

Research Article

Convergence Analysis for a System of Generalized Equilibrium Problems and a Countable Family of Strict Pseudocontractions

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We introduce a new iterative algorithm for a system of generalized equilibrium problems and a countable family of strict pseudocontractions in Hilbert spaces. We then prove that the sequence generated by the proposed algorithm converges strongly to a common element in the solutions set of a system of generalized equilibrium problems and the common fixed points set of an infinitely countable family of strict pseudocontractions.

1. Introduction

Let H be a real Hilbert space with the inner product $\langle \cdot, \cdot \rangle$ and induced norm $\| \cdot \|$. Let C be a nonempty, closed, and convex subset of H . Let $\{f_k\}_{k \in \Lambda} : C \times C \rightarrow \mathbb{R}$ be a family of bifunctions, and let $\{A_k\}_{k \in \Lambda} : C \rightarrow H$ be a family of nonlinear mappings, where Λ is an arbitrary index set. The system of generalized equilibrium problems is to find $\hat{x} \in C$ such that

$$f_k(\hat{x}, y) + \langle A_k \hat{x}, y - \hat{x} \rangle \geq 0, \quad \forall y \in C, k \in \Lambda. \quad (1.1)$$

If Λ is a singleton, then (1.1) reduces to find $\hat{x} \in C$ such that

$$f(\hat{x}, y) + \langle A\hat{x}, y - \hat{x} \rangle \geq 0, \quad \forall y \in C. \quad (1.2)$$

The solutions set of (1.2) is denoted by $\text{GEP}(f, A)$. If $f \equiv 0$, then the solutions set of (1.2) is denoted by $\text{VI}(C, A)$, and if $A \equiv 0$, then the solutions set of (1.2) is denoted by $\text{EP}(f)$.

The problem (1.2) is very general in the sense that it includes, as special cases, optimization problems, variational inequalities, minimax problems, and the Nash equilibrium problem in noncooperative games; see also [1, 2]. Some methods have been constructed to solve the system of equilibrium problems (see, e.g., [3–7]). Recall that a mapping $A : C \rightarrow H$ is said to be

(1) *monotone* if

$$\langle Ax - Ay, x - y \rangle \geq 0, \quad \forall x, y \in C, \quad (1.3)$$

(2) *α -inverse-strongly monotone* if there exists a constant $\alpha > 0$ such that

$$\langle Ax - Ay, x - y \rangle \geq \alpha \|Ax - Ay\|^2, \quad \forall x, y \in C. \quad (1.4)$$

It is easy to see that if A is α -inverse-strongly monotone, then A is monotone and $1/\alpha$ -Lipschitz.

For solving the equilibrium problem, let us assume that f satisfies the following conditions:

(A1) $f(x, x) = 0$ for all $x \in C$,

(A2) f is monotone, that is, $f(x, y) + f(y, x) \leq 0$ for all $x, y \in C$,

(A3) for each $x, y, z \in C$, $\lim_{t \rightarrow 0} f(tz + (1-t)x, y) \leq f(x, y)$,

(A4) for each $x \in C$, $y \mapsto f(x, y)$ is convex and lower semicontinuous.

Throughout this paper, we denote the fixed points set of a nonlinear mapping $T : C \rightarrow C$ by $F(T) = \{x \in C : Tx = x\}$. Recall that T is said to be a κ -strict pseudocontraction if there exists a constant $0 \leq \kappa < 1$ such that

$$\|Tx - Ty\|^2 \leq \|x - y\|^2 + \kappa \|(I - T)x - (I - T)y\|^2. \quad (1.5)$$

It is well known that (1.5) is equivalent to

$$\langle Tx - Ty, x - y \rangle \leq \|x - y\|^2 - \frac{1 - \kappa}{2} \|(I - T)x - (I - T)y\|^2. \quad (1.6)$$

It is worth mentioning that the class of strict pseudocontractions includes properly the class of nonexpansive mappings. It is also known that every κ -strict pseudocontraction is $((1 + \kappa)/(1 - \kappa))$ -Lipschitz; see [8].

In 1953, Mann [9] introduced the iteration as follows: a sequence $\{x_n\}$ defined by $x_0 \in C$ and

$$x_{n+1} = \alpha_n x_n + (1 - \alpha_n) Sx_n, \quad n \geq 0, \quad (1.7)$$

where $\{\alpha_n\}_{n=0}^{\infty} \subset [0, 1]$. If S is a nonexpansive mapping with a fixed point and the control sequence $\{\alpha_n\}_{n=0}^{\infty}$ is chosen so that $\sum_{n=0}^{\infty} \alpha_n(1 - \alpha_n) = \infty$, then the sequence $\{x_n\}$ defined

by (1.7) converges weakly to a fixed point of S (this is also valid in a uniformly convex Banach space with the Fréchet differentiable norm [10]).

In 1967, Browder and Petryshyn [11] introduced the class of strict pseudocontractions and proved existence and weak convergence theorems in a real Hilbert setting by using Mann iterative algorithm (1.7) with a constant sequence $\alpha_n = \alpha$ for all $n \geq 0$. Recently, Marino and Xu [8] and Zhou [12] extended the results of Browder and Petryshyn [11] to Mann's iteration process (1.7). Since 1967, the construction of fixed points for pseudocontractions via the iterative process has been extensively investigated by many authors (see, e.g., [13–22]).

Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let $S : C \rightarrow C$ be a nonexpansive mapping, $f : C \times C \rightarrow \mathbb{R}$ a bifunction, and let $A : C \rightarrow H$ be an inverse-strongly monotone mapping.

In 2008, Moudafi [23] introduced an iterative method for approximating a common element of the fixed points set of a nonexpansive mapping S and the solutions set of a generalized equilibrium problem $\text{GEP}(f, A)$ as follows: a sequence $\{x_n\}$ defined by $x_0 \in C$ and

$$\begin{aligned} f(y_n, y) + \langle Ax_n, y - y_n \rangle + \frac{1}{r_n} \langle y - y_n, y_n - x_n \rangle &\geq 0, \quad \forall y \in C, \\ x_{n+1} &= \alpha_n x_n + (1 - \alpha_n) S y_n, \quad n \geq 1, \end{aligned} \quad (1.8)$$

where $\{\alpha_n\}_{n=0}^\infty \subset (0, 1)$ and $\{r_n\}_{n=0}^\infty \subset (0, \infty)$. He proved that the sequence $\{x_n\}$ generated by (1.8) converges weakly to an element in $\text{GEP}(f, A) \cap F(S)$ under suitable conditions.

Due to the weak convergence, recently, S. Takahashi and W. Takahashi [24] introduced another modification iterative method of (1.8) for finding a common element of the fixed points set of a nonexpansive mapping and the solutions set of a generalized equilibrium problem in the framework of a real Hilbert space. To be more precise, they proved the following theorem.

Theorem 1.1 (see [24]). *Let C be a closed convex subset of a real Hilbert space H , and let $f : C \times C \rightarrow \mathbb{R}$ be a bifunction satisfying (A1)–(A4). Let A be an α -inverse-strongly monotone mapping of C into H , and let S be a nonexpansive mapping of C into itself such that $F(S) \cap \text{GEP}(f, A) \neq \emptyset$. Let $u \in C$ and $x_1 \in C$, and let $\{y_n\} \subset C$ and $\{x_n\} \subset C$ be sequences generated by*

$$\begin{aligned} f(y_n, y) + \langle Ax_n, y - y_n \rangle + \frac{1}{r_n} \langle y - y_n, y_n - x_n \rangle &\geq 0, \quad \forall y \in C, \\ x_{n+1} &= \beta_n x_n + (1 - \beta_n) S[\alpha_n u + (1 - \alpha_n) y_n], \quad n \geq 1, \end{aligned} \quad (1.9)$$

where $\{\alpha_n\}_{n=1}^\infty \subset [0, 1]$, $\{\beta_n\}_{n=1}^\infty \subset [0, 1]$ and $\{r_n\}_{n=1}^\infty \subset [0, 2\alpha]$ satisfy

- (i) $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $\sum_{n=1}^\infty \alpha_n = \infty$,
- (ii) $0 < c \leq \beta_n \leq d < 1$,
- (iii) $0 < a \leq r_n \leq b < 2\alpha$,
- (iv) $\lim_{n \rightarrow \infty} (r_n - r_{n+1}) = 0$.

Then, $\{x_n\}$ converges strongly to $z = P_{F(S) \cap \text{GEP}(f, A)} u$.

Recently, Yao et al. [25] introduced a new modified Mann iterative algorithm which is different from those in the literature for a nonexpansive mapping in a real Hilbert space. To be more precise, they proved the following theorem.

Theorem 1.2 (see [25]). *Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let $S : C \rightarrow C$ be a nonexpansive mapping such that $F(S) \neq \emptyset$. Let $\{\alpha_n\}_{n=0}^{\infty}$, and let $\{\beta_n\}_{n=0}^{\infty}$ be two real sequences in $(0,1)$. For given $x_0 \in C$ arbitrarily, let the sequence $\{x_n\}$, $n \geq 0$, be generated iteratively by*

$$\begin{aligned} y_n &= P_C[(1 - \alpha_n)x_n], \\ x_{n+1} &= (1 - \beta_n)x_n + \beta_n S y_n. \end{aligned} \tag{1.10}$$

Suppose that the following conditions are satisfied:

- (i) $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $\sum_{n=0}^{\infty} \alpha_n = \infty$,
- (ii) $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$,

then, the sequence $\{x_n\}$ generated by (1.10) strongly converges to a fixed point of S .

We know the following crucial lemmas concerning the equilibrium problem in Hilbert spaces.

Lemma 1.3 (see [1]). *Let C be a nonempty, closed, and convex subset of a real Hilbert space H , let f be a bifunction from $C \times C$ to \mathbb{R} satisfying (A1)–(A4). Let $r > 0$ and $x \in H$. Then, there exists $z \in C$ such that*

$$f(z, y) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \quad \forall y \in C. \tag{1.11}$$

Lemma 1.4 (see [26]). *Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let f be a bifunction from $C \times C$ to \mathbb{R} satisfying (A1)–(A4). For $x \in H$ and $r > 0$, define the mapping $T_r^f : H \rightarrow 2^C$ as follows:*

$$T_r^f(x) = \left\{ z \in C : f(z, y) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \forall y \in C \right\}. \tag{1.12}$$

Then, the following statements hold:

- (1) T_r^f is single-valued,
- (2) T_r^f is firmly nonexpansive, that is, for any $x, y \in H$,

$$\|T_r^f x - T_r^f y\|^2 \leq \langle T_r^f x - T_r^f y, x - y \rangle, \tag{1.13}$$

- (3) $F(T_r^f) = \text{EP}(f)$,
- (4) $\text{EP}(f)$ is closed and convex.

Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let $r_k > 0$ for each $k \in \{1, 2, \dots, M\}$. Let $\{f_k\}_{k=1}^M : C \times C \rightarrow \mathbb{R}$ be a family of bifunctions, let $\{A_k\}_{k=1}^M : C \rightarrow H$ be a family of α_k -inverse-strongly monotone mappings, and let $\{T_n\}_{n=1}^\infty : C \rightarrow C$ be a countable family of κ -strict pseudocontractions. For each $k \in \{1, 2, \dots, M\}$, denote the mapping $T_{r_k}^{f_k, A_k} : C \rightarrow C$ by $T_{r_k}^{f_k, A_k} := T_{r_k}^{f_k}(I - r_k A_k)$, where $T_{r_k}^{f_k} : H \rightarrow C$ is the mapping defined as in Lemma 1.4.

Motivated and inspired by Marino and Xu [8], Moudafi [23], S. Takahashi and W. Takahashi [24], and Yao et al. [25], we consider the following iteration: $x_1 \in C$ and

$$\begin{aligned} y_n &= P_C[(1 - \alpha_n)x_n], \\ u_n &= T_{r_M}^{f_M, A_M} T_{r_{M-1}}^{f_{M-1}, A_{M-1}} \dots T_{r_2}^{f_2, A_2} T_{r_1}^{f_1, A_1} y_n, \\ x_{n+1} &= \beta_n x_n + (1 - \beta_n)[\gamma u_n + (1 - \gamma)T_n u_n], \quad n \geq 1, \end{aligned} \quad (1.14)$$

where $\{\alpha_n\}_{n=1}^\infty \subset (0, 1)$, $\{\beta_n\}_{n=1}^\infty \subset (0, 1)$ and $\gamma \in (0, 1)$.

In this paper, we first prove a path convergence result for a nonexpansive mapping and a system of generalized equilibrium problems. Then, we prove a strong convergence theorem of the iteration process (1.14) for a system of generalized equilibrium problems and a countable family of strict pseudocontractions in a real Hilbert space. Our results extend the main results obtained by Yao et al. [25] in several aspects.

2. Preliminaries

Let C be a nonempty, closed, and convex subset of a real Hilbert space H . For each $x \in H$, there exists a unique nearest point in C , denoted by $P_C x$, such that $\|x - P_C x\| = \min_{y \in C} \|x - y\|$. P_C is called the metric projection of H onto C . It is also known that for $x \in H$ and $z \in C$, $z = P_C x$ is equivalent to $\langle x - z, y - z \rangle \leq 0$ for all $y \in C$. Furthermore,

$$\|y - P_C x\|^2 + \|x - P_C x\|^2 \leq \|x - y\|^2, \quad (2.1)$$

for all $x \in H$, $y \in C$. In a real Hilbert space, we also know that

$$\|\lambda x + (1 - \lambda)y\|^2 = \lambda\|x\|^2 + (1 - \lambda)\|y\|^2 - \lambda(1 - \lambda)\|x - y\|^2, \quad (2.2)$$

for all $x, y \in H$ and $\lambda \in [0, 1]$.

In the sequel, we need the following lemmas.

Lemma 2.1 (see [27, 28]). *Let E be a real uniformly convex Banach space, and let C be a nonempty, closed, and convex subset of E , and let $S : C \rightarrow C$ be a nonexpansive mapping such that $F(S) \neq \emptyset$, then $I - S$ is demiclosed at zero.*

Lemma 2.2 (see [29]). *Let $\{x_n\}$ and $\{z_n\}$ be two sequences in a Banach space E such that*

$$x_{n+1} = \beta_n x_n + (1 - \beta_n)z_n, \quad n \geq 1, \quad (2.3)$$

where $\{\beta_n\}_{n=1}^\infty$ satisfies conditions: $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$. If $\limsup_{n \rightarrow \infty} (\|z_{n+1} - z_n\| - \|x_{n+1} - x_n\|) \leq 0$, then $\|x_n - z_n\| \rightarrow 0$ as $n \rightarrow \infty$.

Lemma 2.3 (see [30]). Assume that $\{a_n\}_{n=1}^\infty$ is a sequence of nonnegative real numbers such that

$$a_{n+1} \leq (1 - \gamma_n)a_n + \gamma_n \delta_n, \quad n \geq 1, \quad (2.4)$$

where $\{\gamma_n\}_{n=1}^\infty$ is a sequence in $(0, 1)$ and $\{\delta_n\}_{n=1}^\infty$ is a sequence in \mathbb{R} such that

$$(a) \sum_{n=1}^\infty \gamma_n = \infty; \quad (b) \limsup_{n \rightarrow \infty} \delta_n \leq 0 \text{ or } \sum_{n=1}^\infty |\gamma_n \delta_n| < \infty.$$

Then, $\lim_{n \rightarrow \infty} a_n = 0$.

Lemma 2.4 (see [31]). Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let the mapping $A : C \rightarrow H$ be α -inverse-strongly monotone, and let $r > 0$ be a constant. Then, we have

$$\|(I - rA)x - (I - rA)y\|^2 \leq \|x - y\|^2 + r(r - 2\alpha)\|Ax - Ay\|^2, \quad (2.5)$$

for all $x, y \in C$. In particular, if $0 \leq r \leq 2\alpha$, then $I - rA$ is nonexpansive.

To deal with a family of mappings, the following conditions are introduced: let C be a subset of a real Hilbert space H , and let $\{T_n\}_{n=1}^\infty$ be a family of mappings of C such that $\bigcap_{n=1}^\infty F(T_n) \neq \emptyset$. Then, $\{T_n\}$ is said to satisfy the AKTT-condition [32] if for each bounded subset B of C ,

$$\sum_{n=1}^\infty \sup\{\|T_{n+1}z - T_n z\| : z \in B\} < \infty. \quad (2.6)$$

Lemma 2.5 (see [32]). Let C be a nonempty and closed subset of a Hilbert space H , and let $\{T_n\}$ be a family of mappings of C into itself which satisfies the AKTT-condition. Then, for each $x \in C$, $\{T_n x\}$ converges strongly to a point in C . Moreover, let the mapping T be defined by

$$Tx = \lim_{n \rightarrow \infty} T_n x, \quad \forall x \in C. \quad (2.7)$$

Then, for each bounded subset B of C ,

$$\limsup_{n \rightarrow \infty} \{\|Tz - T_n z\| : z \in B\} = 0. \quad (2.8)$$

The following results can be found in [33, 34].

Lemma 2.6 (see [33, 34]). Let C be a closed, and convex subset of a Hilbert space H . Suppose that $\{T_n\}_{n=1}^\infty$ is a family of κ -strictly pseudocontractive mappings from C into H with $\bigcap_{n=1}^\infty F(T_n) \neq \emptyset$ and $\{\mu_n\}_{n=1}^\infty$ is a real sequence in $(0, 1)$ such that $\sum_{n=1}^\infty \mu_n = 1$. Then, the following conclusions hold:

- (1) $G := \sum_{n=1}^\infty \mu_n T_n : C \rightarrow H$ is a κ -strictly pseudocontractive mapping,
- (2) $F(G) = \bigcap_{n=1}^\infty F(T_n)$.

Lemma 2.7 (see [34]). *Let C be a closed and convex subset of a Hilbert space H . Suppose that $\{S_i\}_{i=1}^{\infty}$ is a countable family of κ -strictly pseudocontractive mappings of C into itself with $\bigcap_{i=1}^{\infty} F(S_i) \neq \emptyset$. For each $n \in \mathbb{N}$, define $T_n : C \rightarrow C$ by*

$$T_n x = \sum_{i=1}^n \mu_n^i S_i x, \quad x \in C, \quad (2.9)$$

where $\{\mu_n^i\}$ is a family of nonnegative numbers satisfying

- (i) $\sum_{i=1}^n \mu_n^i = 1$ for all $n \in \mathbb{N}$,
- (ii) $\mu^i := \lim_{n \rightarrow \infty} \mu_n^i > 0$ for all $i \in \mathbb{N}$,
- (iii) $\sum_{n=1}^{\infty} \sum_{i=1}^n |\mu_{n+1}^i - \mu_n^i| < \infty$.

Then,

- (1) Each T_n is a κ -strictly pseudocontractive mapping.
- (2) $\{T_n\}$ satisfies AKTT-condition.
- (3) If $T : C \rightarrow C$ is defined by

$$Tx = \sum_{i=1}^{\infty} \mu^i S_i x, \quad x \in C, \quad (2.10)$$

then $Tx = \lim_{n \rightarrow \infty} T_n x$ and $F(T) = \bigcap_{n=1}^{\infty} F(T_n) = \bigcap_{i=1}^{\infty} F(S_i)$.

In the sequel, we will write $(\{T_n\}, T)$ satisfies the AKTT-condition if $\{T_n\}$ satisfies the AKTT-condition and T is defined by Lemma 2.5 with $F(T) = \bigcap_{n=1}^{\infty} F(T_n)$.

3. Path Convergence Results

Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let $S : C \rightarrow C$ be a nonexpansive mapping. Let $\{f_k\}_{k=1}^M : C \times C \rightarrow \mathbb{R}$ be a family of bifunctions, let $\{A_k\}_{k=1}^M : C \rightarrow H$ be a family of α_k -inverse-strongly monotone mappings, and let $r_k \in (0, 2\alpha_k)$. For each $k \in \{1, 2, \dots, M\}$, we denote the mapping $T_{r_k}^{f_k, A_k} : C \rightarrow C$ by

$$T_{r_k}^{f_k, A_k} := T_{r_k}^{f_k} (I - r_k A_k), \quad (3.1)$$

where $T_{r_k}^{f_k}$ is the mapping defined as in Lemma 1.4. For each $t \in (0, 1)$, we define the mapping $S_t : C \rightarrow C$ as follows:

$$S_t x = S T_{r_M}^{f_M, A_M} T_{r_{M-1}}^{f_{M-1}, A_{M-1}} \dots T_{r_1}^{f_1, A_1} P_C [(1-t)x], \quad \forall x \in C. \quad (3.2)$$

By Lemmas 1.4(2) and 2.4, we know that $T_{r_k}^{f_k}$ and $I - r_k A_k$ are nonexpansive for each $k \in \{1, 2, \dots, M\}$. So, the mapping $T_{r_k}^{f_k, A_k}$ is also nonexpansive for each $k \in \{1, 2, \dots, M\}$.

Moreover, we can check easily that S_t is a contraction. Then, the Banach contraction principle ensures that there exists a unique fixed point x_t of S_t in C , that is,

$$x_t = ST_{r_M}^{f_M, A_M} T_{r_{M-1}}^{f_{M-1}, A_{M-1}} \dots T_{r_1}^{f_1, A_1} P_C[(1-t)x_t], \quad t \in (0, 1). \quad (3.3)$$

Theorem 3.1. *Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let $S : C \rightarrow C$ be a nonexpansive mapping. Let $\{f_k\}_{k=1}^M : C \times C \rightarrow \mathbb{R}$ be a family of bifunctions, let $\{A_k\}_{k=1}^M : C \rightarrow H$ be a family of α_k -inverse-strongly monotone mappings, and let $r_k \in (0, 2\alpha_k)$. For each $k \in \{1, 2, \dots, M\}$, let the mapping $T_{r_k}^{f_k, A_k}$ be defined by (3.1). Assume that $F := (\bigcap_{k=1}^M \text{GEP}(f_k, A_k)) \cap (\bigcap_{n=1}^{\infty} F(T_n)) \neq \emptyset$. For each $t \in (0, 1)$, let the net $\{x_t\}$ be generated by (3.3). Then, as $t \rightarrow 0$, the net $\{x_t\}$ converges strongly to an element in F .*

Proof. First, we show that $\{x_t\}$ is bounded. For each $t \in (0, 1)$, let $y_t = P_C[(1-t)x_t]$ and $u_t = T_{r_M}^{f_M, A_M} T_{r_{M-1}}^{f_{M-1}, A_{M-1}} \dots T_{r_1}^{f_1, A_1} y_t$. From (3.3), we have for each $p \in F$ that

$$\|x_t - p\| = \|Su_t - Sp\| \leq \|u_t - p\| \leq \|y_t - p\| \leq (1-t)\|x_t - p\| + t\|p\|. \quad (3.4)$$

It follows that

$$\|x_t - p\| \leq \|p\|. \quad (3.5)$$

Hence, $\{x_t\}$ is bounded and so are $\{y_t\}$ and $\{u_t\}$. Observe that

$$\|y_t - x_t\| \leq t\|x_t\| \rightarrow 0, \quad (3.6)$$

as $t \rightarrow 0$ since $\{x_t\}$ is bounded.

Next, we show that $\|u_t - x_t\| \rightarrow 0$ as $t \rightarrow 0$. Denote $\Theta^k = T_{r_k}^{f_k, A_k} T_{r_{k-1}}^{f_{k-1}, A_{k-1}} \dots T_{r_1}^{f_1, A_1}$ for any $k \in \{1, 2, \dots, M\}$ and $\Theta^0 = I$. We note that $u_t = \Theta^M y_t$ for each $t \in (0, 1)$. From Lemma 2.4, we have for each $k \in \{1, 2, \dots, M\}$ and $p \in F$ that

$$\begin{aligned} \|\Theta^k y_t - p\|^2 &= \left\| T_{r_k}^{f_k, A_k} \Theta^{k-1} y_t - T_{r_k}^{f_k, A_k} \Theta^{k-1} p \right\|^2 \\ &= \left\| T_{r_k}^{f_k} \left(\Theta^{k-1} y_t - r_k A_k \Theta^{k-1} y_t \right) - T_{r_k}^{f_k} \left(\Theta^{k-1} p - r_k A_k \Theta^{k-1} p \right) \right\|^2 \\ &\leq \left\| \left(\Theta^{k-1} y_t - r_k A_k \Theta^{k-1} y_t \right) - \left(\Theta^{k-1} p - r_k A_k \Theta^{k-1} p \right) \right\|^2 \\ &\leq \left\| \Theta^{k-1} y_t - p \right\|^2 + r_k (r_k - 2\alpha_k) \left\| A_k \Theta^{k-1} y_t - A_k p \right\|^2. \end{aligned} \quad (3.7)$$

It follows that

$$\begin{aligned}
\|u_t - p\|^2 &= \|\Theta^M y_t - p\|^2 \\
&\leq \|y_t - p\|^2 + \sum_{i=1}^M r_i(r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_t - A_i p\|^2 \\
&= \|P_C[(1-t)x_t] - p\|^2 + \sum_{i=1}^M r_i(r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_t - A_i p\|^2 \\
&\leq (\|x_t - p\| + t\|x_t\|)^2 + \sum_{i=1}^M r_i(r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_t - A_i p\|^2 \\
&\leq \|x_t - p\|^2 + tM_1 + \sum_{i=1}^M r_i(r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_t - A_i p\|^2,
\end{aligned} \tag{3.8}$$

where $M_1 = \sup_{0 < t < 1} \{2\|x_t - p\|\|x_t\| + t\|x_t\|^2\}$. So, we have

$$\begin{aligned}
\|x_t - p\|^2 &\leq \|u_t - p\|^2 \\
&\leq \|x_t - p\|^2 + tM_1 + \sum_{i=1}^M r_i(r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_t - A_i p\|^2,
\end{aligned} \tag{3.9}$$

which implies that

$$\lim_{t \rightarrow 0} \|A_k \Theta^{k-1} y_t - A_k p\| = 0, \tag{3.10}$$

for each $k \in \{1, 2, \dots, M\}$. Since $T_{r_k}^{f_k}$ is firmly nonexpansive for each $k \in \{1, 2, \dots, M\}$, we have for each $p \in F$ and $k \in \{1, 2, \dots, M\}$ that

$$\begin{aligned}
\|\Theta^k y_t - p\|^2 &= \|T_{r_k}^{f_k, A_k} \Theta^{k-1} y_t - T_{r_k}^{f_k, A_k} \Theta^{k-1} p\|^2 \\
&= \|T_{r_k}^{f_k}(\Theta^{k-1} y_t - r_k A_k \Theta^{k-1} y_t) - T_{r_k}^{f_k}(\Theta^{k-1} p - r_k A_k \Theta^{k-1} p)\|^2 \\
&\leq \langle \Theta^{k-1} y_t - r_k A_k \Theta^{k-1} y_t - (p - r_k A_k p), \Theta^k y_t - p \rangle \\
&= \frac{1}{2} \left(\|\Theta^{k-1} y_t - r_k A_k \Theta^{k-1} y_t - (p - r_k A_k p)\|^2 + \|\Theta^k y_t - p\|^2 \right. \\
&\quad \left. - \|\Theta^{k-1} y_t - r_k A_k \Theta^{k-1} y_t - (p - r_k A_k p) - (\Theta^k y_t - p)\|^2 \right)
\end{aligned}$$

$$\begin{aligned}
&\leq \frac{1}{2} \left(\left\| \Theta^{k-1} y_t - p \right\|^2 + \left\| \Theta^k y_t - p \right\|^2 - \left\| \Theta^{k-1} y_t - \Theta^k y_t - r_k (A_k \Theta^{k-1} y_t - A_k p) \right\|^2 \right) \\
&\leq \frac{1}{2} \left(\left\| \Theta^{k-1} y_t - p \right\|^2 + \left\| \Theta^k y_t - p \right\|^2 - \left\| \Theta^{k-1} y_t - \Theta^k y_t \right\|^2 \right. \\
&\quad \left. + 2r_k \left\| \Theta^{k-1} y_t - \Theta^k y_t \right\| \left\| A_k \Theta^{k-1} y_t - A_k p \right\| \right).
\end{aligned} \tag{3.11}$$

This implies that

$$\begin{aligned}
\left\| \Theta^k y_t - p \right\|^2 &\leq \left\| \Theta^{k-1} y_t - p \right\|^2 - \left\| \Theta^{k-1} y_t - \Theta^k y_t \right\|^2 \\
&\quad + 2r_k \left\| \Theta^{k-1} y_t - \Theta^k y_t \right\| \left\| A_k \Theta^{k-1} y_t - A_k p \right\| \\
&\leq \left\| \Theta^{k-1} y_t - p \right\|^2 - \left\| \Theta^{k-1} y_t - \Theta^k y_t \right\|^2 + M_2 \left\| A_k \Theta^{k-1} y_t - A_k p \right\|,
\end{aligned} \tag{3.12}$$

where $M_2 = \max_{1 \leq k \leq M} \sup_{0 < t < 1} \{2r_k \|\Theta^{k-1} y_t - \Theta^k y_t\|\}$. This shows that

$$\begin{aligned}
\left\| u_t - p \right\|^2 &= \left\| \Theta^M y_t - p \right\|^2 \\
&\leq \left\| y_t - p \right\|^2 - \sum_{i=1}^M \left\| \Theta^{i-1} y_t - \Theta^i y_t \right\|^2 + M_2 \sum_{i=1}^M \left\| A_i \Theta^{i-1} y_t - A_i p \right\| \\
&\leq \left\| x_t - p \right\|^2 + tM_1 - \sum_{i=1}^M \left\| \Theta^{i-1} y_t - \Theta^i y_t \right\|^2 + M_2 \sum_{i=1}^M \left\| A_i \Theta^{i-1} y_t - A_i p \right\|.
\end{aligned} \tag{3.13}$$

Hence,

$$\begin{aligned}
\left\| x_t - p \right\|^2 &\leq \left\| u_t - p \right\|^2 \\
&\leq \left\| x_t - p \right\|^2 + tM_1 - \sum_{i=1}^M \left\| \Theta^{i-1} y_t - \Theta^i y_t \right\|^2 + M_2 \sum_{i=1}^M \left\| A_i \Theta^{i-1} y_t - A_i p \right\|.
\end{aligned} \tag{3.14}$$

From (3.10), we obtain

$$\sum_{i=1}^M \left\| \Theta^{i-1} y_t - \Theta^i y_t \right\| \longrightarrow 0, \tag{3.15}$$

as $t \rightarrow 0$. So, we can conclude that

$$\lim_{t \rightarrow 0} \left\| \Theta^{k-1} y_t - \Theta^k y_t \right\| = 0, \tag{3.16}$$

for each $k \in \{1, 2, \dots, M\}$. Observing

$$\begin{aligned} \|u_n - y_t\| &= \|\Theta^M y_t - y_t\| \\ &\leq \|\Theta^M y_t - \Theta^{M-1} y_t\| + \|\Theta^{M-1} y_t - \Theta^{M-2} y_t\| + \dots + \|\Theta^1 y_t - y_t\|, \end{aligned} \quad (3.17)$$

it follows by (3.16) that

$$\lim_{t \rightarrow 0} \|u_t - y_t\| = 0. \quad (3.18)$$

From (3.6) and (3.18), we have

$$\lim_{t \rightarrow 0} \|u_t - x_t\| = 0. \quad (3.19)$$

Hence,

$$\|x_t - Sx_t\| = \|Su_t - Sx_t\| \leq \|u_t - x_t\| \rightarrow 0, \quad (3.20)$$

as $t \rightarrow 0$.

Next, we show that $\{x_t\}$ is relatively norm compact as $t \rightarrow 0$. Let $\{t_n\} \subset (0, 1)$ be a sequence such that $t_n \rightarrow 0$ as $n \rightarrow \infty$. Put $x_n := x_{t_n}$. From (3.20), we obtain

$$\lim_{n \rightarrow \infty} \|x_n - Sx_n\| = 0. \quad (3.21)$$

Since $\{x_n\}$ is bounded, without loss of generality, we may assume that $\{x_n\}$ converges weakly to $x^* \in C$. Applying Lemma 2.1 to (3.21), we can conclude that $x^* \in F(S)$.

Next, we show that $x^* \in \bigcap_{k=1}^M \text{GEP}(f_k, A_k)$. Note that $\Theta^k y_n = T_{r_k}^{f_k, A_k} \Theta^{k-1} y_n = T_{r_k}^{f_k}(\Theta^{k-1} y_n - r_k A_k \Theta^{k-1} y_n)$ for each $k \in \{1, 2, \dots, M\}$. Hence, for each $y \in C$ and $k \in \{1, 2, \dots, M\}$, we obtain

$$f_k(\Theta^k y_n, y) + \frac{1}{r_k} \langle y - \Theta^k y_n, \Theta^k y_n - (\Theta^{k-1} y_n - r_k A_k \Theta^{k-1} y_n) \rangle \geq 0. \quad (3.22)$$

From (A2), we have

$$\frac{1}{r_k} \langle y - \Theta^k y_n, \Theta^k y_n - (\Theta^{k-1} y_n - r_k A_k \Theta^{k-1} y_n) \rangle \geq f_k(y, \Theta^k y_n), \quad \forall y \in C. \quad (3.23)$$

Therefore,

$$\left\langle y - \Theta^k y_{n_j}, \frac{\Theta^k y_{n_j} - \Theta^{k-1} y_{n_j}}{r_k} + A_k \Theta^{k-1} y_{n_j} \right\rangle \geq f_k(y, \Theta^k y_{n_j}), \quad \forall y \in C. \quad (3.24)$$

For each $t \in (0, 1)$ and $y \in C$, put $z_t = ty + (1 - t)x^*$. Then, we have $z_t \in C$. From (3.24), we get that

$$\begin{aligned}
\langle z_t - \Theta^k y_{n_j}, A_k z_t \rangle &\geq \langle z_t - \Theta^k y_{n_j}, A_k z_t \rangle \\
&\quad - \left\langle z_t - \Theta^k y_{n_j}, \frac{\Theta^k y_{n_j} - \Theta^{k-1} y_{n_j}}{r_k} + A_k \Theta^{k-1} y_{n_j} \right\rangle + f_k(z_t, \Theta^k y_{n_j}) \\
&= \langle z_t - \Theta^k y_{n_j}, A_k z_t - A_k \Theta^k y_{n_j} \rangle + \langle z_t - \Theta^k y_{n_j}, A_k \Theta^k y_{n_j} - A_k \Theta^{k-1} y_{n_j} \rangle \\
&\quad - \left\langle z_t - \Theta^k y_{n_j}, \frac{\Theta^k y_{n_j} - \Theta^{k-1} y_{n_j}}{r_k} \right\rangle + f_k(z_t, \Theta^k y_{n_j}).
\end{aligned} \tag{3.25}$$

We note that $\|A_k \Theta^k y_{n_j} - A_k \Theta^{k-1} y_{n_j}\| \leq (1/\alpha_k) \|\Theta^k y_{n_j} - \Theta^{k-1} y_{n_j}\| \rightarrow 0$, $\Theta^k y_{n_j} \rightarrow x^*$ as $j \rightarrow \infty$, and $\{A_k\}_{k=1}^M$ is a family of monotone mappings. It follows from (3.25) that

$$\langle z_t - x^*, A_k z_t \rangle \geq f_k(z_t, x^*). \tag{3.26}$$

So, by (A1), (A4) and (3.26), we have for each $y \in C$ and $k \in \{1, 2, \dots, M\}$ that

$$\begin{aligned}
0 &= f_k(z_t, z_t) \leq t f_k(z_t, y) + (1 - t) f_k(z_t, x^*) \\
&\leq t f_k(z_t, y) + (1 - t) \langle z_t - x^*, A_k z_t \rangle \\
&= t f_k(z_t, y) + t(1 - t) \langle y - x^*, A_k z_t \rangle.
\end{aligned} \tag{3.27}$$

This implies that

$$f_k(z_t, y) + (1 - t) \langle y - x^*, A_k z_t \rangle \geq 0, \quad \forall y \in C. \tag{3.28}$$

Letting $t \rightarrow 0$ in (3.28), it follows from (A3) that

$$f_k(x^*, y) + \langle y - x^*, A_k x^* \rangle \geq 0, \quad \forall y \in C. \tag{3.29}$$

Hence $x^* \in \bigcap_{k=1}^M \text{GEP}(f_k, A_k)$; consequently, $x^* \in F$. Further, we see that

$$\begin{aligned}
\|x_t - x^*\|^2 &= \|Su_t - x^*\|^2 \\
&\leq \|u_t - x^*\|^2 \\
&\leq \|y_t - x^*\|^2 \\
&\leq \|x_t - x^* - tx_t\|^2 \\
&= \|x_t - x^*\|^2 - 2t\langle x_t, x_t - x^* \rangle + t^2\|x_t\|^2 \\
&= \|x_t - x^*\|^2 - 2t\langle x_t - x^*, x_t - x^* \rangle - 2t\langle x^*, x_t - x^* \rangle + t^2\|x_t\|^2.
\end{aligned} \tag{3.30}$$

So, we have

$$\|x_t - x^*\|^2 \leq \langle x^*, x^* - x_t \rangle + \frac{t}{2}\|x_t\|^2. \tag{3.31}$$

In particular,

$$\|x_n - x^*\|^2 \leq \langle x^*, x^* - x_n \rangle + \frac{t_n}{2}\|x_n\|^2. \tag{3.32}$$

Since $x_n \rightarrow x^*$, we have $x_n \rightarrow x^*$ as $n \rightarrow \infty$. By using the same argument as in the proof of Theorem 3.1 of [25], we can show that $x_t \rightarrow x^* \in F$ as $t \rightarrow 0$. This completes the proof. \square

4. Strong Convergence Results

Theorem 4.1. *Let C be a nonempty, closed and convex subset of a real Hilbert space H . Let $\{f_k\}_{k=1}^M : C \times C \rightarrow \mathbb{R}$ be a family of bifunctions, let $\{A_k\}_{k=1}^M : C \rightarrow H$ be a family of α_k -inverse-strongly monotone mappings and let $\{T_n\}_{n=1}^\infty : C \rightarrow C$ be a countable family of κ -strict pseudocontractions for some $0 < \kappa < 1$ such that $F := (\bigcap_{k=1}^M \text{GEP}(f_k, A_k)) \cap (\bigcap_{n=1}^\infty F(T_n)) \neq \emptyset$. Assume that $\{\alpha_n\}_{n=1}^\infty \subset (0, 1)$, $\{\beta_n\}_{n=1}^\infty \subset (0, 1)$, $\gamma \in (\kappa, 1)$ and $r_k \in (0, 2\alpha_k)$ for each $k \in \{1, 2, \dots, M\}$ satisfy the following conditions:*

- (i) $\lim_{n \rightarrow \infty} \alpha_n = 0$ and $\sum_{n=1}^\infty \alpha_n = \infty$,
- (ii) $0 < \liminf_{n \rightarrow \infty} \beta_n \leq \limsup_{n \rightarrow \infty} \beta_n < 1$.

Suppose that $(\{T_n\}, T)$ satisfies the AKTT-condition. Then, $\{x_n\}$ generated by (1.14) converges strongly to an element in F .

Proof. For each $n \in \mathbb{N}$, define $S_n : C \rightarrow C$ by $S_n x = \gamma x + (1 - \gamma)T_n x$, $x \in C$. Then, $F(S_n) = F(T_n) = F(T)$, since $\gamma \in (0, 1)$. Moreover, we know that $\{S_n\}$ satisfies the AKTT-condition, since $\{T_n\}$ satisfies the AKTT-condition. By Lemma 2.5, we can define the mapping $S : C \rightarrow C$ by $Sx = \lim_{n \rightarrow \infty} S_n x$ for $x \in C$. Hence, $Sx = \gamma x + (1 - \gamma)Tx$, $x \in C$, since $T_n x \rightarrow Tx$ for

$x \in C$. Further, we know that S_n is nonexpansive for each $n \in \mathbb{N}$. Indeed, for each $x, y \in C$ and $n \in \mathbb{N}$, we have

$$\begin{aligned}
\|S_n x - S_n y\|^2 &= \|\gamma x + (1 - \gamma)T_n x - \gamma y - (1 - \gamma)T_n y\|^2 \\
&= \|\gamma(x - y) + (1 - \gamma)(T_n x - T_n y)\|^2 \\
&= \gamma\|x - y\|^2 + (1 - \gamma)\|T_n x - T_n y\|^2 - \gamma(1 - \gamma)\|(I - T_n)x - (I - T_n)y\|^2 \\
&\leq \gamma\|x - y\|^2 + (1 - \gamma)\|x - y\|^2 + (1 - \gamma)\kappa\|(I - T_n)x - (I - T_n)y\|^2 \\
&\quad - \gamma(1 - \gamma)\|(I - T_n)x - (I - T_n)y\|^2 \\
&= \|x - y\|^2 + (1 - \gamma)(\kappa - \gamma)\|(I - T_n)x - (I - T_n)y\|^2 \\
&\leq \|x - y\|^2.
\end{aligned} \tag{4.1}$$

Hence, S_n is nonexpansive for each $n \in \mathbb{N}$ and so is S .

Next, we show that $\{x_n\}$ is bounded. Denote $\Theta^k = T_{r_k}^{f_k, A_k} T_{r_{k-1}}^{f_{k-1}, A_{k-1}} \dots T_{r_1}^{f_1, A_1}$ for any $k \in \{1, 2, \dots, M\}$ and $\Theta^0 = I$. We note that $u_n = \Theta^M y_n$. From (1.14), we have for each $p \in F$ that

$$\begin{aligned}
\|x_{n+1} - p\| &= \|\beta_n x_n + (1 - \beta_n)S_n u_n\| \\
&\leq \beta_n \|x_n - p\| + (1 - \beta_n) \|S_n u_n - p\| \\
&\leq \beta_n \|x_n - p\| + (1 - \beta_n) \|u_n - p\| \\
&= \beta_n \|x_n - p\| + (1 - \beta_n) \|\Theta^M y_n - p\| \\
&\leq \beta_n \|x_n - p\| + (1 - \beta_n) \|y_n - p\| \\
&\leq \beta_n \|x_n - p\| + (1 - \beta_n) [(1 - \alpha_n) \|x_n - p\| + \alpha_n \|p\|] \\
&= (1 - \alpha_n(1 - \beta_n)) \|x_n - p\| + \alpha_n(1 - \beta_n) \|p\| \\
&\leq \max\{\|x_n - p\|, \|p\|\}.
\end{aligned} \tag{4.2}$$

Hence, by induction, $\{x_n\}$ is bounded and so are $\{y_n\}$ and $\{u_n\}$.

Next, we show that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = 0. \tag{4.3}$$

Since $u_n = \Theta^M y_n$ and $u_{n+1} = \Theta^M y_{n+1}$,

$$\begin{aligned}
\|u_{n+1} - u_n\| &= \|\Theta^M y_{n+1} - \Theta^M y_n\| \\
&\leq \|y_{n+1} - y_n\|.
\end{aligned} \tag{4.4}$$

Set $z_n = S_n u_n$, $n \in \mathbb{N}$. So, we have from (1.14) and (4.4) that

$$\begin{aligned}
\|z_{n+1} - z_n\| &= \|S_{n+1}u_{n+1} - S_n u_n\| \\
&\leq \|S_{n+1}u_{n+1} - S_{n+1}u_n\| + \|S_{n+1}u_n - S_n u_n\| \\
&\leq \|u_{n+1} - u_n\| + \|S_{n+1}u_n - S_n u_n\| \\
&\leq \|y_{n+1} - y_n\| + \|S_{n+1}u_n - S_n u_n\| \\
&\leq \|(1 - \alpha_{n+1})x_{n+1} - (1 - \alpha_n)x_n\| + \sup_{z \in \{u_n\}} \|S_{n+1}z - S_n z\| \\
&\leq \|x_{n+1} - x_n\| + \alpha_{n+1}\|x_{n+1}\| + \alpha_n\|x_n\| + \sup_{z \in \{u_n\}} \|S_{n+1}z - S_n z\|.
\end{aligned} \tag{4.5}$$

Since $\{S_n\}$ satisfies the AKTT-condition and $\lim_{n \rightarrow \infty} \alpha_n = 0$, it follows that

$$\limsup_{n \rightarrow \infty} (\|z_{n+1} - z_n\| - \|x_{n+1} - x_n\|) \leq 0. \tag{4.6}$$

So, by Lemma 2.2 and (ii), we obtain

$$\lim_{n \rightarrow \infty} \|z_n - x_n\| = 0. \tag{4.7}$$

Hence,

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = \lim_{n \rightarrow \infty} (1 - \beta_n) \|z_n - x_n\| = 0. \tag{4.8}$$

Observe that

$$\|y_n - x_n\| = \|P_C[(1 - \alpha_n)x_n] - P_C x_n\| \leq \alpha_n \|x_n\| \rightarrow 0, \tag{4.9}$$

as $n \rightarrow \infty$. Similar to the proof of Theorem 3.1, we obtain for each $p \in F$ that

$$\|u_n - p\|^2 \leq \|x_n - p\|^2 + \alpha_n M'_1 + \sum_{i=1}^M r_i (r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_n - A_i p\|^2, \tag{4.10}$$

$$\|u_n - p\|^2 \leq \|x_n - p\|^2 + \alpha_n M'_1 - \sum_{i=1}^M \|\Theta^{i-1} y_n - \Theta^i y_n\|^2 + M'_2 \sum_{i=1}^M \|A_i \Theta^{i-1} y_n - A_i p\|^2, \tag{4.11}$$

for some $M'_1 > 0$ and $M'_2 > 0$. Then, from (4.10), we have

$$\begin{aligned}
\|x_{n+1} - p\|^2 &\leq \beta_n \|x_n - p\|^2 + (1 - \beta_n) \|S_n u_n - p\|^2 \\
&\leq \beta_n \|x_n - p\|^2 + (1 - \beta_n) \|u_n - p\|^2 \\
&\leq \beta_n \|x_n - p\|^2 + (1 - \beta_n) \\
&\quad \times \left(\|x_n - p\|^2 + \alpha_n M'_1 + \sum_{i=1}^M r_i (r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_n - A_i p\|^2 \right) \\
&\leq \|x_n - p\|^2 + \alpha_n M'_1 + (1 - \beta_n) \sum_{i=1}^M r_i (r_i - 2\alpha_i) \|A_i \Theta^{i-1} y_n - A_i p\|^2,
\end{aligned} \tag{4.12}$$

which implies that

$$(1 - \beta_n) \sum_{i=1}^M r_i (2\alpha_i - r_i) \|A_i \Theta^{i-1} y_n - A_i p\|^2 \leq \|x_{n+1} - p\|^2 - \|x_n - p\|^2 + \alpha_n M'_1. \tag{4.13}$$

So, from (4.8), (i), (ii) and $0 < r_k < 2\alpha_k$ for each $k = 1, 2, \dots, M$, we have

$$\lim_{n \rightarrow \infty} \|A_k \Theta^{k-1} y_n - A_k p\| = 0, \tag{4.14}$$

for each $k \in \{1, 2, \dots, M\}$. Similarly, from (4.11), we have

$$\begin{aligned}
\|x_{n+1} - p\|^2 &\leq \beta_n \|x_n - p\|^2 + (1 - \beta_n) \|S_n u_n - p\|^2 \\
&\leq \beta_n \|x_n - p\|^2 + (1 - \beta_n) \|u_n - p\|^2 \\
&\leq \beta_n \|x_n - p\|^2 + (1 - \beta_n) \\
&\quad \times \left(\|x_n - p\|^2 + \alpha_n M'_1 - \sum_{i=1}^M \|\Theta^{i-1} y_n - \Theta^i y_n\|^2 + M'_2 \sum_{i=1}^M \|A_i \Theta^{i-1} y_n - A_i p\| \right) \\
&\leq \|x_n - p\|^2 + \alpha_n M'_1 - (1 - \beta_n) \sum_{i=1}^M \|\Theta^{i-1} y_n - \Theta^i y_n\|^2 + M'_2 \sum_{i=1}^M \|A_i \Theta^{i-1} y_n - A_i p\|.
\end{aligned} \tag{4.15}$$

This implies that

$$\begin{aligned}
&(1 - \beta_n) \sum_{i=1}^M \|\Theta^{i-1} y_n - \Theta^i y_n\|^2 \\
&\leq \|x_n - p\|^2 - \|x_{n+1} - p\|^2 + \alpha_n M'_1 + M'_2 \sum_{i=1}^M \|A_i \Theta^{i-1} y_n - A_i p\|.
\end{aligned} \tag{4.16}$$

From (i), (ii), (4.8), and (4.14), it follows that

$$\lim_{n \rightarrow \infty} \left\| \Theta^{k-1} y_n - \Theta^k y_n \right\| = 0, \quad (4.17)$$

for each $k \in \{1, 2, \dots, M\}$.

Next, we show that

$$\lim_{n \rightarrow \infty} \|x_n - Sx_n\| = 0. \quad (4.18)$$

Observing

$$\begin{aligned} \|u_n - y_n\| &= \left\| \Theta^M y_n - y_n \right\| \\ &\leq \left\| \Theta^M y_n - \Theta^{M-1} y_n \right\| + \left\| \Theta^{M-1} y_n - \Theta^{M-2} y_n \right\| + \dots + \left\| \Theta^1 y_n - y_n \right\|, \end{aligned} \quad (4.19)$$

it follows, by (4.17), that

$$\lim_{n \rightarrow \infty} \|u_n - y_n\| = 0. \quad (4.20)$$

From (4.9) and (4.20), we have

$$\lim_{n \rightarrow \infty} \|u_n - x_n\| = 0. \quad (4.21)$$

We see that

$$\begin{aligned} \|x_n - Sx_n\| &\leq \|x_n - S_n u_n\| + \|S_n u_n - S_n x_n\| + \|S_n x_n - Sx_n\| \\ &\leq \|x_n - S_n u_n\| + \|u_n - x_n\| + \sup_{z \in \{x_n\}} \|S_n z - Sz\|. \end{aligned} \quad (4.22)$$

So, by (4.7), (4.21), and Lemma 2.5, we have

$$\lim_{n \rightarrow \infty} \|x_n - Sx_n\| = 0. \quad (4.23)$$

Let the net $\{x_t\}$ be defined by (3.3). By Theorem 3.1, we have $x_t \rightarrow x^* \in F$ as $t \rightarrow 0$. Moreover, by proving in the same manner as in Theorem 3.2 of [25], we can show that

$$\limsup_{n \rightarrow \infty} \langle x^*, x^* - x_n \rangle \leq 0. \quad (4.24)$$

Finally, we show that $x_n \rightarrow x^* \in F$ as $n \rightarrow \infty$. From (1.14), we have

$$\begin{aligned}
\|x_{n+1} - x^*\|^2 &\leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \|S_n u_n - x^*\|^2 \\
&\leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \|u_n - x^*\|^2 \\
&\leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \|y_n - x^*\|^2 \\
&\leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \|(1 - \alpha_n)(x_n - x^*) - \alpha_n x^*\|^2 \\
&\leq \beta_n \|x_n - x^*\|^2 + (1 - \beta_n) \\
&\quad \times \left((1 - \alpha_n) \|x_n - x^*\|^2 - 2\alpha_n(1 - \alpha_n) \langle x^*, x_n - x^* \rangle + \alpha_n^2 \|x^*\|^2 \right) \\
&= (1 - \alpha_n(1 - \beta_n)) \|x_n - x^*\|^2 \\
&\quad + \alpha_n(1 - \beta_n) \left(2(1 - \alpha_n) \langle x^*, x^* - x_n \rangle + \alpha_n \|x^*\|^2 \right).
\end{aligned} \tag{4.25}$$

By (i) and (4.24), it follows from Lemma 2.3 that $x_n \rightarrow x^* \in F$. This completes the proof. \square

As a direct consequence of Lemmas 2.6 and 2.7 and Theorem 4.1, we obtain the following result.

Theorem 4.2. *Let C be a nonempty, closed, and convex subset of a real Hilbert space H . Let $\{f_k\}_{k=1}^M : C \times C \rightarrow \mathbb{R}$ be a family of bifunctions, let $\{A_k\}_{k=1}^M : C \rightarrow H$ be a family of α_k -inverse-strongly monotone mappings, and let $\{S_i\}_{i=1}^\infty$ be a sequence of κ_i -strict pseudocontractions of C into itself such that $F := (\bigcap_{k=1}^M \text{GEP}(f_k, A_k)) \cap (\bigcap_{i=1}^\infty F(S_i)) \neq \emptyset$ and $\sup\{\kappa_i : i \in \mathbb{N}\} = \kappa > 0$. Assume that $\gamma \in (\kappa, 1)$ and $r_k \in (0, 2\alpha_k)$ for each $k \in \{1, 2, \dots, M\}$. Define the sequence $\{x_n\}$ by $x_1 \in C$ and*

$$\begin{aligned}
y_n &= P_C[(1 - \alpha_n)x_n], \\
u_n &= T_{r_M}^{f_M, A_M} T_{r_{M-1}}^{f_{M-1}, A_{M-1}} \dots T_{r_2}^{f_2, A_2} T_{r_1}^{f_1, A_1} y_n, \\
x_{n+1} &= \beta_n x_n + (1 - \beta_n) \left[\gamma u_n + (1 - \gamma) \sum_{i=1}^n \mu_n^i S_i u_n \right], \quad n \geq 1,
\end{aligned} \tag{4.26}$$

where $\{\alpha_n\}_{n=1}^\infty$ and $\{\beta_n\}_{n=1}^\infty$ are real sequences in $(0, 1)$ which satisfy (i)-(ii) of Theorem 4.1 and $\{\mu_n^i\}$ is a real sequence which satisfies (i)-(iii) of Lemma 2.7. Then, $\{x_n\}$ converges strongly to an element in F .

Remark 4.3. Theorems 4.1 and 4.2 extend the main results in [25] from a nonexpansive mapping to an infinite family of strict pseudocontractions and a system of generalized equilibrium problems.

Remark 4.4. If we take $A_k \equiv 0$ and $f_k \equiv 0$ for each $k = 1, 2, \dots, M$, then Theorems 3.1, 4.1, and 4.2 can be applied to a system of equilibrium problems and to a system of variational inequality problems, respectively.

Remark 4.5. Let S_1, S_2, \dots be an infinite family of nonexpansive mappings of C into itself, and let ξ_1, ξ_2, \dots be real numbers such that $0 < \xi_i < 1$ for all $i \in \mathbb{N}$. Moreover, let W_n and W be the W -mappings [35] generated by S_1, S_2, \dots, S_n and $\xi_1, \xi_2, \dots, \xi_n$ and S_1, S_2, \dots and ξ_1, ξ_2, \dots . Then, we know from [7, 35] that $(\{W_n\}, W)$ satisfies the AKTT-condition. Therefore, in Theorem 4.1, the mapping T_n can be also replaced by W_n .

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