A PROBLEM OF THERMAL SHOCK WITH THERMAL RELAXATION

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(Received May 12, 1988)

ABSTRACT. The problem of a semi-infinite medium subjected to thermal shock on its plane boundary is solved using the generalized theory of thermoelasticity. The expressions for temperature, strain and stress are presented. The results are exhibited graphically and compared with previous results.

KEY WORDS AND PHRASES. Generalized theory, relaxation time, Lame's elastic constants, diffusion equation, relaxation constant.

1980 AMS SUBJECT CLASSIFICATION CODE. 73U.

1. INTRODUCTION.

Thermoelastic problems are solved using the governing dynamical equations for the displacement and temperature. These equations are two partial differential equations.

Equation of motion:

\[ p \dddot{u}_i = (\lambda + \mu) u_{j,i,j} + \mu u_{i,j,j} - (3\lambda + 2\mu) \alpha T_{i} \cdot \tag{1.1} \]

Equation of energy:

\[ k \dot{T}_{i,i} = \rho C_v \dot{T} + (3\lambda + 2\mu) \alpha T_0 \cdot \tag{1.2} \]

The first equation is of wave type and the other is of diffusion type. For an isotropic, homogeneous elastic body subjected to a shock, the latter equation shows that the disturbance will be felt instantaneously at distances far from its source. As the equations are coupled this effect will be felt in both temperature and displacement. Such a behavior is physically inadmissible and contradicts the existing theory of heat conduction.

Many researchers, for example Morse and Feshbach [1], Boley [2], Baumlister and Hamill [3] have discussed this paradox and suggested some modifications in the governing equations. Lord and Shulman [4] proposed the Generalized theory of thermoelasticity, where the time lag needed for the onset of thermal wave-relaxation
time is considered and is well-known as the modified coupled heat conduction equation. Based on this modified theory, considerable work is being done by many authors (Fox [5], Ignaczak [6], Sherief and Anwar [7], and Choudhuri and Sain [8]).

Here the problem of an isotropic, homogeneous half-space subjected to thermal shock on its plane boundary is solved using the Laplace transform technique. The equations concerning the generalized theory of thermoelasticity are used to solve the said problem. The boundary condition for temperature is in the form of exponential heating, a more realistic situation. After effecting the Laplace inversion, the expressions for temperature, strain and stress are obtained. As a special case, the results due to Danilovskaya [9] for step-type boundary conditions and that of Sternburg et al [10] for ramp type boundary condition can be obtained. Further by setting relaxation constant to zero, the results due to Daimaruya et al [11] are obtained.

2. FORMULATION OF THE PROBLEM.

Consider an isotropic homogeneous half space, subjected to a thermal disturbance on its boundary. The governing equations of the generalized theory of thermoelasticity for the one dimensional case, are

\[
k \frac{\partial^2 T}{\partial x^2} = \rho C_e \frac{\partial T}{\partial t} + \tau_o \frac{\partial^2 T}{\partial t^2} + (3\lambda + 2\mu) \frac{\partial^2 u}{\partial x^2} + \tau_o \frac{\partial^2 u}{\partial x^2} \tag{2.1}\]

\[
\sigma_{xx} = (\lambda + 2\mu) \frac{\partial u}{\partial x} - (3\lambda + 2\mu) \alpha (T-T_0) \tag{2.2}\]

\[
(\lambda + 2\mu) \frac{\partial^2 u}{\partial x^2} - (3\lambda + 2\mu) \alpha \frac{\partial T}{\partial x} = \rho \frac{\partial^2 u}{\partial t^2} \tag{2.3}\]

where \(k, \rho, C_e, \alpha, \tau_o\) are thermal conductivity, density, specific heat, coefficient of linear thermal expansion and the relaxation time, respectively. \(\lambda\) and \(\mu\) are the well known Lamé's elastic constants. Here \(T, \sigma_{xx},\) and \(u\) are temperature, stress and displacement, respectively.

The initial and boundary conditions are

\[
T(x,0) = T_0, \quad x > 0 \tag{2.4}\]

\[
u(x,0) = 0 = (\frac{\partial u}{\partial t})_{t=0}, \quad (\frac{\partial u}{\partial t})_{t=0} = 0 \tag{2.4}\]

\[
T(0,t) = T_o \left[1-\exp(-t/t_o)\right] \tag{2.5}\]

\[
u'(0,t) = \frac{(3\lambda + 2\mu)\alpha T_o}{(\lambda + 2\mu)} \left[1 - \exp (-t/t_o)\right]. \tag{2.5}\]

In the above, \(T_o\) and \(t_o\) are constants. The step type boundary condition is obtained when \(t_o = 0\), i.e. \(T(0,t) = H(t)\), and the ramp type boundary condition is obtained by expanding the exponential type and neglecting the higher order terms. Here \(H(t)\) is Heaviside unit step function.

The regularity boundary conditions are

\[
T(x,t), u(x,t), \sigma_{xx}(x,t) \rightarrow 0 \text{ as } x \rightarrow \infty. \tag{2.6}\]
Introducing the following non-dimensional variables

\[ z = \left( \frac{\lambda + 2\mu}{\rho} \right)^{1/2} \frac{\rho C_e}{k} x, \quad y = \frac{\lambda + 2\mu}{\rho} \frac{\rho C_e}{k} t, \]

\[ \theta = \frac{T - T_0}{T_o}, \quad \Sigma = \sigma_{xx} \left( 3\lambda + 2\mu \right) \alpha T_0 \]

\[ U = \left[ \rho \left( \frac{\lambda + 2\mu}{\rho} \right)^{3/2} \frac{1}{(3\lambda + 2\mu)\alpha T_0} \frac{\rho C_e}{k} \right] u \]

for distance, time, temperature, stress, and displacement respectively in equations (2.1) - (2.3), we get

\[ \theta'' = \theta' - \beta \theta = \ddot{e} \left( \ddot{u}' + \dot{u}' \dot{\theta}' \right), \]

\[ U'' = \theta' = \ddot{e}, \quad (2.8abc) \]

\[ \Sigma = U' - \Theta \]

where 'dot' and 'dash' denote differentiation with respect to \( y \) and \( z \) respectively and

\[ \beta = \left( \frac{\lambda + 2\mu}{\rho} \right) \frac{\rho C_e}{k} \left( \frac{3\lambda + 2\mu}{\rho C_e} \right) \frac{\alpha T_0}{\tau_o} \]

Here \( \beta \) and \( \ddot{e} \) are the relaxation constant and thermoelastic coupling constant, respectively.

In (2.8a), the strain acceleration term \( \ddot{u}' \) can be ignored as the product \( \ddot{e} \beta \) is much less than \( \ddot{e} \) or \( \beta \) in the intermediate and room temperature.

Now our initial and boundary conditions (2.4) - (2.6) reduce to

\[ \Theta(z,0) = U(z,0) = \frac{\partial U}{\partial y} |_{y=0} = 0 = \frac{\partial \Theta}{\partial y} |_{y=0}, \]

\[ \Theta(0,y) = \exp (-y/\tau_o'), \quad U'(0,y) = 1 - \exp (-y/\tau_o'), \]

\[ \Theta(z,y), U(z,y), \Sigma(z,y) \rightarrow 0 \quad \text{as} \quad z \rightarrow \infty \]

where

\[ \tau_o' = \left( \frac{\lambda + 2\mu}{\rho} \right) \frac{\rho C_e}{k} T_o. \]

3. SOLUTION OF THE PROBLEM.

In order to obtain the solutions for the temperature (\( \Theta \)) and strains (\( U' \)), we first eliminate \( U, \Theta \) from the first two equations of (2.8), namely

\[ \theta''' - (1 + \beta) \theta'' - (1 + \ddot{e}) \theta' - \dot{\theta} + \theta \beta = 0 \quad (3.1) \]

\[ \dddot{u}' = (1 + \beta) \dddot{u}' - (1 + \ddot{e}) \dddot{u}' + \dot{u}' + \beta \dddot{u'} = 0. \quad (3.2) \]

Applying the Laplace transform to (3.1), (3.2) and (2.9), one obtains
\[ \ddot{\theta}'' = p[p(l+\varepsilon) + (1+\varepsilon)] \ddot{\theta}'' + p^2(p+\beta p^2) \ddot{\theta} = 0 \]  
(3.3)

\[ \dddot{U}'' = p[p(1+\beta) + (1+\varepsilon)] \dddot{U}'' + p^2(p+\beta p^2) \ddot{U} = 0. \]

Here \( \ddot{\theta}, \ddot{U} \) are Laplace transforms of \( \theta \) and \( U \) respectively and \( p \) is the transform parameter, and

\[ \ddot{\theta}(0, p) = -\tau'_{o} p_{o} \]
\[ \ddot{U}(0, p) = 1/p p_{o} \]  
(3.4)

\[ \dddot{\theta}(z, 0) = \dddot{U}(z, 0) = 0. \]

In the above,

\[ p_{o} = p \tau'_{o} + 1. \]

From (3.3) and (3.4), we get

\[ \ddot{\theta} = A_{1} \exp(-\alpha_{1} z) + A_{2} \exp(-\alpha_{2} z) \]
\[ \ddot{U} = B_{1} \exp(-\alpha_{1} z) + B_{2} \exp(-\alpha_{2} z) \]  
(3.5)

where

\[ A_{1,2} = \pm D [e + \tau'_{o} (\alpha_{2,1} - pp'_{o})] \]
\[ A_{1,2} = \pm D [e - \tau'_{o} pp'_{o} + p - \alpha_{2,1}]p \]
\[ \frac{1}{D} = p_{o} (\alpha_{2} - \alpha_{2}) \]
\[ p_{o}' = 1 + \beta p \]
\[ \alpha_{1,2}^2 = \frac{p}{2} [(1+\beta) p + (1+\varepsilon) \pm \sqrt{((1+\beta) p + (1+\varepsilon))^2 - 4pp'_{o}]}^{1/2} \]

We consider a special case in which the relaxation constant (\( \beta \)) is expressed in terms of the coupling constant \( \varepsilon \), i.e. \( \beta = \frac{1}{1+\varepsilon} \). For this value of \( \beta \), we get

\[ \alpha_{1}^2 = p^2 + p/\beta, \quad \alpha_{2}^2 = \beta p^2 \]  
(3.6)

and then the transformed temperature and strain become

\[ \ddot{\theta}(z, p) = N(p) [(\ddot{\varepsilon} - \tau'_{o})p \exp(-\alpha_{1} z) - (p^2 \tau'_{o}(1-\beta) + \ddot{\varepsilon} p_{o}) \exp(-\alpha_{2} z)] \]  
(3.7)

\[ \ddot{U}'(z, p) = N(p) [(\ddot{\varepsilon} + p(1-\beta-\tau'_{o}) - \beta p \tau'_{o} p^2) \exp(-\alpha_{1} z)] \]
\[ \exp(1 + \tau'_{o} p'_{o} p) \exp(-\alpha_{2} z) \]  
(3.8)

where
Inverting (3.7) and (3.8), we get

\[
\begin{align*}
\Theta &= C_1 I(0) + C_2 \exp(-y/\tau'_o) I(1/\tau'_o) + C_3 \exp(-b^2 y) I(b^2) \\
&+ C_4 \Theta_1(1/\tau'_o) + C_5 \Theta_1(b^2) + C_6 \Theta_2(1/\tau'_o) + C_7 \Theta_2(b^2)
\end{align*}
\]  

(3.9)

and

\[
\begin{align*}
U' &= K_1 I(0) + K_2 I(1/\tau'_o) + K_3 I(b^2) + K_4 \Theta_1(1/\tau'_o) \\
&+ K_5 \Theta_1(b^2) + K_6 \Theta_1(1/\tau'_o) + K_7 \Theta_2(b^2) - (\beta/(1-\beta))(e^{-y/2\beta} - 1)
\end{align*}
\]  

(3.10)

where

\[
\begin{align*}
I(w) &= \int_0^y z \exp[(z-y)w] \frac{F(z,y)}{\Gamma(z) \Gamma(\tau'_o) \Gamma(1/\tau'_o)} \\
C_1 &= (1-\beta) D_1, \quad C_2 = b^2 \tau'_o D_1 D_2 \\
C_3 &= -b^2 \tau'_o + e D_1 D_2, \quad C_4 = -C_2/D_1 \\
C_5 &= -C_3/D_1, \quad C_6 = D_2, \quad C_7 = -D_1 D_2/(1-\beta), \quad K_1 = C_1, \quad K_2 = b^2 (\tau'_o - \beta) D_1 D_2 \exp(-y/\tau'_o) \\
K_3 &= D_1 D_2 D_3 b^2 \exp(-b^2 y)/(1-\beta), \quad K_4 = b^2 (\tau'_o - \beta)/D_2 \exp(-y/2\beta) \\
K_5 &= b^2 \beta D_2 D_3 \exp(-z/2\beta), \quad K_6 = -D_2/(b^2 \tau'_o (1-\beta)^2) \\
K_7 &= b^2 \beta D_2 D_3/(1-\beta)^2, \quad D_1 = 1/(144 \beta^2) \\
D_2 &= 1/(1-b^2 \tau'_o), \quad D_3 = (1-\beta)^2 + \tau'_o
\end{align*}
\]

\[
\begin{align*}
\phi_1(w) &= [1 - \exp((z-y)w)] H(y-z)/w, \quad \phi_2(w) = [1 - \exp((\sqrt{\beta} z - y)w)] H(y-\sqrt{\beta} z)/w \\
F(z,y) &= I_1((z'/2\beta)/D_1 z') \\
H(y-z) &= 0, \quad 0 < y < z \\
&= 1, \quad y > z
\end{align*}
\]

and

\[
z' = (y^2 - z^2)^{1/2}
\]

Here $I_1$ is the modified Bessel function of first kind.
The expression for stress can be obtained from (2.8c), (3.9) and (3.10). Taking $\tau' = 0$, recovers the results due to Danilovskaya [9] and setting $\beta = 0$, recovers the results of Daimaruya [11].

4. RESULTS AND DISCUSSION.

The results for temperature, strain and stress distributions are evaluated numerically and exhibited graphically in figures 1 to 3, for a particular value of the relaxation constant ($\beta$) given by $\beta = 1/\left(1+\bar{e}\right)$. The transport of thermal energy in the medium, i.e. either a diffusion process or a wave-like process depends on the magnitude of the relaxation constant. It was observed that at low temperatures the magnitude of the relaxation constant becomes significant and the energy equation predicts a wave-type phenomenon. The magnitudes of the coupling and relaxation constants were calculated over a range of intermediate and high temperatures by Lord [12]. The values of the coupling parameter $\bar{e}$ are smaller than unity for most of the materials.

Here for the computation, the relaxation constant ($\beta$) was taken as 0.98 and 0.76 (the corresponding values of $\bar{e}$ are 0.1 and 0.31 respectively) and the values 0.25, 0.5, 1 and 2 for the $\tau'_0$. The time-dependence of the non-dimensional temperature ($\theta$), strain ($\epsilon'$), and stress ($\sigma$) are depicted as a function of non-dimensional time $\gamma$ at the non-dimensional distance $z = 2$ for $\tau'_0 = 0.5$.

As the relaxation constant increases the corresponding components of temperature, strain and stress decrease. The gap between these corresponding parameters increases, due to the effect of relaxation time unlike that of coupled theory. It may be mentioned that a similar phenomena was observed by Daimaruya [11] in case of coupled theory. Moreover due to presence of Heaviside unit step function, the two discontinuities can occur in temperature and stress at the wavefronts $y = z$ and $y = \sqrt{\beta} z$ and the corresponding acoustic velocity ($v_1$) and thermal velocity ($v_2$) at the wavefronts are 1 and $1/\sqrt{\beta}$ respectively. Last but not least, the results obtained here which including the effect of the relaxation time are more general.

ACKNOWLEDGEMENT.

The second author wishes to thank the Council of Scientific and Industrial Research, New Delhi, for the financial assistance given for his work.
Fig. 1. Time dependence of temperature at $z = 2$.

Fig. 2. Time dependence of strain at $z = 2$. 
Fig. 3. Time dependence of stress at $z = 2$.

REFERENCES

Thinking about nonlinearity in engineering areas, up to the 70s, was focused on intentionally built nonlinear parts in order to improve the operational characteristics of a device or system. Keying, saturation, hysteretic phenomena, and dead zones were added to existing devices increasing their behavior diversity and precision. In this context, an intrinsic nonlinearity was treated just as a linear approximation, around equilibrium points.

Inspired on the rediscovering of the richness of nonlinear and chaotic phenomena, engineers started using analytical tools from “Qualitative Theory of Differential Equations,” allowing more precise analysis and synthesis, in order to produce new vital products and services. Bifurcation theory, dynamical systems and chaos started to be part of the mandatory set of tools for design engineers.

This proposed special edition of the Mathematical Problems in Engineering aims to provide a picture of the importance of the bifurcation theory, relating it with nonlinear and chaotic dynamics for natural and engineered systems. Ideas of how this dynamics can be captured through precisely tailored real and numerical experiments and understanding by the combination of specific tools that associate dynamical system theory and geometric tools in a very clever, sophisticated, and at the same time simple and unique analytical environment are the subject of this issue, allowing new methods to design high-precision devices and equipment.

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