacelike parallel p_i -equidistant ruled surfaces.

The following theorem can be given by means of definition 2.1 without proof:

Theorem 2.1. i) The Frenet frames $\{V_1, V_2, \dots, V_k\}$ and $\{V_1^*, V_2^*, \dots, V_k^*\}$ are equivalent at the corresponding points on α and α^* .

ii) For the curvatures k_i and k_i^* of α and α^* , respectively, we have

$$k_i^* = \frac{dt}{dt^*} k_i, \quad 1 \leq i < k.$$

Theorem 2.2. The relation between the base curves of M and M^* , is

$$\alpha^* = \alpha + p_1 V_1 + p_2 V_2 + \dots + p_m V_m + \varepsilon_{m+1} p_{m+1} V_{m+1} + \varepsilon_{m+2} p_{m+2} V_{m+2} + \dots + \varepsilon_k p_k V_k.$$

Proof. Since the vector $\alpha\alpha^*$ can be written as:

$$\alpha\alpha^* = a_1 V_1 + a_2 V_2 + \dots + a_m V_m + a_{m+1} V_{m+1} + \dots + a_k V_k, \quad a_i \in IR, \quad 1 \leq i \leq k,$$

we find

$$\begin{cases} \langle \alpha\alpha^*, V_i \rangle = a_i, & 1 \leq i \leq m \\ \langle \alpha\alpha^*, V_i \rangle = a_i \varepsilon_i, & \varepsilon_i = \langle V_i, V_i \rangle, \quad m+1 \leq i \leq k \end{cases} .$$

Also, the distance between the osculator planes is

$$p_i = \begin{cases} |a_i|, & 1 \leq i \leq m \\ |a_i \varepsilon_i|, & m+1 \leq i \leq k \end{cases}$$

and thus

$$\alpha^* = \alpha + p_1 V_1 + p_2 V_2 + \dots + p_m V_m + \varepsilon_{m+1} p_{m+1} V_{m+1} + \varepsilon_{m+2} p_{m+2} V_{m+2} + \dots + \varepsilon_k p_k V_k$$

□

Theorem 2.3. *All the asymptotic and tangential bundles of \mathbf{M} and \mathbf{M}^* are equal.*

Proof. Let $A(t)$ and $A(t^*)$ be asymptotic bundles of \mathbf{M} and \mathbf{M}^* , respectively, then we have

$$A(t) = Sp\{V_1, V_2, \dots, V_m, V'_1, V'_2, \dots, V'_m\}$$

and

$$A(t^*) = Sp\{V_1^*, V_2^*, \dots, V_m^*, V_1^{*'}, V_2^{*'}, \dots, V_m^{*'}\}.$$

Similarly, if $T(t)$ and $T(t^*)$ are the tangential bundles of \mathbf{M} and \mathbf{M}^* , respectively, then from the definition of the tangential bundles we also have

$$T(t) = Sp\{V_1, V_2, \dots, V_m, V'_1, V'_2, \dots, V'_m, \alpha'\}$$

and

$$T(t^*) = Sp\{V_1^*, V_2^*, \dots, V_m^*, V_1^{*'}, V_2^{*'}, \dots, V_m^{*'}, \alpha^{*'}\}.$$

From the definition 2.1 and Theorem 2.1

$$A(t) = A(t^*) = T(t) = T(t^*)$$

is obtained. □

II

In this part, we will study the matrices A_{ξ_j} and $A_{\xi_j^*}$, $1 \leq j \leq n - m - 1$, of \mathbf{M} and \mathbf{M}^* , respectively. Using equation (2.1) and (2.2), we can write

$$X_t = V_1 + \sum_{i=1}^m u_i V'_i, \quad X_{u_1} = V_1, \dots, \quad X_{u_m} = V_m$$

and

$$X_{t^*} = V_1^* + \sum_{i=1}^m u_i^* V_i^{*'}, \quad X_{u_1^*} = V_1^*, \dots, \quad X_{u_m^*} = V_m^*.$$

Thus, we obtain the orthonormal bases $\{V_1, \dots, V_{m+1}\}$ and $\{V_1^*, \dots, V_{m+1}^*\}$ of \mathbf{M} and \mathbf{M}^* , respectively. If we take the orthonormal bases of the normal bundles \mathbf{M}^\perp and $\mathbf{M}^{*\perp}$ as

$$\{\xi_1, \dots, \xi_{k-m-1}, \dots, \xi_{n-m-1}\} \text{ and } \{\xi_1^*, \dots, \xi_{k-m-1}^*, \dots, \xi_{n-m-1}^*\},$$

respectively, then we get the orthonormal bases

$$\{V_1, \dots, V_{m+1}, \xi_1, \dots, \xi_{k-m-1}, \dots, \xi_{n-m-1}\}$$

and

$$\{V_1^*, \dots, V_{m+1}^*, \xi_1^*, \dots, \xi_{k-m-1}^*, \dots, \xi_{n-m-1}^*\}$$

of R_1^n at $P \in \mathbf{M}$ and at $P^* \in \mathbf{M}^*$, respectively, where $\xi_i = V_{m+1+i}$ and $\xi_j^* = V_{m+1+j}^*$, $1 \leq i \leq k - m - 1$. Let the connections of R_1^n , \mathbf{M} and \mathbf{M}^* be \bar{D} , D and D^* , respectively. Then we have the following Weingarten equations:

$$(2.3) \begin{cases} \bar{D}_{V_1} \xi_j = \sum_{i=1}^{m+1} a_{1i}^j V_i + \sum_{q=1}^{n-m-1} b_{1q}^j \xi_q, & 1 \leq j \leq n - m - 1 \\ \vdots \\ \bar{D}_{V_{m+1}} \xi_j = \sum_{i=1}^{m+1} a_{(m+1)i}^j V_i + \sum_{q=1}^{n-m-1} b_{(m+1)q}^j \xi_q, & 1 \leq j \leq n - m - 1. \end{cases}$$

So, the matrix A_{ξ_j} , $1 \leq j \leq n - m - 1$, can be written as:

$$(2.4) A_{\xi_j} = - \begin{bmatrix} a_{11}^j & a_{12}^j & \cdots & a_{1(m+1)}^j \\ \vdots & \vdots & & \vdots \\ a_{(m+1)1}^j & a_{(m+1)2}^j & \cdots & a_{(m+1)(m+1)}^j \end{bmatrix}.$$

Since α is a spacelike curve and $E_m(t)$ is a spacelike subspace, we obtain

$$(2.5) \begin{cases} a_{11}^j = \langle \bar{D}_{V_1} \xi_j, V_1 \rangle & \cdots & a_{(m+1)1}^j = \langle \bar{D}_{V_{m+1}} \xi_j, V_1 \rangle \\ \vdots & & \vdots \\ a_{1m}^j = \langle \bar{D}_{V_1} \xi_j, V_m \rangle & \cdots & a_{(m+1)m}^j = \langle \bar{D}_{V_{m+1}} \xi_j, V_m \rangle \\ a_{1(m+1)}^j = \varepsilon_{m+1} \langle \bar{D}_{V_1} \xi_j, V_{m+1} \rangle & \cdots & a_{(m+1)(m+1)}^j = \varepsilon_{m+1} \langle \bar{D}_{V_{m+1}} \xi_j, V_{m+1} \rangle \end{cases}$$

where $\varepsilon_{m+1} = \langle V_{m+1}, V_{m+1} \rangle$.

Similarly, for any normal vector field ξ^* on \mathbf{M}^* , we can write

$$\bar{D}_{X^*} \xi^* = -A_{\xi^*}(X^*) + D_{X^*}^* \xi^*.$$

Then we obtain:

$$(2.6) \begin{cases} \bar{D}_{V_1^*} \xi_j^* = \sum_{i=1}^{m+1} c_{1i}^j V_i^* + \sum_{q=1}^{n-m-1} d_{1q}^j \xi_q^*, & 1 \leq j \leq n - m - 1 \\ \vdots \\ \bar{D}_{V_{m+1}^*} \xi_j^* = \sum_{i=1}^{m+1} c_{(m+1)i}^j V_i^* + \sum_{q=1}^{n-m-1} d_{(m+1)q}^j \xi_q^*, & 1 \leq j \leq n - m - 1. \end{cases}$$

Thus, we obtain the matrix $A_{\xi_j^*}$, $1 \leq j \leq n - m - 1$, as follows:

$$(2.7) A_{\xi_j^*} = - \begin{bmatrix} c_{11}^j & c_{12}^j & \cdots & c_{1(m+1)}^j \\ \vdots & \vdots & & \vdots \\ c_{(m+1)1}^j & c_{(m+1)2}^j & \cdots & c_{(m+1)(m+1)}^j \end{bmatrix}, \quad 1 \leq j \leq n - m - 1.$$

Since α^* is a spacelike curve and $E_m(t^*)$ is a spacelike subspace, we get

$$(2.8) \begin{cases} c_{11}^j = \langle \bar{D}_{V_1^*} \xi_j^*, V_1^* \rangle & \cdots & c_{(m+1)1}^j = \langle \bar{D}_{V_{m+1}^*} \xi_j^*, V_1^* \rangle \\ \vdots & & \vdots \\ c_{1m}^j = \langle \bar{D}_{V_1^*} \xi_j^*, V_m^* \rangle & \cdots & c_{(m+1)m}^j = \langle \bar{D}_{V_{m+1}^*} \xi_j^*, V_m^* \rangle \\ c_{1(m+1)}^j = \varepsilon_{m+1} \langle \bar{D}_{V_1^*} \xi_j^*, V_{m+1}^* \rangle & \cdots & c_{(m+1)(m+1)}^j = \varepsilon_{m+1} \langle \bar{D}_{V_{m+1}^*} \xi_j^*, V_{m+1}^* \rangle \end{cases}$$

where $\varepsilon_{m+1} = \langle V_{m+1}^*, V_{m+1}^* \rangle$. Hence, the following theorems can be given:

Theorem 2.4. *If \mathbf{M} is $(m+1)$ -dimensional spacelike ruled surface in R_1^n , then*

$$A_{\xi_1} = A_{V_{m+2}} = \begin{bmatrix} 0 & \cdots & 0 & \varepsilon_{m+1}k_{m+1} \\ 0 & \cdots & 0 & 0 \\ \vdots & & \vdots & \vdots \\ 0 & \cdots & 0 & 0 \end{bmatrix}_{(m+1) \times (m+1)} \quad \text{and } A_{\xi_j} = 0, \\ 2 \leq j \leq n - m - 1.$$

Theorem 2.5. *If \mathbf{M}^* is $(m+1)$ -dimensional spacelike ruled surface in R_1^n , then*

$$A_{\xi_1^*} = A_{V_{m+2}^*} = \begin{bmatrix} 0 & \cdots & 0 & \varepsilon_{m+1}k_{m+1}^* \\ 0 & \cdots & 0 & 0 \\ \vdots & & \vdots & \vdots \\ 0 & \cdots & 0 & 0 \end{bmatrix}_{(m+1) \times (m+1)} \quad \text{and } A_{\xi_j^*} = 0, \\ 2 \leq j \leq n - m - 1.$$

Theorem 2.6. *Let \mathbf{M} and \mathbf{M}^* be $(m+1)$ -dimensional spacelike parallel p_i -equidistant ruled surfaces in R_1^n . For the matrices of \mathbf{M} and \mathbf{M}^* , we have*

$$A_{\xi_1^*} = \frac{dt}{dt^*} A_{\xi_1} \quad , \quad A_{\xi_j^*} = A_{\xi_j} = 0 \quad , \quad 2 \leq j \leq n - m - 1.$$

Theorem 2.7. *The Lipschitz-Killing curvatures of \mathbf{M} and \mathbf{M}^* in all normal directions are zero.*

Proof. From the definition of Lipschitz-Killing curvature in the direction of ξ_j , we can write

$$G(P, \xi_j) = \det A_{\xi_j} = 0 \quad \text{for all } P \in \mathbf{M}, \quad 1 \leq j \leq n - m - 1.$$

Similarly, the Lipschitz-Killing curvature in the direction of ξ_j^* of \mathbf{M}^* , we get

$$G(P^*, \xi_j^*) = \det A_{\xi_j^*} = 0 \quad , \quad 1 \leq j \leq n - m - 1 \quad , \quad \text{for all } P^* \in \mathbf{S}^*. \quad \square$$

Theorem 2.8. *\mathbf{M} and \mathbf{M}^* are minimal and the scalar normal curvatures of \mathbf{M} and \mathbf{M}^* are zero.*

Proof. If H and K_N (H^* and K_{N^*}) are the mean curvature vector and the scalar normal curvature of \mathbf{M} (\mathbf{M}^*), then from Theorem 2.4 and Theorem 2.5, we have

$$H = H^* = 0 \quad \text{and} \quad K_N = K_{N^*} = 0.$$

Thus, \mathbf{M} and \mathbf{M}^* are the minimal ruled surfaces. \square

III

If X and Y are vector fields and V is the second fundamental form of \mathbf{M} , then from (1.2) and (1.3) we can write

$\langle \bar{D}_X Y, \xi \rangle = \langle V(X, Y), \xi \rangle = \langle A_\xi(X), Y \rangle$, $\xi \in \mathbf{M}^\perp$ and

$$V(X, Y) = - \sum_{j=1}^{n-m-1} \langle Y, \bar{D}_X \xi_j \rangle \xi_j.$$

So, for the Frenet vectors V_i and V_j , $1 \leq i, j \leq m+1$, we obtain

$$V(V_i, V_j) = - \sum_{s=1}^{n-m-1} \langle V_j, \bar{D}_{V_i} \xi_s \rangle \xi_s, \quad 1 \leq i, j \leq m+1.$$

Thus, from (2.3) we get

$$V(V_i, V_j) = - \sum_{s=1}^{n-m-1} \varepsilon_j a_{ij}^s \xi_s.$$

Using Theorem 2.4, we have

$$(2.9) \quad \begin{cases} V(V_1, V_{m+1}) = - \sum_{s=1}^{n-m-1} \varepsilon_{m+1} a_{1(m+1)}^s \xi_s = \varepsilon_{m+1}^2 k_{m+1} V_{m+2} \\ V(V_i, V_j) = - \sum_{s=1}^{n-m-1} \varepsilon_j a_{ij}^s \xi_s = 0, \quad 1 \leq i, j \leq m+1. \end{cases}$$

Similarly, if X^* and Y^* are vector fields and V^* is the second fundamental form of \mathbf{M}^* , then from equations (1.2) and (1.3) we have

$\langle \bar{D}_{X^*} Y^*, \xi^* \rangle = \langle V^*(X^*, Y^*), \xi^* \rangle = \langle A_{\xi^*}(X^*), Y^* \rangle$, $\xi^* \in M^{*\perp}$

and

$$V^*(X^*, Y^*) = - \sum_{j=1}^{n-m-1} \langle Y^*, \bar{D}_{X^*} \xi_j^* \rangle \xi_j^*.$$

For the Frenet vectors V_i^* and V_j^* , $1 \leq i, j \leq m+1$, we have

$$V^*(V_i^*, V_j^*) = - \sum_{s=1}^{n-m-1} \langle V_j^*, \bar{D}_{V_i^*} \xi_s^* \rangle \xi_s^* \quad , \quad 1 \leq i, j \leq m+1$$

and from equation (2.6) we get

$$V^*(V_i^*, V_j^*) = - \sum_{s=1}^{n-m-1} \varepsilon_j c_{ij}^s \xi_s^* \quad , \quad 1 \leq i, j \leq m+1.$$

Using Theorem 2.5, we obtain

$$(2.10) \quad \begin{cases} V^*(V_1^*, V_{m+1}^*) = \varepsilon_{m+1}^2 k_{m+1}^* V_{m+2}^* , \\ V^*(V_i^*, V_j^*) = 0 \quad 1 \leq i, j \leq m+1 \end{cases}$$

and from Theorem 2.1 we get

$$(2.11) \quad \begin{cases} V^*(V_1^*, V_{m+1}^*) = \frac{dt}{dt^*} V(V_1, V_{m+1}) , \\ V^*(V_i^*, V_j^*) = V(V_i, V_j) = 0 \quad 1 \leq i, j \leq m+1. \end{cases}$$

Thus, the following theorems can be given:

Theorem 2.9. V_1 and V_{m+1} are conjugate vectors iff V_1^* and V_{m+1}^* are conjugate vectors.

Theorem 2.10. *i)* For the Riemannian curvature of \mathbf{M} in two dimensional direction spanned by V_i and V_j , we have

$$K(V_1, V_{m+1}) = \varepsilon_{m+1}\varepsilon_{m+2}(k_{m+1})^2 \text{ and } K(V_i, V_j) = 0, \quad 1 \leq i, j \leq m+1, i \neq j.$$

ii) For the Riemannian curvature of \mathbf{M}^* in two dimensional direction spanned by V_i^* and V_j^* , we have

$$K(V_1^*, V_{m+1}^*) = \varepsilon_{m+1}\varepsilon_{m+2}(k_{m+1})^2 \text{ and } K(V_i^*, V_j^*) = 0, \quad 1 \leq i, j \leq m+1, i \neq j.$$

Theorem 2.11. For the Riemannian curvatures of \mathbf{M} and \mathbf{M}^*

$$\begin{cases} K(V_1^*, V_{m+1}^*) = \left(\frac{dt}{dt^*}\right)^2 K(V_1, V_{m+1}) , \\ K(V_i^*, V_j^*) = K(V_i, V_j) = 0 \quad , \quad 1 \leq i, j \leq m+1, i \neq j \end{cases}$$

are valid.

Theorem 2.12. If $S(V_i, V_i)$, and r_{sk} ($S(V_i^*, V_i^*)$ and r_{sk}^*), $1 \leq i \leq m+1$, are the Ricci and scalar curvatures of $\mathbf{M}(\mathbf{M}^*)$, then we have

$$S(V_i^*, V_i^*) = S(V_i, V_i) = 0, \quad 1 \leq i \leq m,$$

$$S(V_{m+1}^*, V_{m+1}^*) = \left(\frac{dt}{dt^*}\right)^2 S(V_{m+1}, V_{m+1}),$$

$$r_{sk} = 2\varepsilon_{m+2}S(V_{m+1}, V_{m+1}) ,$$

$$r_{sk}^* = 2\varepsilon_{m+2}S(V_{m+1}^*, V_{m+1}^*),$$

$$r_{sk}^* = \left(\frac{dt}{dt^*}\right)^2 r_{sk} \quad .$$

Proof. For the Ricci curvature in the direction V_i , $1 \leq i \leq m+1$, of \mathbf{M} , we can write

$$\begin{aligned} S(V_i, V_i) &= \sum_{j=1}^{m+1} \varepsilon_j \langle R(V_j, V_i)V_i, V_j \rangle, \quad \varepsilon_j = \langle V_j, V_j \rangle \\ &= \sum_{j=1}^{m+1} \varepsilon_j \{ \langle V(V_j, V_i), V(V_j, V_i) \rangle - \langle V(V_j, V_j), V(V_i, V_i) \rangle \}. \end{aligned}$$

Using equation (2.9), we have

$$(2.12) \begin{cases} S(V_{m+1}, V_{m+1}) = \varepsilon_{m+2}(k_{m+1})^2, \quad \varepsilon_{m+2} = \langle V_{m+2}, V_{m+2} \rangle \\ S(V_i, V_i) = 0, \quad 1 \leq i \leq m. \end{cases}$$

For the scalar curvature of \mathbf{M} , we get

$$r_{sk} = \sum_{i \neq j} K(V_i, V_j) = 2 \sum_{i < j} K(V_i, V_j).$$

From Theorem 2.10, we obtain

$$(2.13) \quad r_{sk} = 2K(V_1, V_{m+1}) = 2\varepsilon_{m+1}\varepsilon_{m+2}(k_{m+1})^2.$$

If we use equation (2.12) we have

$$(2.14) \quad r_{sk} = 2\varepsilon_{m+2}S(V_{m+1}, V_{m+1}), \quad \varepsilon_{m+2} = \langle V_{m+2}, V_{m+2} \rangle.$$

Similarly, for the Ricci curvature in the direction V_i^* , $1 \leq i \leq m + 1$, of \mathbf{M}^* we get

$$(2.15) \begin{cases} S(V_{m+1}^*, V_{m+1}^*) = \varepsilon_{m+1}(k_{m+1}^*)^2, \quad \varepsilon_{m+1} = \langle V_{m+1}^*, V_{m+1}^* \rangle \\ S(V_i^*, V_i^*) = 0, \quad 1 \leq i \leq m. \end{cases}$$

Also, for the scalar curvature of \mathbf{M}^* , we find

$$(2.16) \quad r_{sk}^* = 2K(V_1^*, V_{m+1}^*) = 2\varepsilon_{m+2}S(V_{m+1}^*, V_{m+1}^*), \quad \varepsilon_{m+2} = \langle V_{m+2}^*, V_{m+2}^* \rangle.$$

From Theorem 2.1 we have

$$S(V_{m+1}^*, V_{m+1}^*) = \left(\frac{dt}{dt^*}\right)^2 S(V_{m+1}, V_{m+1}) \text{ and } r_{sk}^* = \left(\frac{dt}{dt^*}\right)^2 r_{sk}. \quad \square$$

Theorem 2.13. Let $X = \sum_{i=1}^{m+1} a_i V_i$, $Y = \sum_{i=1}^{m+1} b_i V_i \in \mathbf{M}$. \mathbf{M} is totally geodesic iff $V(V_1, V_{m+1}) = 0$ or $a_1 b_{m+1} = 0$.

Proof. Since

$$V(X, Y) = \sum_{i,j=1}^{m+1} a_i b_j V(V_i, V_j),$$

using equation (2.9), we get

$$(2.17) \quad V(X, Y) = a_1 b_{m+1} V(V_1, V_{m+1}).$$

Thus, the definition of totally geodesic completes the proof. \square

We can give the following corollary:

Corollary 2.1. If $a_1 b_{m+1} \neq 0$ and \mathbf{M} is totally geodesic, then \mathbf{M}^* is totally geodesic and the Riemannian curvatures of \mathbf{M} and \mathbf{M}^* in the two dimensional direction spanned by V_i and V_j , $1 \leq i, j \leq m + 1$, $i \neq j$, are zero.

References

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