

CHARACTERIZATIONS OF SOME NEAR-CONTINUOUS FUNCTIONS AND NEAR-OPEN FUNCTIONS

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(Received April 7, 1986)

ABSTRACT. A subset N of a topological space is defined to be a θ -neighborhood of x if there exists an open set U such that $x \in U \subseteq \text{Cl } U \subseteq N$. This concept is used to characterize the following types of functions: weakly continuous, θ -continuous, strongly θ -continuous, almost strongly θ -continuous, weakly δ -continuous, weakly open and almost open functions. Additional characterizations are given for weakly δ -continuous functions. The concept of θ -neighborhood is also used to define the following types of open maps: θ -open, strongly θ -open, almost strongly θ -open, and weakly δ -open functions.

KEY WORDS AND PHRASES. θ -neighborhood, weakly continuous function, θ -continuous function, strongly θ -continuous function, almost strongly θ -continuous function, weakly δ -continuous function, weakly open function, almost open function, θ -open function, strongly θ -open function, almost strongly θ -open function, weakly δ -open function.
1980 AMS SUBJECT CLASSIFICATION CODE. 54C10.

1. INTRODUCTION.

Near-continuity has been investigated by many authors including Levine [1], Long and Herrington [2], Noiri [3], and Rose [4]. Near-openness has been developed by Rose [5] and Singal and Singal [6]. The purpose of this note is to characterize several types of near-continuity and near-openness in terms of the concept of θ -neighborhood. These characterizations clarify both the nature of these functions and the relationships among them. Additional characterizations of weak δ -continuity are given. The concept of θ -neighborhood also leads to the definition of several new types of near-open functions.

2. DEFINITIONS AND NOTATION.

The symbols X and Y denote topological spaces with no separation axioms assumed unless explicitly stated. Let U be a subset of a space X . The closure of U and the interior of U are denoted by $\text{Cl } U$ and $\text{Int } U$ respectively. The set U is said to be regular open (regular closed) if $U = \text{Int } \text{Cl } U$ ($U = \text{Cl } \text{Int } U$). The θ -closure (δ -closure) (Velicko [7]) of U is the set of all x in X such that every closed neighborhood (the interior of every closed neighborhood) of x intersects

U . The θ -closure and the δ -closure of U are denoted by $Cl_{\theta}U$ and $Cl_{\delta}U$ respectively. The set U is called θ -closed (δ -closed) if $U = Cl_{\theta}U$ ($U = Cl_{\delta}U$). A set is said to be θ -open (δ -open) if its complement is θ -closed (δ -closed). For a given space X the collection of all θ -open sets and the collection of all δ -open sets both form topologies. The space X with the θ -open (δ -open) topology will be signified by X_{θ} (X_{δ}).

DEFINITION 1. A function $f: X \rightarrow Y$ is said to be weakly continuous (Levine [1]) (θ -continuous (Fomin [8]), strongly θ -continuous (Long and Herrington [2]), almost strongly θ -continuous (Noiri and Kang [9]), weakly δ -continuous (Baker [10])) if for each $x \in X$ and each open neighborhood V of $f(x)$, there exists an open neighborhood U of x such that $f(U) \subseteq Cl V$ ($f(Cl U) \subseteq Cl V$, $f(Cl U) \subseteq V$, $f(Cl U) \subseteq Int Cl V$, $f(Int Cl U) \subseteq Cl V$).

DEFINITION 2. A function $f: X \rightarrow Y$ is said to be weakly open (Rose [5]) (almost open (Rose [5])) provided that for each open subset U of X , $f(U) \subseteq Int f(Cl U)$ ($f(U) \subseteq Int Cl f(U)$).

DEFINITION 3. A subset N of a space X is said to be a θ -neighborhood (δ -neighborhood) of a point x in X if there exists an open set U such that $x \in U \subseteq Cl U \subseteq N$ ($x \in U \subseteq Int Cl U \subseteq N$).

Note that a θ -neighborhood is not necessarily a neighborhood in the θ -topology, but a δ -neighborhood is a neighborhood in the δ -topology.

3. NEAR-CONTINUOUS FUNCTIONS.

The main results can be paraphrased as follows: weak continuity corresponds to " f^{-1} (θ -neighborhood) = neighborhood"; θ -continuity corresponds to " f^{-1} (θ -neighborhood) = θ -neighborhood"; strong θ -continuity corresponds to " f^{-1} (neighborhood) = θ -neighborhood"; almost strong θ -continuity corresponds to " f^{-1} (δ -neighborhood) = θ -neighborhood", and weak δ -continuity corresponds to " f^{-1} (θ -neighborhood) = δ -neighborhood".

THEOREM 1. A function $f: X \rightarrow Y$ is weakly continuous if and only if for each x in X and each θ -neighborhood N of $f(x)$, $f^{-1}(N)$ is a neighborhood of x .

PROOF. Assume f is weakly continuous. Let $x \in X$ and let N be a θ -neighborhood of $f(x)$. Then there exists an open set V such that $f(x) \in V \subseteq Cl V \subseteq N$. Since f is weakly continuous, there exists an open neighborhood U of x such that $f(U) \subseteq Cl V \subseteq N$. Thus $x \in U \subseteq f^{-1}(N)$ and hence $f^{-1}(N)$ is a neighborhood of x .

Assume for each $x \in X$ and each θ -neighborhood N of x that $f^{-1}(N)$ is a neighborhood of x . Let $x \in X$ and let V be an open neighborhood of $f(x)$. Since $Cl V$ is a θ -neighborhood of $f(x)$, $f^{-1}(Cl V)$ is a neighborhood of x . Thus there is an open set U for which $x \in U \subseteq f^{-1}(Cl V)$ and $f(U) \subseteq Cl V$ which proves f is weakly continuous.

THEOREM 2. A function $f: X \rightarrow Y$ is θ -continuous if and only if for each x in X and each θ -neighborhood N of $f(x)$, $f^{-1}(N)$ is a θ -neighborhood of x .

PROOF. Assume $f: X \rightarrow Y$ is θ -continuous. Let $x \in X$ and let N be a θ -neighborhood of $f(x)$. Then there exists an open set V for which $f(x) \in V \subseteq \text{Cl} V \subseteq N$. By the θ -continuity of f , there exists an open neighborhood U of x such that $f(\text{Cl} U) \subseteq \text{Cl} V \subseteq N$. Thus $x \in U \subseteq \text{Cl} U \subseteq f^{-1}(N)$ and hence $f^{-1}(N)$ is a θ -neighborhood of x .

Assume for each x in X and for each θ -neighborhood N of $f(x)$ that $f^{-1}(N)$ is a θ -neighborhood of x . Let $x \in X$ and let V be an open neighborhood of $f(x)$. Since $\text{Cl} V$ is a θ -neighborhood of $f(x)$, $f^{-1}(\text{Cl} V)$ is a θ -neighborhood of x . Hence there exists an open set U for which $x \in U \subseteq \text{Cl} U \subseteq f^{-1}(\text{Cl} V)$. That is, $f(\text{Cl} U) \subseteq \text{Cl} V$ and thus f is θ -continuous.

The proof of the following theorem is similar to that of Theorem 2 and is omitted.

THEOREM 3. A function $f: X \rightarrow Y$ is strongly θ -continuous if and only if for each x in X and each neighborhood N of $f(x)$, $f^{-1}(N)$ is a θ -neighborhood of x .

THEOREM 4. A function $f: X \rightarrow Y$ is almost strongly θ -continuous if and only if for each x in X and each δ -neighborhood N of $f(x)$, $f^{-1}(N)$ is a θ -neighborhood of x .

PROOF. Assume $f: X \rightarrow Y$ is almost strongly θ -continuous. Let $x \in X$ and let N be a δ -neighborhood of $f(x)$. Then there exists an open set V such that $f(x) \in V \subseteq \text{Int Cl} V \subseteq N$. Since f is almost strongly θ -continuous, there exists an open neighborhood U of x for which $f(\text{Cl} U) \subseteq \text{Int Cl} V \subseteq N$. Then $x \in U \subseteq \text{Cl} U \subseteq f^{-1}(N)$ which proves that $f^{-1}(N)$ is a θ -neighborhood of x .

Assume for each $x \in X$ and each δ -neighborhood N of $f(x)$ that $f^{-1}(N)$ is a θ -neighborhood of x . Let $x \in X$ and let V be an open neighborhood of $f(x)$. Since $\text{Int Cl} V$ is a δ -neighborhood of $f(x)$, $f^{-1}(\text{Int Cl} V)$ is a θ -neighborhood of x . Hence there is an open set U such that $x \in U \subseteq \text{Cl} U \subseteq f^{-1}(\text{Int Cl} V)$. That is, $f(\text{Cl} U) \subseteq \text{Int Cl} V$ and hence f is almost strongly θ -continuous.

THEOREM 5. A function $f: X \rightarrow Y$ is weakly δ -continuous if and only if for each $x \in X$ and each θ -neighborhood N of $f(x)$, $f^{-1}(N)$ is a δ -neighborhood of x .

The proof of this theorem is similar to that of Theorem 4. The following theorem gives additional characterizations of weak δ -continuity. These results are analogous to those obtained by Noiri and Kang in [9] for almost strongly θ -continuous functions.

LEMMA. Let X be a space and $H \subseteq X$. Then

- (a) $\text{Cl}_\theta H = \{x \in X: \text{every } \theta\text{-neighborhood of } x \text{ intersects } H\}$ and
- (b) $\text{Cl}_\delta H = \{x \in X: \text{every } \delta\text{-neighborhood of } x \text{ intersects } H\}$.

The proof follows easily from the definitions.

THEOREM 6. For $f: X \rightarrow Y$ the following statements are equivalent:

- (a) $f: X \rightarrow Y$ is weakly δ -continuous.
- (b) For each $H \subseteq X$, $f(\text{Cl}_\delta H) \subseteq \text{Cl}_\theta f(H)$.
- (c) For each $K \subseteq Y$, $\text{Cl}_\delta f^{-1}(K) \subseteq f^{-1}(\text{Cl}_\theta K)$.
- (d) $f: X_\delta \rightarrow Y$ is weakly continuous.

PROOF. (a) \Rightarrow (b). Let $H \subseteq X$ and let $y \in f(Cl_\delta H)$. Then there exists an x in $Cl_\delta H$ such that $y = f(x)$. Let N be a θ -neighborhood of $f(x)$. By Theorem 5 $f^{-1}(N)$ is a δ -neighborhood of x . Since $x \in Cl_\delta H$, $f^{-1}(N) \cap H \neq \emptyset$. That is, $N \cap f(H) \neq \emptyset$. Hence $y \in Cl_\theta f(H)$. Thus $f(Cl_\delta H) \subseteq Cl_\theta f(H)$.

(b) \Rightarrow (c). Let $K \subseteq Y$. By (b) $f(Cl_\delta f^{-1}(K)) \subseteq Cl_\theta f(f^{-1}(K)) \subseteq Cl_\theta K$. Thus $Cl_\delta f^{-1}(K) \subseteq f^{-1}(Cl_\theta K)$.

(c) \Rightarrow (d). Let $x \in X$ and let V be an open neighborhood of $f(x)$. Since $Cl V$ is a θ -neighborhood of $f(x)$, $f(x) \notin Cl_\theta (Y - Cl V)$. Hence $x \notin f^{-1}(Cl_\theta (Y - Cl V))$.

By (c) $x \notin Cl_\delta f^{-1}(Y - Cl V)$. Thus there is a neighborhood U of x such that $(Int Cl U) \cap f^{-1}(Y - Cl V) = \emptyset$. Then $f(Int Cl U) \subseteq Cl V$. Since $Int Cl U$ is a regular open, $f: X_S \rightarrow Y$ is weakly continuous.

(d) \Rightarrow (a). Let $x \in X$ and let V be an open neighborhood of $f(x)$. Since $f: X_S \rightarrow Y$ is weakly continuous, there exists a δ -open set W containing x such that $f(W) \subseteq Cl V$. Then there is a regular open set U for which $x \in U \subseteq W$. Then $f(Int Cl U) = f(U) \subseteq f(W) \subseteq Cl V$ and hence f is weakly δ -continuous.

4. NEAR-OPEN FUNCTIONS.

In this section weak openness and almost openness are characterized in terms of the concept of θ -neighborhood.

THEOREM 7. A function $f: X \rightarrow Y$ is weakly open if and only if for each $x \in X$ and each θ -neighborhood N of x , $f(N)$ is a neighborhood of $f(x)$.

PROOF. Assume f is weakly open. Let $x \in X$ and let N be a θ -neighborhood of x . Then there is an open set U such that $x \in U \subseteq Cl U \subseteq N$. Since f is weakly open $f(x) \in f(U) \subseteq Int f(Cl U) \subseteq Int f(N)$. Hence $f(N)$ is a neighborhood of $f(x)$.

Assume for each x in X and each θ -neighborhood N of x that $f(N)$ is a neighborhood of $f(x)$. Let U be an open set in X . Suppose $x \in U$. Since $Cl U$ is a θ -neighborhood of x , $f(Cl U)$ is a neighborhood of $f(x)$. Hence $f(x) \in Int f(Cl U)$. Thus $f(U) \subseteq Int f(Cl U)$ and f is weakly open.

The proof of the following theorem is similar and is omitted.

THEOREM 8. A function $f: X \rightarrow Y$ is almost open if and only if for each $x \in X$ and each neighborhood N of x , $Cl f(N)$ is a θ -neighborhood of $f(x)$.

Theorem 7 and the characterizations of near-continuous functions in Section 3 suggest the following definitions of near-open functions.

DEFINITION 4. A function $f: X \rightarrow Y$ is said to be θ -open (strongly θ -open, almost strongly θ -open, weakly δ -open) if for each $x \in X$ and each θ -neighborhood (neighborhood, δ -neighborhood, θ -neighborhood) N of x , $f(N)$ is a θ -neighborhood (θ -neighborhood, θ -neighbourhood, δ -neighborhood) of $f(x)$.

The following theorems characterize these near-open functions in terms of the closure and interior operators. Since the proofs are all similar, only the first theorem is proved.

THEOREM 9. A function $f: X \rightarrow Y$ is θ -open if and only if for each $x \in X$ and each open neighborhood U of x , there exists an open neighborhood V of $f(x)$ such that $Cl V \subseteq f(Cl U)$.

PROOF. Assume $f: X \rightarrow Y$ is θ -open. Let $x \in X$ and let U be an open neighborhood of x . Since $f(Cl U)$ is a θ -neighborhood of $f(x)$, there exists an open set V such that $f(x) \in V \subseteq Cl V \subseteq f(Cl U)$.

Assume that for each $x \in X$ and each open neighborhood U of x there exists an open neighborhood V of $f(x)$ for which $Cl V \subseteq f(Cl U)$. Let $x \in X$ and let N be a θ -neighborhood of x . Then there is an open set U for which $x \in U \subseteq Cl U \subseteq N$. There exists an open set V such that $f(x) \in V \subseteq Cl V \subseteq f(Cl U) \subseteq f(N)$. Hence $f(N)$ is a θ -neighborhood of $f(x)$ and f is θ -open.

THEOREM 10. A function $f: X \rightarrow Y$ is strongly θ -open if and only if for each $x \in X$ and each open neighborhood U of x , there exists an open neighborhood V of $f(x)$ such that $Cl V \subseteq f(U)$.

THEOREM 11. A function $f: X \rightarrow Y$ is almost strongly θ -open if and only if for each $x \in X$ and each open neighborhood U of x there exists an open neighborhood V of $f(x)$ such that $Cl V \subseteq f(Int Cl U)$.

THEOREM 12. A function $f: X \rightarrow Y$ is weakly δ -open if and only if for each $x \in X$ and each open neighborhood U of x , there exists an open neighborhood V of $f(x)$ such that $Int Cl V \subseteq f(Cl U)$.

We have the following implications: almost open \leq st. θ -open \Rightarrow almost st. θ -open \Rightarrow θ -open \Rightarrow weak δ -open \Rightarrow weak open. The following examples show that these implications are not reversible.

EXAMPLE 1. Let $X = \{a, b\}$, $T_1 = \{X, \phi, \{a\}\}$, $Y = \{a, b, c\}$, and $T_2 = \{Y, \phi, \{a\}, \{a, b\}\}$. The inclusion mapping: $(X, T_1) \rightarrow (Y, T_2)$ is weak open but not weak δ -open.

In the next example the space (Y, T_2) is from Example 2.2 in Noiri and Kang [9].

EXAMPLE 2. Let (X, T_1) be as in Example 1. Let $Y = \{a, b, c, d\}$ and $T_2 = \{Y, \phi, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{a, b, c\}, \{a, c, d\}\}$. The inclusion mapping: $(X, T_1) \rightarrow (Y, T_2)$ is weak δ -open, but not θ -open.

EXAMPLE 3. Let (Y, T_2) be as in Example 2. The identity mapping: $(Y, T_2) \rightarrow (Y, T_2)$ is θ -open but not almost strongly θ -open.

EXAMPLE 4. Let $X = \{a, b, c\}$, $T_1 = \{X, \phi, \{a\}, \{a, c\}\}$ and $T_2 = \{X, \phi, \{a\}, \{c\}, \{a, c\}, \{a, b\}\}$. The identity mapping: $(X, T_1) \rightarrow (X, T_2)$ is almost strongly θ -open and almost open, but not strongly θ -open.

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