The Schauder conjecture that every compact convex subset of a metric linear space has the fixed-point property was recently established by Cauty (2001). This paper elaborates on Cauty’s proof in order to make it more detailed and therefore more accessible. Such a detailed analysis allows us to show that the convex compacta in metric linear spaces possess the simplicial approximation property introduced by Kalton, Peck, and Roberts. The latter demonstrates that the original Schauder approach to solve the conjecture is in some sense “correctable.”

1. Introduction

Throughout most of this paper, \( X \) will be a compact convex subset of a separable metric linear space \((E, || \cdot ||)\) which is not necessarily locally convex. We can always assume (and we will) that \( || \cdot || \) is an \( F \)-norm on \( E \); hence, we have \( ||x + y|| \leq ||x|| + ||y||, \) \( ||tx|| \leq ||x|| \) for all \( x, y \in E \) and \(-1 \leq t \leq 1\); in general, \( || \cdot || \) is not homogeneous. Generalizing the classical Brouwer theorem, in 1930, Schauder [28] claimed the proof of the fixed-point property of \( X \); unfortunately, his argument contained a gap. As an effect, the question of whether every compact convex subset of a metric linear space has the fixed-point property was put, in August 1935, [25, Problem 54]; it became known as Schauder’s conjecture. Since then, many partial results were obtained but the general case went unsettled. Almost all those partial results were based on the so-called finite-dimensional approximation property that some convex compacta possess. The property requires that, \( \text{id}_X \), the identity map on \( X \), is, in a uniform way, arbitrarily closely approximated by maps \( \psi : X \to X \) such that \( \dim(\psi(X)) < \infty \). Here, the dimension “\( \dim \)” can be understood in any reasonable (i.e., “linear” or purely topological) way; for further information, see [7]. In the case that \( E \) is locally convex, such an approximation can be obtained via partitions of unity. Such an
approach predominates in the textbook proofs of the Schauder-Tychonoff theorem which states that every compact convex subset of a locally convex topological vector space has the fixed-point property. This most transparent fact in the area was published by Tychonoff [29] in 1935.

Note that, as a consequence of some advanced results of infinite-dimensional topology, a convex compactum \( X \) having the finite-dimensional property not only has the fixed-point property, but actually is homeomorphic either to \([0, 1]^n, n \in \mathbb{N}\), or to \([0, 1]^\infty\), the Hilbert cube, see [7, 12]. As later becomes clear, it is remarkable that Schauder in his failed attempt did not intend to verify the finite-dimensional property, but a weaker property which was later formalized by Kalton et al. in [21]. This “local” property, which is called the simplicial approximation property in [21], yields the fixed-point property, but itself is rather far from the finite-dimensional property, which in turn could be viewed as a “global” property. In [21], the simplicial approximation property was used to verify the fixed-point property of certain convex compacta without extreme points. Those compacta were earlier discovered by Roberts.

Finally, in 1999, Cauty [5] provided a proof of the Schauder conjecture. His proof did not rely on any of the above properties, but was based on the existence of a certain resolution map \( \phi : Z \to X \) from a certain countable-dimensional compactum \( Z \) onto \( X \). Actually, Cauty has proved a more general result stating that, for an arbitrary convex subset \( C \) of a topological vector space, every map \( f : C \to C \) such that \( f(C) \) is contained in a compact subset of \( C \) (i.e., every relatively compact map \( f : C \to C \)) has the fixed-point property. We mention that a similar result for the locally convex case was obtained by Mazur [26] and Hukuhara [19] in 1938 and 1950, respectively.

This paper elaborates on Cauty’s proof of the metric case only; that is, on the following result.

**Theorem 1.1 (Cauty [5]).** Let \( X \) be a convex compactum of a metric linear space \((E, \| \cdot \|)\) and let \( f : X \to X \) be a map. There exists \( x \in X \) with \( f(x) = x \).

Revisiting Cauty’s proof, we were able to isolate its two basic ingredients. The first ingredient is of purely topological (or, better to say, metric) nature; it deals with the construction of the resolution \( \phi \). The second ingredient has a linear (affine) flavor and, employing the resolution map \( \phi \), it establishes a certain approximation property. We hope that our analysis makes Cauty’s proof more accessible. Surprisingly, such an analysis enables us to verify the simplicial approximation property of \( X \) (cf. [8]). This shows that the original approach of Schauder is “correctable.” As it stands, the proof of the fixed-point property is very much complex. Now, knowing that the simplicial approximation property holds for every \( X \), it is reasonable to ask for a simple way of verifying it.

According to a result of [10], every noncompact convex subset \( C \) of a metric linear space contains a topological copy of \([0, \infty)\) (this observation, for the normed case, was made long before by Klee [22]). As easily observed, it follows
that such a $C$ fails the fixed-point property. Combining this with Cauty’s result, we infer that for convex subsets of metric linear spaces, only compacta have the fixed-point property. On the other hand, there are examples of noncompact convex subsets of locally convex topological vector spaces that do have the fixed-point property, see [10, Example 4.1].

Cauty has extended his technique to show the fixed-point property for compacta that are uniformly contractible. Recall that a space $X$ is locally uniformly contractible if there exists a continuous map $\mu(x, y; t)$ (which is referred to as an equiconnecting map) defined for all $(x, y)$ in a neighborhood $U$ of the diagonal in $X \times X$ and $t \in I = [0, 1]$, such that $\mu(x, y; 0) = x$, $\mu(x, y; 1) = y$, and $\mu(x, x; t) = x$ for all $(x, y; t) \in U \times I$. If $U$ can be taken as the whole $X \times X$, then $X$ is called uniformly contractible. All convex sets are uniformly contractible. If $r : C \rightarrow X$ is a retraction of a convex set $C$ onto $X$, then $X$ is uniformly contractible because $\mu(x, y; t) = r((1 - t)x + ty)$ is as required. If a topological group $G$ is contractible, that is, there exists a homotopy $H : G \times I \rightarrow G$ such that $H(g, 0) = g$ and $H(g, 1) = e$ ($e$ is the unit element of $G$) for all $(g, t) \in G \times I$, then $G$ is uniformly contractible via $\mu(g, h; t) = (H(e, t))^{-1} \cdot H(g \cdot h^{-1}, t) \cdot h$, see [7]. It follows that every retract of such a $G$ is uniformly contractible. On the other hand, a metrizable uniformly contractible compactum is a retract of a contractible metrizable topological group [3]. Generalizing the classical Lefschetz-Hopf fixed-point theorem, Cauty [4] has shown that every self-map $f$ of a locally uniformly contractible compactum $X$ has a fixed-point if the Lefschetz number $\Lambda(f) \neq 0$. In particular, all uniformly contractible compacta have the fixed-point property. Necessary modifications for obtaining the proof of this fact are presented at the end of Section 2 (see also the end of Section 3). Observe that every uniformly contractible compactum is a contractible and locally contractible space. The question of whether a contractible and locally contractible metrizable compactum has the fixed-point property remains unanswered.

For the locally convex case, the fixed-point property of $X$ yields, for an upper semicontinuous (USC) convex-valued map $F : X \Rightarrow X$, the fixed-point property of $F$, that is, there exists $x \in X$ such that $x \in F(x)$. (Here, by a convex-valued map $F$, we mean a multivalued map such that $F(x)$ is a convex compactum; such a map is USC if $\{x \in X \mid F(x) \subset U\}$ is open for every open set $U \subset X$.) Again, known techniques require partitions of unity, a tool that does not work for the nonlocally convex case. Our approach enabled us to show that, for every dense convex subset $C$ of the convex compactum $X$, every map $f : C \rightarrow X$ admits approximate fixed-points; that is, there exists a sequence $(x_n) \subset C$ such that $\lim \|f(x_n) - x_n\| = 0$, see Corollary 2.6. In [9], we used this fact, together with yet another approximation result that was based on a certain technique developed by Cellina-Lasota [6], to obtain the fixed-point property for every USC convex-valued map $F$ of a compact convex set of an arbitrary topological vector space. The details of such a generalization of Cauty’s result go beyond the scope of this paper and will not be included here. For the record, we mention that
the convex-valued case has been established, among others, by Kakutani [20], Bohnenblust and Karlin [2], Fan [15], and Glicksberg [16].

This introduction alludes to the author’s observations that were made while revisiting Cauty’s paper [5]. It contains only a handful of historical remarks on the fixed-point property of convex compacta that were needed to put those observations in some historical perspective. The author did not intend to make an expository paper on the subject with such overwhelming literature.

2. The simplicial approximation property

Following [21], we say that a convex set $C \subset E$ has the simplicial approximation property if for every $\varepsilon > 0$, there exists a finite-dimensional compact convex set $C_\varepsilon \subset C$ such that if $S$ is any finite-dimensional simplex in $C$ (i.e., $S$ is a convex hull of finitely many vectors in $C$), then there exists a continuous map $\gamma : S \to C_\varepsilon$ with $\| \gamma(x) - x \| < \varepsilon$, $x \in S$. According to [21, Remark (2), page 217] (see also [11, Lemma 5.1]), if a convex compactum $X$ has the simplicial approximation property, then it has the fixed-point property. We have the following obvious generalization of that fact.

**Lemma 2.1.** Assume that a convex set $C \subset E$ has the simplicial approximation property. Then every map $f : C \to \bar{C}$ has an approximate fixed-point, that is, $\lim \| f(x_n) - x_n \| = 0$ for some sequence $(x_n) \subset C$.

**Proof.** According to the definition above, for each $n \in \mathbb{N}$, pick a convex compactum $C_n \subset C$ such that for a simplex $S$, we have a sequence $\gamma_n : S \to C_n$ with $\lim \| \gamma_n - \text{id}_S \| = 0$. Approximate $f \mid C_n$ by a map $f_n : C_n \to S$, where $S$ is a simplex in $C$, see [7]. By Brouwer fixed-point theorem, there exists $x_n \in C_n$ such that $\gamma_n(f_n(x_n)) = x_n$. It is easy to see that $\lim \| f(x_n) - x_n \| = 0$. □

Say that a convex set $C \subset E$ has the $\aleph_0$-simplicial approximation property if for every $\varepsilon > 0$, there exists a countable-dimensional convex set $C_\varepsilon \subset C$ such that if $S$ is any $\aleph_0$-simplex in $C$ (i.e., $S$ is a convex hull of countable many vectors of $C$), then there exists a relatively compact map $\gamma : S \to C_\varepsilon$ with $\| \gamma(x) - x \| < \varepsilon$, $x \in S$. Actually, this property is equivalent to the one that requires $C_\varepsilon$ to be an $\aleph_0$-simplex. To see this, use the separability of $E$ to find an $\aleph_0$-simplex $C'_\varepsilon \subset C_\varepsilon$ that is dense in $C_\varepsilon$. Now, let $\gamma$ be a relatively compact map of $S$ into $C_\varepsilon$. Using the fact that $C_\varepsilon$ is countable dimensional, find a map of $C_\varepsilon$ into $C'_\varepsilon$ that is as close to the identity as we wish, see [7]. Composing this map with $\gamma$, we obtain a relatively compact map of $S$ into $C'_\varepsilon$.

**Lemma 2.2.** If a convex set $C \subset E$ has the $\aleph_0$-simplicial approximation property, then it has the simplicial approximation property.

**Proof.** Fix $\varepsilon > 0$. Use the above modification of the $\aleph_0$-simplex approximation property to find, for $\varepsilon/3$, an $\aleph_0$-simplex $C_\varepsilon \subset C$ as required in the definition. Let
γ₀ : Cₑ → Cₑ be a relatively compact map with ∥γ₀(x) − x∥ < ε/3, x ∈ Cₑ. There exists a map g : γ₀(Cₑ) → Cₑ whose range is contained in a finite-dimensional compact convex set Kₑ and that satisfies ∥g(x) − x∥ < ε/3 for all x, see [7, Lemma 2]. Now, let S be a finite-dimensional simplex in Cₑ. Assuming that Cₑ is dense (here we employ the separability of E), we find a map g : γ₀(Cₑ) → Cₑ whose range is contained in a finite-dimensional compact convex set Kₑ and that satisfies ∥g(x) − x∥ < ε/3 for all x, see [7, Lemma 2].

Now, let S be a finite-dimensional simplex in Cₑ. Then, the composition g ◦ γ₀ ◦ γ₀ : S → Kₑ is as required.

□

Remark 2.3. Replacing the convexity assumption on Cₑ by the assumption that Cₑ ∈ ANR, we obtain a weaker version of the ℵ₀-simplicial approximation property. Such a weaker property also yields the approximate fixed-point property of Cₑ. To see this, we employ the ANR property of Cₑ (use a factorization of an ANR through a locally finite-dimensional, locally compact, separable space) to approximate a map Cₑ → Cₑ by one whose range is S, an ℵ₀-simplex. Next, using the contractibility of S, we extend this map to c(Cₑ), the metric cone over Cₑ. Composing such a map with a relatively compact γ : S → Cₑ ⊂ c(Cₑ), which is provided by the definition (of such a weaker version of the ℵ₀-simplicial approximation property), we obtain a relatively compact self-map of c(Cₑ). An application of the so-called generalized Schauder theorem (stating that every relatively compact self-map of an AR space has the fixed-point property [13, page 94]) yields a fixed-point xe ∈ Cₑ, which is a counterpart of xn that was obtained in the proof of Lemma 2.1.

Below, we state the main technical ingredient of Cauty’s proof that establishes a property which, in a sense, is equivalent to the ℵ₀-simplicial approximation property of X.

Proposition 2.4 (cf. [5, Lemma 3]). For the convex compactum X, there exist a countable-dimensional compactum Z and a map ϕ : Z → X such that, if Z is embedded onto a linearly independent subset of a metric linear space (F, |·|) so that the affine extension ˆϕ : conv(Z) → X of ϕ is continuous (the existence of such an embedding is ensured by Lemma 2.5 below), then, for every ε > 0, every separable metrizable space Y ∈ ANR, and every map ξ : Y → X, there exists a map

η : Y → conv(Z) (2.1)

such that

(i) ˆϕ(η(y)) − ξ(y)∥ < ε for all y ∈ Y,
(ii) η(Y) ∪ conv₂(Z) is a compact subset of conv(Z); hence, η is relatively compact.

Here by conv₂(Z), we mean \{t₁z₁ + t₂z₂ | z₁, z₂ ∈ Z, 0 ≤ t₁, t₂ ≤ 1, t₁ + t₂ = 1\}.

Lemma 2.5. Given a map ϕ : Z → X of a compactum Z, there exists a metric linear space (F, |·|) topologically containing Z as a linearly independent subset such that
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\[ \hat{\phi} \colon \text{conv}(Z) \to X \text{ defined by} \]

\[ \hat{\phi} \left( \sum_{i=1}^{k} t_i z_i \right) = \sum_{i=1}^{k} t_i \phi(z_i), \quad (2.2) \]

where \( \sum_{i=1}^{k} t_i = 1, t_i \geq 0, k \in \mathbb{N}, \) is continuous.

Proof of Lemma 2.5. Embed Z onto a linearly independent subset of \( (\ell_2, || \cdot ||) \). Extend \( \phi \) to a linear (not necessarily continuous) map \( \hat{\phi} : \ell_2 \to E \).

Define an \( F \)-norm on \( \ell_2 \) by

\[ |x| = ||x|| + ||\hat{\phi}(x)||. \quad (2.3) \]

Let \( F = (\ell_2, | \cdot |) \). Then \( \hat{\phi} : F \to E \) is continuous, and \( (Z, | \cdot |) \) yields the original topology of Z.

Corollary 2.6 (cf. [8, Theorem]). Every convex set \( C \subset E \) with a compact closure \( X \) has the \( \aleph_0 \)-simplicial approximation property. Consequently, by Lemma 2.1, every map \( f : C \to X \) has an approximate fixed-point.

Proof. Let Z, \( \varphi \), and \( \hat{\phi} \) be that of Proposition 2.4. Fix \( \varepsilon > 0 \). Since the compactum Z is countable dimensional, so is \( \text{conv}(Z) \). An application of an argument of [7] shows that there exist an \( \aleph_0 \)-simplex \( X_\varepsilon \subset C \) and a map \( \varphi_\varepsilon : \text{conv}(Z) \to X_\varepsilon \) such that \( ||\hat{\phi}(z) - \varphi_\varepsilon(z)|| < \varepsilon/2, z \in \text{conv}(Z) \). Let S be \( \aleph_0 \)-simplex in C. By a theorem of Haver [17] (see also [7, Note 4]), we have \( S \in \text{AR} \). Apply Proposition 2.4 to \( Y = S \) and to \( \xi \), the inclusion of \( S \) into \( X \). There exists a relatively compact \( \eta : S \to \text{conv}(Z) \) with \( ||\hat{\phi} \circ \eta(x) - x|| < \varepsilon/2, x \in S \). Let \( y = \varphi_\varepsilon \circ \eta : X \to X_\varepsilon \). We have that \( ||y(x) - x|| \leq ||\varphi_\varepsilon \circ \eta(x) - \hat{\phi} \circ \eta(x)|| + ||\hat{\phi} \circ \eta(x) - x|| \leq \varepsilon/2 + \varepsilon/2 = \varepsilon. \)

Proof of Theorem 1.1. Applying Corollary 2.6, we conclude that \( f \) has an approximate fixed-point. By the compactness of \( X \), \( f \) has a fixed-point.

Reduction Fact 2.7. The assertion of Proposition 2.4 holds provided it does hold for the class of spaces \( Y \) that are separable, metrizable, locally finite dimensional, and locally compact.

Proof. Let \( Y \) be an arbitrarily separable, metrizable ANR, let \( \xi : Y \to X \) be a map, and let \( \varepsilon > 0 \). By [18, page 138], there exist a countable locally finite simplicial complex \( |N| \) (considered in the metric topology) and maps

\[ \alpha : Y \to |N|, \quad \beta : |N| \to Y \quad (2.4) \]

such that

\[ ||\xi(\beta \circ \alpha(y)) - \xi(y)|| < \frac{\varepsilon}{2}, \quad (2.5) \]
We see that \( t \) is easily seen that \( \hat{\eta}(p) = \xi(y) \) if \( \hat{\eta}(\alpha(y)) \) is such a simplex. In this way, Proposition 2.4 establishes a convex subset (of a vector space) with a metric topology that makes the convex combination map \( \beta \rightarrow \xi(\beta \alpha(y)) - \xi(y) \) continuous. Such an extension \( \hat{\phi} : \conv(Z) \rightarrow X \), where \( \conv(Z) \) is a convex subset (of a vector space) with a metric topology that makes the convex combination map \( (z_1, z_2; t) \rightarrow (1 - t)z_1 + tz_2 \) continuous. Such an extension can be obtained by inspecting the proof of Lemma 2.5. As in that proof, we embed the compactum \( Z \) onto a linearly independent subset of \( \ell_2 \). Next, extend \( \phi \) to (not necessarily continuous) \( \hat{\phi} : \conv(Z) \rightarrow X \) that is \( \mu \)-affine. Finally, letting 

\[
d a \text{ for a metric on } X, \quad \rho(z_1, z_2) = \|z_1 - z_2\| + d(\phi(z_1), \phi(z_2)) \]

defines a required metric on \( \conv(Z) \), a convex subset of \( \ell_2 \). Before we show how to obtain \( \hat{\phi} \), for \( x_1, \ldots, x_n \in X \) and \( (t_1, \ldots, t_n) \in s_n = \{(t_1, \ldots, t_n) \mid t_i \geq 0 \text{ for all } i \text{ and } \sum_{i=1}^n t_i = 1\} \), we inductively let 

\[
\mu_n(x_1, \ldots, x_n; t_1, \ldots, t_n) = \mu_{n-1}(x_1, \ldots, x_{n-1}; t_1/(1 - t_n), \ldots, t_{n-1}/(1 - t_n)) \tag{2.6}
\]

if \( t_n \neq 1 \), and \( \mu_n(x_1, \ldots, x_n; t_1, \ldots, t_n) = x_n \) otherwise; set \( \mu_1(x_1; 1) = x_1 \). Now, well order the set \( Z \) by a relation \( < \) and, for \( z = \sum_{i=1}^n t_iz_i \) where \( (t_1, \ldots, t_n) \in s_n \) and \( z_1, \ldots, z_n \in Z \) with \( z_1 < \cdots < z_n \), define \( \hat{\phi}(z) = \mu_n(\phi(z_1), \ldots, \phi(z_n); t_1, \ldots, t_n) \). It is easily seen that \( \hat{\phi} \) is \( \mu \)-affine. Using the cross-section method (see [1, page 271]), we can show that \( \conv(Z) = (\conv(Z), \rho) \) is countable dimensional. Since \( \conv(Z) \) is locally contractible and contractible, by a theorem of Haver [17], \( \conv(Z) \in \AR \). To conclude the fixed-point property of \( X \) by such a generalized version of Proposition 2.4, we find a sequence of relatively compact maps \( (\eta_n) \) of \( Y = \conv(Z) \) with \( \lim \phi \circ \eta_n = f \circ \hat{\phi} \). By a generalized Schauder theorem [13, page 94], there exists \( y_n \in Y \) such that \( \eta(y_n) = y_n \). We can assume that the
sequence \((\phi(y_n))\) converges to \(x \in X\). Such an \(x\) is a fixed-point of \(f\) because \(f(x) = \lim f(\phi(y_n)) = \lim \phi(\eta_n(y_n)) = \lim \phi(y_n) = x\).

3. The proof of Proposition 2.4

This section contains the proof of Proposition 2.4. The proof will rely on Lemma 3.1, a purely topological fact, which is an abstraction on Cauty’s construction of the resolution \(\phi : Z \to X\) (that will be provided in Section 4). However, after completing the proof of Proposition 2.4, we give a rough sketch of the proof of Lemma 3.1 for the reader who is not interested in all details.

**Lemma 3.1.** Let \((X, d)\) be a metric space. There exist an inverse sequence \((Z_n, \pi_n^{n+1})\), where each \(Z_n\) is a (finite-dimensional) compactum, a map \(k_n : X \to Z_n\), a finite open cover \(\{W_\alpha | \alpha \in A(n)\}\) of \(Z_n\), \(n \in \mathbb{N}\), and a map \(\varphi : Z = \lim\ lim(Z_n, \pi_n^{n+1}) \to X\) that satisfy the following conditions:

1. \(Z\) is a countable-dimensional compactum;
2. \(d(\varphi(z), V_\alpha) \leq 2\Delta_n\) whenever \(\pi_n(z) \in W_\alpha\) and \(\alpha \in A(n)\), where \(\pi_n : Z \to Z_n\) is an obvious projection and \(V_\alpha = k_n^{-1}(W_\alpha), \alpha \in A(n)\);
3. \(\Delta_n = \sup \{\text{diam}_d(V_\alpha) | \alpha \in A(n)\}\) → \(\infty\) as \(n \to \infty\).

The space \(Z = \lim\ lim(Z_n, \pi_n^{n+1})\) is equipped with a metric \(d_Z\), a restriction of \(d_Z((x_n), (y_n)) = \sum_{n=1}^\infty 2^{-n}d_n(x_n, y_n)\) defined on \(\prod_{n=1}^\infty Z_n\), where each \(d_n\) is a compatible, bounded by 1, metric on \(Z_n\).

**Proof of Proposition 2.4.** The convex compactum \(X\) will be equipped with the metric \(d\) that is induced by an \(F\)-norm \(\|\cdot\|\). Lemma 3.1 provides us with a compactum \(Z\) and a map \(\varphi : Z \to X\) that satisfy (1), (2), and (3). (Further on, the countable dimensionality of \(Z\) will not be used.) Moreover, \(Z\) is assumed to be a linearly independent subset of a metric linear space \((F, |\cdot|)\) such that the affine extension \(\phi : \text{conv}(Z) \to X\) is continuous. Let \(\xi : Y \to X\) be a map, and let \(\varepsilon > 0\), \(\varepsilon \leq 1\). Applying Reduction Fact 2.7, we may assume that \(Y\) is a locally finite-dimensional, locally compact, separable, metrizable space. There exists an open cover \(\{Y_i\}_{i=1}^\infty\) such that, for every \(i\), \(Y_i\) is relatively compact, \(\text{dim}(Y_i) \leq i\), and \(Y_i \cap Y_j = \emptyset\) whenever \(|i - j| > 1\), see [14, page 291].

By the compactness of \(Z\), for each \(i\), there exists \(\delta_i > 0\) that satisfies

\[
\delta_i \leq \frac{\varepsilon}{2i + 3}, \quad d_Z(z, z') < \delta_i \implies |z - z'| < \frac{1}{2(2i + 3)}i \tag{3.1}
\]

for all \(z, z' \in Z\). Choose \(n_i \in \mathbb{N}\) such that \(n_{i-1} < n_i\) and \(\max(2^{-n_i}, \Delta_{n_i}) < \delta_i/3\). For \(i\) and for every \(1 \leq m \leq n_i\), define \(g_{n_i}^m = \{(\pi_{n_i}^m \circ k_{n_i} \circ \xi)^{-1}(B(z, 2^{-n_i})) | z \in Z_m\}\) (here, \(B(z, r)\) stands for the open \(d_m\)-ball in \(Z_m\) that is centered at \(z\) with radius \(r\)) and \(g_0^n = (k_{n_i} \circ \xi)^{-1}(W_\alpha) = \xi^{-1}(V_\alpha) | \alpha \in A(n_i)\). Write \(g_0 = \bigcap_{n=1}^{\infty} g_0^n\), and define \(g_i = g_0 \cap \bigcap_{n=1}^{n_i} g_0^n \cap \bigcap_{m=1}^{n_i} g_m^n, \text{an open cover of } Y\). Here, for open covers \(\mathcal{A}, \ldots, \mathcal{A}_p\), we designate \(\mathcal{A}_1 \cap \cdots \cap \mathcal{A}_p = \{A_1 \cap \cdots \cap A_p | A_i \in \mathcal{A}_i, i = 1, \ldots, p\}\). Pick an open cover \(\mathcal{U}\) that is a
star refinement of $\mathcal{G}$. Using the fact $\dim Y_i \leq i$, find a partition of unity $\{\lambda_U\}_{U \in \mathcal{U}}$ such that $\text{supp}(\lambda_U) = \lambda^{-1}((0,1]) \subset U$ and $\bigcap_{k=1}^{n+2} \text{supp}(\lambda_{U_k}) = \emptyset$ if each $U_k$ is a subset of $Y_i$. For each $U \in \mathcal{U}$, choose the smallest $i \in \mathbb{N}$ with $U \subset Y_i$, and pick $z_U \in Z$ such that $\pi_{n_i}(z_U) \in k_{n_i} \circ \xi(U)$. Define $\eta(y) = \sum_{U \in \mathcal{U}} \lambda_U(y)z_U$, $y \in Y$.

Fix $y \in Y$ and write $A(y) = \{U \mid y \in \text{supp}(\lambda_U)\}$. Suppose $i \in \mathbb{N}$ is the first index such that $y \in Y_i$. It may happen that $y \in Y_{i+1}$. Consequently, the cardinality of $A(y)$ is at most $2i + 3$. It also follows that $U(y) = \bigcup\{U \mid U \in A(y)\} \subset Y_i \cup Y_{i+1}$. We conclude that for each $l = n_i$ or $n_{i+1}$, there exists $a(l) \in A(l)$ such that $U(y) \subset (k_l \circ \xi)^{-1}(W_{a(l)})$. On the other hand, for each $U \in A(y)$ and for a certain index $l$, we have $\pi_l(z_U) \in k_l \circ \xi(U)$; so, we have $U \subset (k_l \circ \xi)^{-1}(W_\alpha) = \xi^{-1}(V_\alpha)$ and $\pi_l(z_U) \in k_l \circ \xi(U) \subset W_\alpha$ for $\alpha \in A(l)$, where $l = n_i$ or $l = n_{i+1}$. It shows that $\xi(y) \in V_\alpha$ and, by (2) of Lemma 3.1, that $d(\varphi(z_U), V_\alpha) \leq 2\Delta_l$; hence, $\|\varphi(z_U) - \xi(y)\| \leq 3\Delta_l < \max(\delta_i, \delta_{i+1})$ because $l$ is either $n_i$ or $n_{i+1}$. We can estimate

$$
\| \varphi(\eta(y)) - \xi(y) \| = \left\| \sum_{U \in A(y)} \lambda_U(y)(\varphi(z_U) - \xi(y)) \right\| \\
\leq (2i + 3)\| \varphi(z_U) - \xi(y) \| \\
\leq (2i + 3) \max(\delta_i, \delta_{i+1}) \\
\leq \varepsilon.
$$

The last inequality follows from the first part of (3.1). This shows (i).

To show (ii), we first partition the family $A(y)$ into $A^1(y)$ and $A^2(y)$; $U \in A^1(y)$ if and only if $i + j - 1$ is the first index so that $U \subset Y_{i+j-1}$, $j = 1, 2$. As previously, for each $l = n_i$ or $n_{i+1}$ and $m \leq l$, there exists $z_{(l,m)} \in Z_m$ such that

$$
U(y) \subset (\pi_m \circ k_l \circ \xi)^{-1}(B(z_{(l,m)}, 2^{-i})) = (k_l \circ \xi)^{-1}(\pi_m^{-1}(B(z_{(l,m)}, 2^{-i}))).
$$

Hence, if $\pi_l(z_U) \in k_l \circ \xi(U)$, then $\pi_m(z_U) \in B(z_{(l,m)}, 2^{-i})$. It follows that, given $m$ with $1 \leq m \leq n_i$, $\pi_m(z_U) \in B(z_{(n,m)}, 2^{-n_i})$ for all $U \in A^1(y)$; so, $\text{diam}_{d_m}(\pi_m(z_U) \mid U \in A^1(y)) \leq 2^{-n_i}$. Since

$$
\text{diam}_{d_z}(S) \leq \sum_{m=1}^{\infty} 2^{-m} \text{diam}_{d_m}(\pi_m(S)) \\
\leq \left( \sum_{m=1}^{n_i} 2^{-m} \text{diam}(S) \right) + 2^{-n_i}
$$

for every $S \subset Z$, we conclude that $\text{diam}_{d_z}(z_U \mid U \in A^1(y)) \leq 2^{-n_i} + 2^{-n_i} \leq \delta_i$. In a similar way, we show that $\text{diam}_{d_z}(z_U \mid U \in A^2(y)) \leq 2^{-n_{i+1}} + 2^{-n_{i+1}} \leq \delta_{i+1}$. Hence, by the second part of (3.1),

$$
|z_{U_i} - z_{U_i'}| < \frac{1}{2(2i + 3)i}, \quad |z_{U_2} - z_{U_2'}| < \frac{1}{2(2i + 5)(i + 1)}
$$

(3.5)
for all \( z_{U_i}, z'_{U_i} \in A^1(y) \) and all \( z_{U_j}, z'_{U_j} \in A^2(y) \). Fix \( z_{U_j} \), where \( U_j \in A^j(y) \), and let \( t_j = \sum \{ \lambda_U(y) \mid U \in A^j(y) \} \), \( j = 1, 2 \). From (3.5), we obtain

\[
|\eta(y) - (t_1 z_{U_1} + t_2 z_{U_2})| = \left| \sum_{U \in A(y)} \lambda_U(y)(z_U - z_{U_1}) + \sum_{U \in A^2(y)} \lambda_U(y)(z_U - z_{U_2}) \right| \\
\leq (2i + 3) \left( \frac{1}{2(2i + 3)i} + \frac{1}{2(2i + 5)(i + 1)} \right) < \frac{1}{i}.
\]  

(3.6)

Now, if \( \{ \eta(y_k) \} \) is a sequence in \( \text{conv}(Z) \), then either \( \{ y_k \} \) has a subsequence contained in some \( Y_i \) (this subsequence, in turn, contains a convergent subsequence because \( \eta(Y_i) \) is compact), or else it contains a subsequence \( \{ y_{i(n)} \} \) such that \( y_{i(n)} \in Y_{i(n)} \) for all \( n \). In the latter instance, from the above estimate, we have \( |\eta(y_{i(n)})| \leq \frac{1}{i(n)} \) for some \( t_n^1, t_n^2 \geq 0 \) with \( t_n^1 + t_n^2 = 1 \) and some \( z_n^1, z_n^2 \in Z \). By the compactness of \( Z \), it now easily follows that \( \{ \eta(y_{i(n)}) \} \) contains a subsequence that converges to \( \text{conv}_2(Z) \). Since \( \text{conv}_2(Z) \) is compact, (ii) is shown.

In what follows, we present a general overview of the argument that justifies Lemma 3.1. More precisely, we give a sketch of the proof of Lemma 3.1 assuming that \( \{ V_\alpha \} \) and the inverse sequence \( \{ Z_n, \pi^{n+1}_n \} \) satisfy conditions (3.7), (3.8), and (3.9). We will not comment on the construction of the sequence \( \{ Z_n, \pi^{n+1}_n \} \). This will be done in Section 4.

Remark 3.2. The continuity of \( \phi \) is easily obtained from condition (2) of Lemma 3.1 as follows. For every \( n \), \( \{ \pi^{-1}_n(W_\alpha) \mid \alpha \in A(n) \} \) is an open cover of \( Z \). If \( z, z' \in \pi^{-1}_n(W_\alpha) \), then \( d(\phi(z), \phi(z')) \leq d(\phi(z), \bar{V}_\alpha) + \text{diam}(\bar{V}_\alpha) + d(\phi(z'), \bar{V}_\alpha) \leq 5\Delta_n \to 0 \).

Now, we first define \( \phi \) in case (3.7) holds.

Remark 3.3. Fix \( z \in Z \) and let \( A(z) = \{ \alpha \in A(n) \mid \pi_n(z) \in W_\alpha \} \). Define \( F_n(z) = \bigcap \{ \bar{V}_\alpha \mid \alpha \in A(z) \} \). Assume

\[
d_H(F_n(z), F_m(z)) \leq 2\Delta_n
\]

(3.7)

for \( 1 \leq n \leq m \) (here, \( d_H \) stands for the Hausdorff metric induced by \( d \)). Let \( \phi(z) = x \), where \( \{ x \} = \lim_{d_H} F_n(z) \). Note that (3.7), together with condition (3) of Lemma 3.1, implies that the sequence \( \{ F_n(z) \} \) converges to a singleton in the hyperspace of \( X \); hence, \( \phi \) is well defined. On the other hand, \( F_n(z) \subset \bar{V}_\alpha \) for all \( \alpha \in A(z) \). Applying (3.7) again, we easily obtain (2) of Lemma 3.1.

Next, we indicate how the countable dimensionality of \( Z \) can be achieved (here, we can compare this argument with that of Zarichnyi [30]). We stress that the countable dimensionality of \( Z \) is essential for deducing Corollary 2.6 from Proposition 2.4.
Remark 3.4. Suppose that each $Z_n$ is a tower of compacta $Z_n^k$ (in Section 4, denoted by $\mathcal{M}_n^k$), $0 \leq k < n$, such that

$$\dim(Z_n^k) \leq k, \quad (\pi_n^{n+1})^{-1}(Z_n^k) \subset Z_{n+1}^k \quad (3.8)$$

for every $0 \leq k < n$. Furthermore, suppose $Z_n \setminus Z_n^{n-1} = \bigcup \mathcal{U}_n$ for a certain family $\mathcal{U}_n = \{U_\beta \mid \beta \in B(n)\}$ that consists of finite, pairwise disjoint open subsets of $Z_n$ with

$$\text{diam}_{dm}(\pi_n^m(U_\beta)) \leq 2^{-n+1} \quad (3.9)$$

for every $0 \leq m < n$ and $\beta \in B(n)$. Then, we have $Z = P_0 \cup \bigcup_{n=1}^{\infty} P_n$, where $P_0 = \bigcap_{n=1}^{\infty} \pi_n^{-1}(\bigcup \mathcal{U}_n)$ and $P_n = \pi_n^{-1}(Z_n^{n-1})$. Since condition (3.9) yields $\text{diam}_{dm}(\pi_n^{-1}(U_\beta B)) < 2^{-n+2}$ for every $\beta \in B(n)$, $n \in \mathbb{N}$, it follows that for every $n$, $P_0$ can be covered by the finite family $\{\pi_n^{-1}(U_\beta) \mid \beta \in B(n)\}$ which consists of open pairwise disjoint sets of diameter $< 2^{-n+2}$; hence, $\dim(P_0) \leq 0$. On the other hand, it can be easily checked that $P_n = \pi_n^{-1}(Z_n^{n-1})$ is merely a uniformly contractible compactum, the proof of Proposition 2.4 requires the following adjustments (that were initiated at the end of Section 2). Formally, the definition of $\eta$ is the same, but to guarantee Proposition 2.4(i) and (ii), we must modify the choice of $\delta_i$ made in condition (3.1). Assuming $\delta_{i+1} \leq \delta_i$, it suffices to have $d(\mu_{2i+3}(x_1, \ldots, x_{2i+3}; t_1, \ldots, t_{2i+3}), x) \leq \epsilon$ for $d(x_i, x) < \delta_i$ and $i = 1, \ldots, 2i + 3$, and $\rho(t_1 z_1 + \cdots + t_{2i+5} z_{2i+5} + t'_1 z'_1 + \cdots + t'_{2i+5} z'_{2i+5}, tz + t'z') < 1/i$ for $d_Z(z, z) < \delta_i$ and $d_Z(z'_i, z') < \delta_i$, $i = 1, \ldots, 2i + 5$, where $(t_1, \ldots, t_{2i+5}, t'_1, \ldots, t'_{2i+5}) \in \mathcal{S}_{4i+10}$ and $t = \sum_{i=1}^{2i+5} t_i$, $t' = \sum_{i=1}^{2i+5} t'_i$. 

4. The proof of Lemma 3.1

We begin with a statement of the three main points of Cauty’s original construction of $\varphi : Z \to X$. Having done this, we show how Lemma 3.1 can be deduced. The detailed Cauty’s construction is performed in Sections 4.1 and 4.2.

Step 1. With the metric compactum $X = (X, d)$, we associate an inverse sequence $(K_n, q_n)$ of finite simplicial complexes $K_n$, $\dim(K_n) \leq n$, which are nerves of certain open finite covers $\mathcal{V}_n = \{V_\alpha \mid \alpha \in A_n\}$ of $X$, which is indexed in such a way that $\alpha \neq \alpha'$ implies $V_\alpha \neq V_{\alpha'}$. Writing $K_n = \text{nerv}(\mathcal{V}_n)$, we identify elements of $A_n$ with the vertices of $K_n$. Later, the set of the vertices of $K$ is denoted by Vert($K$); for a vertex $\alpha \in \text{Vert}(K)$, $\text{st}(\alpha, K)$ stands for the open star of $\alpha$ in $|K|$, the body of $K$. We further assume that

(K1) $\mathcal{V}_{n+1} \subset \mathcal{V}_n$ (i.e., $\mathcal{V}_{n+1}$ is inscribed in $\mathcal{V}_n$) and the simplicial map $q_n : K_{n+1} \to K_n$ is onto, which is a consequence of (K2);
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(K2) each canonical map

\[ \psi_n : X \rightarrow |K_n| \]  \hspace{1cm} (4.1)

is onto; recall that \( \psi_n^{-1}(\text{st}(\alpha, K_n)) = V_\alpha, \alpha \in A; \)

(K3) \( \dim(K_n) \leq n; \)

(K4) \( \Delta_n = \sup\{\text{diam}_d(V_\alpha) \mid \alpha \in A_\} \rightarrow 0 \) as \( n \rightarrow \infty. \)

We are not going to elaborate on justifying the assertion of this step which, in a sense, belongs to the topological folklore (see [23, 24, 27]). Note that though we could have additionally arranged \( X = \lim\leftarrow (K_n, q_n) \), we do not request that. Our objective is just the opposite: to “modify” this inverse sequence in order to get a countable-dimensional compactum as its limit.

**Step 2.** The space \( Z \) is constructed as the inverse limit of the sequence \( (Z_n, \pi_{n+1}) \) of finite-dimensional compacta \( Z_n \) so that \( |K_n| \subset Z_n \) and \( |K_n| \) is a retract of \( Z_n; \) that is, there exists a retraction \( \rho_n : Z_n \rightarrow |K_n| \). Moreover, we have

\[ \pi_{n+1}(|K_{n+1}|) \supset |K_n| \]  \hspace{1cm} (4.2)

for every \( n \). The compactum \( Z_n \) is built in two stages; first, we enlarge \( K_n \) to yet another finite complex \( M_n = M(K_n(k), n), \) and then the body \( |M_n| \) is enlarged to the compactum \( Z_n. \) Write \( \pi_n : Z = \lim(Z_n, \pi_{n+1}) \rightarrow Z_n \) for the natural projection. Condition (4.2) guarantees that \( \pi_n(Z) \supset |K_n| \) for every \( n \).

**Step 3.** For a point \( z \in Z \), we define a subcompact \( F_n(z) \subset X \) as follows. To \( z \) we assign the smallest simplex \( s_n(z) \in K_n \) containing \( \rho_n \circ \pi_n(z). \) Then \( F_n(z) = \bigcap \{V_\alpha \mid V_\alpha \in \mathcal{V}_n \text{ is a vertex of } s_n(z)\}. \) For every \( z, \) the sequence of compacta \( (F_n(z)) \) is convergent to a singleton; we set

\[ \varphi(z) = \lim_n F_n(z). \]  \hspace{1cm} (4.3)

**Lemma 4.1**, a counterpart of **Lemma 3.1**, contains a fact that is detached from Cauty’s original work related to the construction of \( \varphi : Z \rightarrow X. \) Following the statement, we note that actually **Lemma 4.1** implies **Lemma 3.1**; this shows that the original construction of Cauty yields **Lemma 3.1**. The proof of **Lemma 4.1** will be given in Sections 4.1 and 4.2.

**Lemma 4.1.** Steps 1, 2, and 3 can be performed in order, for \( Z = \lim(Z_n, \pi_{n+1}^n) \), to be a countable-dimensional compactum and, for the map \( \varphi : Z \rightarrow X, \) to satisfy the following condition:

\[ d(\varphi(z), V_\alpha) \leq 2\Delta_n \]  \hspace{1cm} (4.4a)

for all \( z \in Z \) and all \( \alpha \in A_\), such that \( \rho_n \circ \pi_n(z) \in \text{st}(\alpha, K_n). \)
Proof of Lemma 3.1. Let $K_n, \{V_\alpha \mid \alpha \in A_n\}, \rho_n,$ and $\psi_n$ be that of Lemma 4.1. Designate $W_\alpha = \rho_n^{-1}(\text{st}(\alpha, V_\alpha))$, $A(n) = A_n$, and $k_n = \psi_n$. We see that $\psi_n^{-1}(W_\alpha) = \psi_n^{-1}(\text{st}(\alpha, V_\alpha)) = V_\alpha$ for $\rho_n \circ \pi_n(z) \in \text{st}(\alpha, K_n)$ if and only if $\pi_n(z) \in \rho_n^{-1}(\text{st}(\alpha, K_n)) = W_\alpha$. Now, conditions (1), (2), and (3) of Lemma 3.1 follow from (K4) and (4.4a) of Lemma 4.1.

Note 4.2. In deriving Proposition 2.4 from Lemma 4.1, the full power of (4.4a) is needed only to show the continuity of $\varphi$. (As in Remark 3.2, for every $n, \{(\rho_n \circ \pi_n)^{-1}(\text{st}(\alpha, K_n)) \mid \alpha \in A_n\}$ is an open cover of $Z$. Now, if $z, z' \in (\rho_n \circ \pi_n)^{-1}(\text{st}(\alpha, K_n))$, then $d(\varphi(z), \varphi(z')) \leq d(\varphi(z), \bar{V}_\alpha) + \text{diam}(\bar{V}_\alpha) + d(\varphi(z'), \bar{V}_\alpha) \leq 5\Delta_n$. Since $\lim \Delta_n = 0$, the continuity of $\varphi$ follows.) The remaining part of the proof of Proposition 2.4 employs the following weaker version of condition (4.4a):

$$d(\varphi(z), \bar{V}_\alpha) \leq 2\Delta_n$$

for all $z \in Z$ and all $\alpha \in A_n$, such that $\pi_n(z) \in |K_n|$ and $\pi_n(z) \in \text{st}(\alpha, K_n)$.

4.1. The compactum $Z$. In this subsection, which is split in a few units, we gradually provide details related to the statement of Step 2.

4.1.1. Construction and properties of $M(K, n)$. Let $K$, a finite complex, and $n = 0, 1, 2, \ldots$ be given so that $\dim(K) \leq n$. For a simplex $\sigma \in K$, $b_\sigma$ denotes the barycenter of $\sigma$. By $K^{(1)}$ we denote the first barycentric subdivision of $K$ ($K^{(1)}$ denotes the first barycentric subdivision of $K$); $K^{(1)}$ consists of simplices $(b_{\sigma_0}, \ldots, b_{\sigma_k})$ where $\sigma_0 \leq \cdots \leq \sigma_k$ (i.e., $\sigma_0 \subseteq \cdots \subseteq \sigma_k$), $\sigma_j \in K$. Mimicking this pattern, we construct a finite simplex $M(K, n)$ associated with $K$ and $n$. We let

$$\text{Vert}(M(K, n)) = \{ v = (b_\sigma, m) \mid \sigma \in K, m \in \{ \dim(\sigma), 1 + \dim(\sigma), \ldots, n \} \}.$$  \hspace{1cm} (4.5)

A finite set of vertices $\{v_0 = (b_{\sigma_0}, m_0), \ldots, v_k = (b_{\sigma_k}, m_k)\}$ is a simplex of $M(K, n)$ if

$$\sigma_0 \leq \cdots \leq \sigma_k, \quad m_0 < \cdots < m_k.$$  \hspace{1cm} (4.6)

The retraction $r = r(K, n): M(K, n) \to K^{(1)}$. Define $r((b_\sigma, m)) = b_\sigma$ to obtain a simplicial map of $M(K, n)$ onto $K^{(1)}$. Identifying $K^{(1)}$ with a subcomplex $M(K, n)$ generated by the vertices $(b_\sigma, \dim(\sigma))$, we see that such $r = r(K, n)$ is a simplicial retraction of $M(K, n)$ onto $K^{(1)}$.

The subcomplex $M^k(K, n)$. For $0 \leq k \leq n$, define $M^k(K, n)$ as a subcomplex of $M(K, n)$ generated by the vertices $(b_\sigma, m)$ with $m \leq k$. Notice that $K^{(1)} \subset M^{\dim(\sigma)}(K, n)$ and $M^n(K, n) = M(K, n)$. 

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The map \( v(x) = v(K,n)(x) \). For \( x \in |M(K,n)| \), define

\[
    v(x) = \sum \{ t_v(x) \mid v = (b_\sigma,m) \in \text{Vert}(M(K,n)) \text{ with } m > \dim(\sigma) \}, \tag{4.7}
\]

where \( t_v(x) \) stands for the \( v \)th barycentric coordinate of \( x \). Note that \( v||K| = 0 \).

The following lemma shows that \( K^{(1)} \) is a deformation retract of \( M(K,n) \); furthermore, there exists a deformation (whose other technical properties are listed below) that preserves the fibres of \( r \).

**Lemma 4.3** (cf. [5, Lemma 4]). *There exists a homotopy \( H : |M(K,n)| \to |M(K,n)| \) satisfying*

(i) \( H(x,0) = x \) for every \( x \in |M(K,n)| \) and \( H(x,t) = x \) for every \( x \in |K| \) and \( 0 \leq t \leq 1 \),

(ii) \( H(x,1) = r(x) \) for every \( x \in |M(K,n)| \),

(iii) \( (\text{for all } x,t \in |M(K,n)| \times [0,1]) [r(H(x,t)) = r(x)] \),

(iv) \( (\text{for all } 0 \leq k \leq n) [x \in |M^k(K,n)| \Rightarrow H(x,t) \in |M^k(K,n)|] \),

(v) \( (\text{for all } 0 \leq k \leq n) [x \in |M^k(K,n)| \Rightarrow H(x,t) = H(x,k/n) = H(x,1) \text{ if } k/n \leq t \leq 1] \),

(vi) \( (\text{for all } x \in |M(K,n)| \text{)} [t \to v(H(x,t)) \text{ is decreasing}] \),

(vii) \( (\text{for all } x \in |M(K,n)| \text{)} (\text{for all } t \in [0,1]) (\text{for all } v = (b_v,m)) [t_v(H(x,t)) \neq 0 \Rightarrow m = \dim(\tau) \text{ or } m \leq k], \text{ where } k = \max \{ m \mid v = (b_\sigma,m) \text{ with } m > \dim(\sigma) \text{ and } t_v(x) \neq 0 \} \),

(viii) \( (\text{for all } x \in |M(K,n)|\text{)} (\text{for all } v = (b_\sigma,m) \in \text{Vert}(M(K,n)) \text{ with } m > 0) [t_v(x) > 0 \text{ and } \dim(\sigma) < m \Rightarrow ((m-1)/n,m/n) \ni t \Rightarrow t_v(H(x,t)) \text{ linearly decreases to zero}] \) in the remaining case (i.e., whenever \( t_v(x) = 0 \) or \( \dim(\sigma) = m \)) for every \((m-1)/n \leq t \leq m/n\), \( t_v(H(x,t)) \text{ is constant} \).

**Proof.** Letting \( H(x,0) = x \), we first define \( H \) over the interval \( 0 \leq t \leq 1/n \). Namely, for \( v = (b_\sigma,m) \in \text{Vert}(M(K,n)) \), we let \( H(v,t) = v \) if \( m = \dim(\sigma) \), and \( H(v,t) = (1-nt)(b_\sigma,m) + nt(b_\sigma,\dim(\sigma)) \) if \( m = 1 \). Extend this homotopy affinely with respect to \( t \) over all simplices of \( M(K,n) \), and notice that \( H(x,1/n) \) belongs to a subcomplex \( L_1 \) of \( M(K,n) \) that is generated by the vertices \( v = (b_\sigma,m) \) for which either \( m = \dim(\sigma) \) or \( m \geq 2 \).

For \( 1/n \leq t \leq 2/n \), \( H(x,t) \) will be of the form \( G(H(x,1/n),t) \), where \( G \) is a certain homotopy defined on \( L_1 \times [1/n,2/n] \). Namely, for \( v = (b_\sigma,m) \in \text{Vert}(L_1) \), let \( G(v,t) = v \) if \( m \neq 2 \), and \( G(v,t) = (2-nt)(b_\sigma,m) + nt(b_\sigma,\dim(\sigma)) \) otherwise. To extend \( G \) over the simplices of \( L_1 \), it is enough to consider a simplex \( \{(b_{\sigma_0},m_0), \ldots, (b_{\sigma_k},m_k)\} \subseteq L_1 \) (\( m_0 < \cdots < m_k \)) such that, for some \( j \geq 1 \), \( \dim(\sigma_j) < m_j = 2 \). Then \( m_{j-1} < 2 \), and hence \( m_{j-1} = \dim(\sigma_{j-1}) = \dim(\sigma_j) \). It follows that \( \{ (b_{\sigma_0},m_0), \ldots, (b_{\sigma_{j-1}},m_{j-1}), (b_{\sigma_j},\dim(\sigma_j)), (b_{\sigma_j},m_j), \ldots, (b_{\sigma_k},m_k) \} \) is a simplex of \( L_1 \) (we obviously have \( (b_{\sigma_{j-1}},m_{j-1}) = (b_{\sigma_j},\dim(\sigma_j)) \) if \( \dim(\sigma_{j-1}) = \dim(\sigma_j) \)). This allows us to extend \( G \) affinely with respect to \( t \) over \( |L_1| \) and conclude that \( H(x,2/n) \) will be a point of a subcomplex \( L_2 \) generated by the vertices \( v = (b_\sigma,m) \) for which either \( m = \dim(\sigma) \) or \( m \geq 3 \).
After finitely many steps, we finally define \( H \) over the interval \( [(n-1)/n, 1] \) such that \( H(x,1) \in L_n = K^{(1)} \). Since, for every vertex \( v \), we have \( r \circ H(v,t) = r(v) \), it follows that \( r \circ H(x,t) = r(x) \) for every \( x \); in particular, \( H(x,1) = r(x) \). Properties (iv), (v), (vi), (vii), and (viii) also follow.

**Corollary 4.4.** The following holds:

\[
\begin{align*}
(i) & \quad (\text{for all } \sigma \in K) \ |D_{\sigma} = r^{-1}(|\sigma|)\text{ is contractible}, \\
(ii) & \quad \text{the family } \{D_{\sigma} \setminus M^{n-1}(K,n) | \ |\sigma| \in K\} \text{ is finite and consists of open, pair-wise disjoint sets of } |M(K,n)|.
\end{align*}
\]

**Proof.** Item (i) follows from Lemma 4.3(iii). To prove item (ii), observe that for each \( \sigma \in K \), \( r^{-1}(\sigma) \setminus M^{n-1}(K,n) = \text{st}(v,M(K,n)) \), where \( \text{st}(v,M(K,n)) \) is the open star of the vertex \( v = (b_{\sigma_0},n) \in M(K,n) \). No such stars have a point in common since there is no simplex in \( M(K,n) \) with two vertices of this kind (i.e., for any other vertex \( (b_r,m) \), we must have \( m < n \)).

**Corollary 4.5 ([5, Lemma 5]).** For every \( \varepsilon > 0 \), there exists a map \( h_\varepsilon : |M(K,n)| \to |M(K,n)| \) such that

\[
\begin{align*}
(i) & \quad h_\varepsilon|K| = \text{id}_{|K|}, \\
(ii) & \quad (\text{for all } x \in |M(K,n)|) \ r(h_\varepsilon(x)) = r(x), \\
(iii) & \quad (\text{for all } 0 \leq k \leq n) \ |h_\varepsilon^{-1}(|M^k(K,n)|)| = |M^k(K,n)|, \\
(iv) & \quad (\text{for all } x \in |M(K,n)|) \ |v(h_\varepsilon(x))| \leq \varepsilon.
\end{align*}
\]

**Proof.** Let \( H \) be a homotopy of Lemma 4.3. Define \( \alpha(x) = \sup\{t \in [0,1] | v(H(x,t)) \geq \varepsilon\} \) (let \( \sup \emptyset = 0 \)) and \( \beta(x) = \inf\{t \in [0,1] | v(H(x,t)) = 0\} \); \( \alpha \) is upper semicontinuous and \( \beta \) is lower semicontinuous. Denote by \( G \) the complement of \( \beta^{-1}(0) \); \( G \) is an open set. By Lemma 4.3(vi), for all \( x \in G \), \( \alpha(x) < \beta(x) \). There exists a continuous function \( y : G \to [0,1] \) such that \( \alpha(x) < y(x) < \beta(x) \), \( x \in G \). Extend \( y \) to a (necessarily) continuous function over the whole \( |M(K,n)| \) by letting \( y(x) = 0 \) off \( G \). Finally, let \( h_\varepsilon(x) = H(x,y(x)) \).

Properties (i), (ii), and (iv) follow from those (i) and (iii) of Lemma 4.3 and the definition of \( \alpha \). Taking into account Lemma 4.3(iv), property (iii) reduces to \( h_\varepsilon^{-1}(|M^k(K,n)|) \subset |M^k(K,n)| \) for \( 0 \leq k \leq n \). To show this, let \( x \notin |M^k(K,n)| \), and additionally, \( x \notin |K| \); the latter implies \( \beta(x) > 0 \). Find the smallest simplex \( \{(b_{\sigma_0},m_0), \ldots, (b_{\sigma_p},m_p)\} \) containing \( x \). Then \( m_p > k \) and, by Lemma 4.3(v), \( H(x,t) = H(x,m_p/n) \in |K| \) for all \( t \geq m_p/n \). Since \( y(x) < \beta(x) \leq m_p/n \), by an application of Lemma 4.3(viii) to the vertex \( v = (b_{\sigma_p},m_p) \), we get \( t_v(H(x,y(x))) \neq 0 \); hence, \( h_\varepsilon(x) \notin |M^k(K,n)| \).

For \( l \geq 1 \), consider the complex \( M(K^{(l)}, n) \) associated with \( K^{(l)} \), the \( l \)th barycentric subdivision of \( K \). Together with the map \( r : M(K,n) \to K^{(1)} \), we consider \( r_1 = r(K^{(l)}, n) : M(K^{(l)}, n) \to (K^{(1)})^{(l)} = K^{(l+1)} \). In the next lemma, we list properties of an important map \( |M(K^{(l)}, n)| \to |M(K,n)| \) that will be used in constructing \( \pi_n^{n+1} \).
Lemma 4.6 ([5, Lemma 6]). There exists \( f : |M(K^{(i)}, n)| \rightarrow |M(K, n)| \) satisfying
\[
(i) \ f \ |K| = \text{id}_{|K|}, \\
(ii) \ (\text{for all} \ x \in |M(K^{(i)}, n)|) [d(r(f(x)), r_1(x)) < \varepsilon], \\
(iii) \ (\text{for all} \ 0 \leq k \leq n) [f^{-1}(|M^k(K,n)|) \subset |M^k(K^{(i)}, n)|], \\
(iv) \ (\text{for all} \ \sigma \in K^{(i)}) [f(r_1^{-1}(|\sigma|)) \subset r_1^{-1}(|\sigma|)], \\
v) \ (\text{for all} \ x \in |M(K^{(i)}, n)|) [v(f(x)) < \varepsilon].
\]

Proof. Notice that if \( f \) satisfies (i), (ii), (iii), and (iv), then, letting \( h_\varepsilon \) be that of Corollary 4.5, \( h_\varepsilon \circ f \) satisfies all conditions (i), (ii), (iii), (iv), and (v). Furthermore, we claim that it is enough to consider the case of \( l = 1 \). Suppose \( f_l : |M(K^{(i)}, n)| = |M((K^{(i-1)})^{(1)}, n)| \rightarrow |M(K^{(i-1)}, n)|, 1 \leq i \leq l, \) has been constructed in order to satisfy conditions (i), (ii), (iii), (iv), and (v) (with a suitable \( \varepsilon_i > 0 \)), and (vi) below. Then the composition \( f_l \circ \cdots \circ f_1 \) can serve for \( f \).

We use induction with respect to \( \text{dim}(K) \) to construct the requested \( f : |M(K^{(1)}, n)| \rightarrow |M(K, n)| \); we impose the following extra condition on \( f \):
\[
v) \ (\text{for all} \ x \in |M^k(K^{(1)}, n)|) \ (\text{for all} \ v = (b_\sigma, m) \in \text{Vert}(M(K, n))) [t_v(f(x)) \\
\neq 0 \Rightarrow m = \dim(\sigma) \text{ or } m \leq k].
\]

If \( \text{dim}(K) = 0 \), then \( f = \text{id} \) will work. So, letting \( \text{dim}(K) = d > 0 \), we may assume that the assertion of Lemma 4.6 holds for all complexes of dimension less than or equal to \( d-1 \). Denote by \( K_{d-1} \) the \((d-1)\) skeleton of \( K \) and let \( f' : |M(K_{d-1}^{(1)}, n)| = r_1^{-1}(|K_{d-1}|) \rightarrow |M(K_{d-1}, n)| = r_1^{-1}(|K_{d-1}|) \) be a map that satisfies (i), (ii), (iii), (iv), and (vi) with \( \varepsilon > 0 \). Our goal is to extend \( f' \) to a required map \( f \) step by step over all simplices of dimension \( d \).

Fix \( s \in K, \text{dim}(s) = d, \) and let \( b_s \) be its barycenter. Write \( V = \{v \in \text{Vert}(M(K^{(1)}, n)) | r_1(v) \in s^{(2)} \} \) and let
\[
S = \{v \in V | r_1(v) \in \text{st}(b_s, K^{(2)})\}, \quad T = \{v \in V | r_1(v) \in (\partial s)^{(2)}\}; \quad (4.8)
\]
we have \( V = S \cup T \). For \( x \in r_1^{-1}(|s|) \), define
\[
\alpha(x) = \sum_{v \in S} t_v(x), \quad \beta(x) = \sum_{v \in T} t_v(x); \quad (4.9)
\]
clearly, \( \alpha(x) + \beta(x) = 1 \). First, we define auxiliary maps \( \xi : r_1^{-1}(\text{int } |s|) \rightarrow r_1^{-1}(b_s) \) by
\[
\xi(x) = \sum_{v=(b_s, m) \in S} t_v(x) \frac{t_v(x)}{\alpha(x)} (b_s, \max(m, d)), \quad (4.10)
\]
and \( \eta : r_1^{-1}(|s| \setminus |\text{st}(b_s, K^{(2)})|) \rightarrow r_1^{-1}(|\partial s|) \) by
\[
\eta(x) = \sum_{v \in T} t_v(x) \frac{t_v(x)}{\beta(x)} v. \quad (4.11)
\]
We let \( \pi = \rho \circ r_1 : r_1^{-1}(|s| \setminus \{b_s\}) \to |\partial s| \), where \( \rho : |s| \setminus \{b_s\} \to |\partial s| \) is the radial projection. For \( x \in r_1^{-1}(|s| \setminus \{b_s\}) \), the equation

\[
r_1(x) = (1 - \mu(x))\pi(x) + \mu(x)b_s
\]

determines a continuous function \( \mu : r_1^{-1}(|s| \setminus \{b_s\}) \to [0, 1] \).

Choose open sets \( U_1, U_2 \subset r_1^{-1}(|s| \setminus |s|) \) such that \( r_1^{-1}(|\partial s|) \setminus |s| \subset U_1 \subset U_2 \) and

\[
\bar{U}_2 \subset r_1^{-1}(|s| \setminus \overline{\Pi}(b_s, K(2))), \quad \bar{U}_2 \cap |s| = |\partial s|, \quad \bar{U}_1 \subset U_2 \cup |\partial s|;
\]

here, the closure is taken in \( r_1^{-1}(|s|) \). Finally, we employ two steering functions \( \gamma, \delta : r_1^{-1}(|s|) \setminus |s| \to [0, 1] \) such that

\[
\gamma|r_1^{-1}(|\partial s|) \setminus |s| = 0, \quad \gamma(x) = 1 \text{ if } x \notin U_1, \\
\delta|U_1 = 0, \quad \delta(x) = 1 \text{ if } x \notin U_2.
\]

Letting \( H \) be a homotopy of Lemma 4.3, we define a required map \( f : r_1^{-1}(|s|) \to r_1^{-1}(|s|) \) by

\[
f(x) = \begin{cases} 
  f'(x) & \text{if } x \in r_1^{-1}(|\partial s|), \\
  (1 - \mu(x))H(f' \circ \eta(x), \gamma(x)) + \mu(x)\pi(x) & \text{if } x \in \bar{U}_1 \setminus r_1^{-1}(|\partial s|), \\
  (1 - \mu(x))[(1 - \delta(x))\rho + f' \circ \eta(x) + \delta(x)\pi(x)] + \mu(x)\pi(x) & \text{if } x \in \bar{U}_2 \setminus (U_1 \cup |s|), \\
  \xi(x) & \text{if } x \in r_1^{-1}(\{b_s\}) \setminus U_2,
\end{cases}
\]

(4.15)

By the properties of \( \gamma \) and \( \delta \), the formulas agree on the respective boundaries. So, \( f \) will be well defined if we show that each pair

(a) \( \pi(x) \) and \( \xi(x) \),

(b) \( r \circ f' \circ \eta(x) \) and \( \pi(x) \), and furthermore, \( (1 - \delta)r \circ f' \circ \eta(x) + \delta\pi(x) \) and \( \xi(x) \) for \( 0 \leq \delta \leq 1 

(c) \( H(f' \circ \eta(x), \gamma(x)) \) and \( \xi(x) \)

belongs to a simplex of \( M(K, n) \) for a respective \( x \in r_1^{-1}(\operatorname{int}|s| \setminus \{b_s\}) \).

To show (a), find \( \tau \in (\partial s)^{(1)} \subset M(K, n) \) with \( \pi(x) \in |\tau| \). Let \( \hat{\tau} \in M(K, n) \) be the simplex that consists of the vertices of \( \tau \) and all the vertices of the form \( (b_{\sigma}, m), d \leq m \leq n \); in particular \( \tau \leq \hat{\tau} \). By the definition of \( \xi \), we have that \( \pi(x), \xi(x) \in |\hat{\tau}| \).

Sublemma 4.7. For \( x \in r_1^{-1}(\operatorname{int}|s|) \), let \( \{v_0 = (b_{\sigma_0}, m_0), \ldots, v_p = (b_{\sigma_p}, m_p)\} \subset V \), where \( \sigma_0 \leq \cdots \leq \sigma_p \) and \( m_0 < \cdots < m_p \), be the smallest simplex of \( M(K^{(1)}, n) \) containing \( x \). Then

(i) \( (\exists 0 \leq q \leq p - 1) \ [\sigma_i \in (\partial s)^{(1)}] \iff 0 \leq i \leq q \),
(ii) \((b_{\sigma q}, m_p) \in S\) and \(m_p \geq \dim(\sigma_p) = d\),
(iii) if \(\eta(x)\) is defined, then \(\eta(x) \in \{v_0, \ldots, v_q\}\),
(iv) \(\xi(x)\) is an element of the simplex \(\{(b_s, \max(d, m_{q+1})), \ldots, (b_s, \max(d, m_p))\}\).

To justify (b), assume that \(x \in r_1^{-1}(\text{int } [s] \setminus \mathbb{S}(b_s, K^{(2)}))\). With \(\tau\) as above and \(\sigma_q\) as in Sublemma 4.7(i), we have \(|\sigma_q| \subset |\tau|\). It follows that \(r_1(\eta(x)) \in |\sigma_q| \subset |\tau|\) (see Sublemma 4.7(iii)) and, by Lemma 4.6(iv) applied to \(f'\), we obtain \(r(f'(\eta(x))) \in |\tau|\). This shows that \(r \circ f' \circ \eta(x), \pi(x) \in |\tau| \subset |\tau|\) and, by the proof of item (a), \((1 - \delta)r \circ f' \circ \eta(x) + \delta \pi(x), \xi(x) \in |\tau|\).

To show (c), assume \(x \in U_1\). By Sublemma 4.7(iii), \(\eta(x) \in |M_0(K_{d-1}, n)|\). Applying Lemma 4.3(vii) to \(f'\) (with \(\eta(x)\) and \(k = m_q\)), for every \(v = (b_{\sigma}, m) \in \text{Vert}(M(K_{d-1}, n))\) with \(t_v(f'(\eta(x))) \neq 0\), either \(m = \dim(\sigma)\) or \(m \leq m_q\). Let \(\sigma'\) be the smallest simplex of \(M(K_{d-1}, n)\) such that \(H(f' \circ \eta(x), y(x)) \in |\sigma'|\). Take any vertex \((b_{\tau}, m)\) of \(\sigma'\); note that \(\tau \in \partial s\). By Lemma 4.3(vii), if \(m > \dim(\tau)\), then \(m \leq m_q\). It then follows that \(m \leq \max(\dim(\tau), m_q) < d(m, m_{q+1})\). Enlarge \(\sigma'\) to the simplex \(\sigma'\) by adding to the vertices of \(\sigma'\) all the vertices of the form \((b_s, k)\), where \(\max(d, m_{q+1}) \leq k \leq n\). Taking into account Sublemma 4.7(iv), it is now clear that \(H(f' \circ \eta(x), y(x)), \xi(x) \in |\delta|\).

Now, we verify the continuity of \(f\). By the continuity of all involved maps in the formula for \(\hat{f} = f'\) is continuous on \(r_1^{-1}(\text{int } [s] \setminus \{b_s\})\). Therefore, it is enough to show that \(\hat{f}\) is continuous at \(x_0\) in the following three cases: \(x_0 \in r_1^{-1}(b_s), x_0 \in r_1^{-1}(|\partial s|) \setminus |\partial s|,\) and \(x_0 \in |\partial s|\). Let \(\{x_i\}_{i=1}^{\infty} \subset r_1^{-1}(\text{int } [s] \setminus \{b_s\})\) with \(\lim x_i = x_0\).

If \(x_0 \in r_1^{-1}(b_s)\), then \(\lim \mu(x_i) = 1\) because \(\lim r_1(x_i) = b_s\). Consequently, \(\lim f(x_i) = \lim[(1 - \mu(x_i))\pi(x_i) + \mu(x_i)\xi(x_i)] = \xi(x_0) = f(x_0)\). If \(x_0 \in r_1^{-1}(|\partial s|) \setminus |\partial s|,\) then \(\lim y(x_i) = 0, \lim \mu(x_i) = 0,\) and \(\lim \eta(x_i) = \eta(x_0) = x_0\) (provided \(\eta(x_i)\) is well defined). Consequently,

\[
\begin{align*}
\lim H(f'(\eta(x_i)), y(x_i)) &= H(f'(\eta(x_0)), 0) = f'(\eta(x_0)) = f'(x_0) = f(x_0), \\
\lim f(x_i) &= \lim[(1 - \mu(x_i))H(f'(\eta(x_i)), y(x_i)) + \mu(x_i)\xi(x_i)] = f(x_0),
\end{align*}
\]

(4.16)

Let \(x_0 \in |\partial s|\). The following family, consisting of sets:

\[
O(W, \lambda) = \{(1 - t)y + tz \in r_1^{-1}(|s|) \mid y \in W, z \in r_1^{-1}(|s|), 0 \leq t \leq \lambda\},
\]

(4.17)

where \(W\) runs over all neighborhoods of \(x_0\) in \(r_1^{-1}(|\partial s|)\) and \(0 < \lambda < 1\), is a base of neighborhoods of \(x_0\) in \(r_1^{-1}(|s|)\). Fix such a neighborhood \(O(W, \lambda)\) of \(x_0\). (Below, we evaluate maps at \(x\) only if they are well defined at such an \(x\).) The continuity of \(\pi\) and the facts that \(\pi(x_0) = x_0\) and \(\lim_{x \to x_0} H(f'(\eta(x)), y(x)) = x_0\) imply that there exists a neighborhood \(P\) of \(x_0\) in \(r_1^{-1}(|s|)\) such that \(H(f'(\eta(x)), y(x)), \pi(x) \in W\) provided \(x \in P\). On the other hand, since \(r(f'(\eta(x_0))) = x_0\) and \(\pi(x_0) = x_0\), we can assume that \((1 - \delta)r(f'(\eta(x_0))) + \delta \pi(x) \in W\) for every \(x \in P\) and every \(0 \leq \delta \leq 1\). We can also assume that for \(x \in P\), \(\mu(x) \leq \lambda\) because \(\mu(x_0) = 0\). Now, for \(x \in P\), \((1 - \mu(x))\pi(x) + \mu(x)\xi(x), (1 - \mu(x))H(f'(\eta(x)), y(x)) + \mu(x)\xi(x),\)
and \((1 - \mu(x))(1 - \delta(x))r(f'(\eta(x))) + \delta(x)\pi(x)) + \mu(x)\xi(x)\) belong to \(O(W, \lambda)\). This completes the proof of the continuity of \(f\).

Now, we verify properties (i), (ii), (iii), and (iv) of Lemma 4.6 and (vi). We need to consider a point \(x \in r_1^{-1}(\text{int}|s|)\) only. If, additionally, \(x \notin U_2\), then \(r(f(x)) = r_1(x)\). By the inductive assumption, \(d(r(f(y)), r_1(y)) < \varepsilon\) for all \(y \in r^{-1}(\text{int}|s|)\); by the continuity of the maps involved, this inequality holds for all \(x\) in some neighborhood of \(r_1^{-1}(\text{int}|s|)\) in \(r_1^{-1}(\text{int}|s|)\). Taking \(U_2\) to be contained in that neighborhood, we see that \(d(r(f(x)), r_1(x)) < \varepsilon\) for all \(x\). This shows (i).

If \(x \in \text{int}|s|, x \neq b_s\), then \(f(x) = (1 - \mu(x))\pi(x) + \mu(x)b_s = r_1(x) = x\); if \(x = b_s\), then \(f(x) = \xi(b_s) = b_s\). This shows (ii).

To show (iii), let \(x \in r_1^{-1}(\text{int}|s|) \setminus |M^{k}(K^{(1)}, n)|, 0 \leq k \leq n\). Using the notation of Sublemma 4.7, \(m_p > k\); by Sublemma 4.7(ii), \(v_p \in S\) and \(\max(m_p, d) = m_p > k\). Now, looking at Sublemma 4.7(iv), for the vertex \(v = (b_o, \max(m_p, d))\), we have \(t_v(\xi(x)) \neq 0\); consequently, \(\xi(x) \notin |M^{k}(K^{(1)}, n)|\). This, together with the fact that \(\mu(x) > 0\), yields \(f(x) \notin |M^{k}(K^{(1)}, n)|\) because \(\xi(x)\) shows up in all the formulas defining \(f(x)\).

To show (iv), fix \(\sigma \in K^{(1)}\) and \(x \in r_1^{-1}(|\sigma|) \cap r_1^{-1}(\text{int}|s|)\). Using the notation of Sublemma 4.7, we have \(\sigma_p \leq \sigma\). This implies that both \(r(\xi(x)) = b_s\) and \(r(\pi(x)) = \pi(x)\) belong to \(|\sigma|\), and \(r_1(\eta(x)) \in |\sigma| \cap |\partial s|\) (use Sublemma 4.7(iii)). By an application of Lemma 4.6(iv) to \(f'\), we infer that \(r(f'^{\circ} \eta(x)) \in |\sigma| \cap |\partial s| \subset |\sigma|\). Since \(r(H(f'^{\circ} \eta(x), y(x))) = r(f'^{\circ} \eta(x))\), we obtain \(H(f'^{\circ} \eta(x), y(x)) \in |\sigma|\). (All maps are evaluated at \(x\) if they are defined at such an \(x\).) Finally, using the fact that \(r\) is simplicial and looking at the formulas that define \(f\), we conclude that \(r(f(x)) \in |\sigma|\).

To show property (vi), let \(x \in |M^{k}(K^{(1)}, n) \cap r_1^{-1}(\text{int}|s|), 0 \leq k \leq n\). We will examine \(v = (b_o, m) \in \text{Vert}(M(K, n))\) for which \(t_v(f(x)) \neq 0\) and \(m > \text{dim}(\sigma)\). Using the notation of Sublemma 4.7, by (iii), we obviously have \(m_p \leq k\) and \(\eta(x) \in |M^{k}(K_{d-1}, n)|\). Now, as in the proof of item (c), by an application of (vi) to \(f'\) and Sublemma 4.7(vii), we infer that if \(t_v(H(f'^{\circ} \eta(x), y(x))) \neq 0\), then \(m \leq k\). On the other hand, by Sublemma 4.7(iv), we see that if \(t_v(\xi(x)) \neq 0\), then \(m \leq \max(m_p, d) \leq m_p < k\) (see Sublemma 4.7(ii)). Finally, since \(t_v(f(x)) \neq 0\) implies either \(t_v(H(f'^{\circ} \eta(x), y(x))) \neq 0\) or \(t_v(\xi(x)) \neq 0\), we complete the proof by noting that in both these cases \(m \leq k\).

\[4.1.2\] The compacta \(Z_n\) and the retractions \(\rho_n : Z_n \rightarrow |K_n|\). To the complex \(K_n\), we assign the finite complex

\[M_n = M(K^{(k_o)}, n)\] (4.18)

for a certain \(k_o > k_{n-1}\) (which will be provided later), and we write

\[r_n = r(K^{(k_o)}_n, n) : M_n = M(K^{(k_o)}, n) \rightarrow K^{(k_o+1)}_n = (K^{(k_o)})^{(1)}\] (4.19)
The set $C_\sigma$. For a simplex $\sigma \in K_n^{(k_n)}$ (not just $\sigma \in K_n^{(k_n+1)}$), we let

$$D_\sigma = r_n^{-1}(|\sigma|), \quad C_\sigma = D_\sigma \times [0, 1].$$  \hspace{1cm} (4.20)

We write $[\sigma, x, t]$ for a typical point of $(x, t) \in D_\sigma \times [0, 1] = C_\sigma$ and identify $D_\sigma \ni x \rightarrow [\sigma, x, 0] \in C_\sigma$. Write $p_n : C_\sigma \rightarrow D_\sigma$ for the obvious retraction given by

$$p_n([\sigma, x, t]) = x \quad \forall x \in D_\sigma, \ 0 \leq t \leq 1. \hspace{1cm} (4.21)$$

The space $Z_n$. We let

$$Z_n = |M_n| \cup \bigcup \{C_\sigma \mid \sigma \in K_n^{(k_n)}\}, \hspace{1cm} (4.22)$$

where $C_\sigma$ are attached to $|M_n|$ in such a way that $C_\sigma \cap C_\tau = D_\sigma \cap D_\tau$ for $\sigma \neq \tau$. Clearly, $Z_n$ is a finite-dimensional metric compactum; we let $d_n \leq 1$ to be a compatible metric on $Z_n$. Now, $p_n$ gives rise to a retraction $\rho_n : Z_n \rightarrow |M_n|$ defined by

$$\rho_n = r_n \circ p_n : Z_n \rightarrow |K_n|. \hspace{1cm} (4.23)$$

The map $x \rightarrow v(K_n^{(k_n)}, n)(x)$, $x \in |M_n|$, gives rise to a map $v_n = v(K_n^{(k_n)}, n) \circ p_n : Z_n \rightarrow [0, 1]$ so that

$$v_n([\sigma, x, t]) = v(K_n^{(k_n)}, n)(x) \quad \forall x \in D_\sigma, \ 0 \leq t \leq 1. \hspace{1cm} (4.24)$$

It follows from the definition of $v_n$ that $v_n|||M_n|| = 0$. Finally, we define $\gamma_n : Z_n \rightarrow [0, 1]$ so that $\gamma_n|||M_n|| = 0$ and $\gamma_n([\sigma, x, t]) = t$.

The sequences $\{k_n\}$ and $(\epsilon_n)$. Now, we inductively specify the sequences $\{k_n\}$ and $(\epsilon_n)$ that will be crucial in verifying the countable dimensionality of $Z$. Suppose we have defined the spaces $Z_1, \ldots, Z_n$ (hence, the maps $\rho_n$, $v_n$, and $\gamma_n$ are also known) and the bonding maps $\pi_m^n : Z_m \rightarrow Z_n$ for $1 \leq m \leq n$, and that we have already chosen $k_1 < \cdots < k_n$ ($n \geq 1$). For every set $S \subset |K_n|$, we have $\rho_n^{-1}(S) \cap v_n^{-1}(0) \cap \gamma_n^{-1}(0) = S$. This, together with the fact that $\sup \{\text{diam}(|s|) \mid s \in K_n^{(k_n)}\} \rightarrow 0$ if $k \rightarrow \infty$, guarantees the existence of $k_{n+1} > k_n$ and $0 < \epsilon_n \leq 1$ such that

$$\text{diam}_{d_m} \left[\pi_m^n \left(\rho_n^{-1}(B(|\sigma|, \epsilon_n)) \cap v_n^{-1}([0, \epsilon_n]) \cap \gamma_n^{-1}([0, \epsilon_n])\right)\right] \leq 2^{-n} \hspace{1cm} (4.25)$$

for all $\sigma \in K_n^{(k_{n+1})}$ and $m = 1, \ldots, n$. (Here, $B(|\sigma|, \epsilon_n)$ stands for the generalized closed ball around $|\sigma|$ of radius $\epsilon_n$.)
To start the induction, set $k_1 = 0$. Then $K_1^{(k_1)} = K_1$ and $M_1 = M(K_1, 1)$. Define $\rho_1$, $v_1$, and $y_1$. Since, for every set $S \subset |K_1|$, $\rho_1^{-1}(S) \cap v_1^{-1}(0) \cap y_1^{-1}(0) = S$, and since $\sup \{\diam(|s|) \mid s \in K_1^{(k_1)}\} \to 0$ if $k \to \infty$, there exist $k_2 > k_1 = 0$ and $0 < \epsilon_1 \leq 1/2$ such that $\diam_1 [\rho_1^{-1}(B(|\sigma|, \epsilon_1)) \cap v_1^{-1}([0, \epsilon_1]) \cap y_1^{-1}([0, \epsilon_1])] \leq 1/2$ for every $\sigma \in K_1^{(k_2)}$.

4.1.3. The bonding maps $\pi_n^{n+1}: Z_{n+1} \to Z_n$. Together with $M_n = M(K_n^{(k_n)}, n)$ and $M_{n+1} = M(K_n^{(k_{n+1})}, n+1)$, and maps $r_n = r(K_n^{(k_n)}, n)$ and $r_{n+1} = r(K_n^{(k_{n+1})}, n+1)$, we also consider

$$M(K_n^{(k_{n+1})}, n), \quad r_n = r(K_n^{(k_{n+1})}, n) : M(K_n^{(k_{n+1})}, n) \to K_n^{(k_{n+1})}.$$ (4.26)

The simplicial “bonding” map $q_n : K_{n+1} \to K_n$ gives rise to the simplicial map

$$q_n^{(k_{n+1})} : K_{n+1}^{(k_{n+1})} \to K_n^{(k_{n+1})}. \quad (4.27)$$

This, in turn, yields a simplicial map

$$\mu_n : M^n(K_{n+1}^{(k_{n+1})}, n+1) = M_{n+1}^n \to M(K_n^{(k_{n+1})}, n)$$ (4.28)

defined as follows:

$$\mu_n((b_\sigma, m)) = \left(b_{q_n^{(k_{n+1})}(\sigma)}, m\right) \quad \text{for} \quad (b_\sigma, m) \in \text{Vert} \left(M_{n+1}^n\right). \quad (4.29)$$

The following functions between complexes will be used throughout the remaining part of this text:

$$K_{n+1}^{(k_{n+1})} \ni \sigma \to \sigma' = q_n^{(k_{n+1})}(\sigma) \in K_n^{(k_{n+1})}, \quad (4.30)$$

and $\hat{\sigma}$ being the smallest simplex with this property.

**Lemma 4.8.** For every $\sigma \in K_{n+1}^{(k_{n+1})}$, $\mu_n(r_n^{-1}(|\sigma|) \cap M_n^n) \subset \hat{r}_n^{-1}(|\sigma'|)$.

**Proof.** Assume that $x \in |M_{n+1}^n|$ with $r_{n+1}(x) \in |\sigma|$, where $\sigma \in K_{n+1}^{(k_{n+1})}$. Then, $x = \sum t_v(x)\nu \mid \nu = (b_\tau, m), m \leq n\}$ (here $(b_\tau, m)$ are the vertices of the smallest simplex of $M_n^n$ containing $x$). It follows that, for each such vertex $(b_\tau, m)$, we have $\tau \leq \sigma$. By the definition of $\mu_n$, $\mu_n(x) = \sum t_v(x)(b_{q_n^{(k_{n+1})}(\tau)}, m)$. Consequently, $\hat{r}_n(\mu_n(x)) = \sum t_v(x)b_{q_n^{(k_{n+1})}(\tau)}$ . Hence, $\hat{r}_n(\mu_n(x)) \in |\sigma'|$. \quad $\Box$

Using the fact that for every $\sigma, \tau \in K_{n+1}^{(k_{n+1})}$, $\sigma \neq \tau$, we have that $C_\sigma \cap C_\tau = r_n^{-1}(\sigma) \cap r_n^{-1}(\tau)$, and that $\hat{r}_n^{-1}(|\sigma'|)$ is contractible (see Corollary 4.4(i)); by Lemma 4.8, we extend $\mu_n| |M_{n+1}^n|$ over the whole $Z_{n+1}$ so that

$$(\forall \sigma \in K_{n+1}^{(k_{n+1})}) \quad \left[\mu_n(C_\sigma) \subset \hat{r}_n^{-1}(|\sigma'|)\right]. \quad (4.31)$$
We need a “subdivision map” $f_n : |M(K_n^{(k_n+1)}, n)| \to |M_n| = |M(K_n^{(k_n)}, n)|$ such that

$$
(f_n(\hat{r}^{-1}_n(|s|))) \subset r_n^{-1}(|s|));
$$

we achieve this by applying Lemma 4.6 with $K = K^{(k_n)}_n$, $l = k_{n+1} - k_n$, and $\varepsilon = \varepsilon_n$. Now, we can define

$$
\theta_n = f_n \circ \mu_n : \tilde{Z}_{n+1} \to |M_n| \subset Z_n.
$$

Now, we extend $\theta|||M_{n+1}^\sigma$ to the desired map $\pi_{n+1}^n$. For $\sigma \in K^{(k_n+1)}_n$, consider the sets $C_\sigma \subset Z_{n+1}$ and $C_\sigma \subset Z_n$ (for which we have $D_\sigma = r_n^{-1}(|\sigma|)$ and $D_\sigma = r_n^{-1}(|\sigma|)$, respectively). Let

$$
E_{\sigma}^{n+1} = C_\sigma \setminus |M_{n+1}^\sigma|.
$$

Applying (4.31) and (4.32) (with $s = \sigma' \in K^{(k_n+1)}_n$), we infer that $f_n(\mu_n(C_\sigma)) \subset r_n^{-1}(|\sigma'|) \subset r_n^{-1}(|\sigma|)$ because $|\sigma'| \subset |\sigma|$. We conclude that $\theta_n(\mu_n(C_\sigma)) \subset r_n^{-1}(|\sigma|) = D_\sigma$. Letting $\beta_{n+1} : Z_n \to [0, \varepsilon_n]$ with $\beta_{n+1}^{-1}(0) = |M_{n+1}^\sigma|$ be a continuous steering function, it is easy to see that the following formula well defines the required bonding map $\pi_{n+1}^n : \tilde{Z}_{n+1} \to Z_n$:

$$
\pi_{n+1}^n(x) = \begin{cases} 
\theta_n(x) & \text{if } x \in |M_{n+1}^\sigma|, \\
[\sigma, \theta_n(x), \beta_{n+1}(x)] & \text{if } x \in E_{\sigma}^{n+1}, \sigma \in K^{(k_n+1)}_n.
\end{cases}
$$

Moreover, we have

$$
\pi_{n+1}^n(C_\sigma) \subset C_\sigma.
$$

We put $\pi_{n+1}^n = \pi_{n+1}^n \circ \pi_{n+1}^n$ and $\pi_{n+1}^n = \text{id}$. We show condition (4.2) of Step 2, that is, $\pi_{n+1}^n(|K_{n+1}^\sigma|) \supset |K_n|$. To this end, for a given $s \in K_n$, we find $\sigma \in K_{n+1}$ such that $|s| = \pi_{n+1}^n(|\sigma|)$. Since $q_n$ is surjective, there exists $\sigma \in K_{n+1}$, $\dim(\sigma) = \dim(s)$, with $q_n(\sigma) = s$. Hence, the maps $q_n \mid \sigma$ and $q_n^{(k_{n+1}+1)} \mid \sigma^{(k_{n+1}+1)} : \sigma^{(k_{n+1}+1)} \to s^{(k_{n+1}+1)}$ are simplicial isomorphisms. We identify $K^{(k_{n+1}+1)}_n$ with a subcomplex of $M_{n+1}^\sigma$, and we have that $\sigma^{(k_{n+1}+1)} \subset M_{n+1}^\sigma$ because $\dim(\sigma) = \dim(s) \leq \dim K_n \leq n$. By the definition of $\mu_n$, $\mu_n \mid \sigma^{(k_{n+1}+1)} = q_n^{(k_{n+1}+1)} \mid \sigma^{(k_{n+1}+1)}$. So, using Lemma 4.6(i), $\pi_{n+1}^n(|\sigma|) = f_n(\mu_n(|\sigma|)) = \mu_n(|\sigma|) = |q_n^{(k_{n+1}+1)}(\sigma)| = |\sigma|$. This shows condition (4.2) of Step 2.

As announced earlier, the compactum $Z$ is defined as

$$
Z = \varprojlim (Z_n, \pi_{n+1}^n).
$$
The countable dimensionality of $Z$. Here are some additional properties of $\pi_{n+1}^k$ that are needed to prove the countable dimensionality of $Z$.

Lemma 4.9. The following holds:

(i) (for all $0 \leq k \leq n - 1$) \([\pi_{n+1}^k]^{-1}(\{M_n^k\}) \subset \{M_n^k\}\),

(ii) (for all $\sigma \in K_{n+1}^{(k+1)}$) (for all $0 \leq m \leq n$) $\text{diam}_{\text{d}_m}(\pi_{m+1}^n(E_{\sigma}^{(n+1)})) \leq 2^{-n}$; consequently, $\text{diam}(\pi_{n+1}^1(E_{\sigma}^{(n+1)})) < 2^{-n+1}$,

(iii) the family $\{E_{\sigma}^{n+1} | \sigma \in K_{n+1}^{(k+1)}\}$ consists of open, pairwise disjoint subsets of $Z_{n+1}$.

Proof. To verify (i), take $x \in Z_{n+1} \setminus \{M^k_{n+1}\}$ for $0 \leq k \leq n - 1$. If, additionally, $x \notin \{M^k_{n+1}\}$, then $\beta_{n+1}(x) \neq 0$, and consequently, $\pi_{n+1}^k(x) = \{\hat{\sigma}, \theta_n(x), \beta_{n+1}(x)\} \notin \{M^k_{n+1}\}$ (see the definition of $\pi_{n+1}^k$ and (4.30) for the choice of $\hat{\sigma}$). Now, assume that $x \in \{M^k_{n+1}\}$. Taking into account the smallest simplex of $M^k_{n+1}$ that contains $x$, we have $x = \sum t_i(x)(b_{\sigma_i}, m_i)$, where $v_i = (b_{\sigma_i}, m_i)$ are the vertices of this simplex. Then, there exists $i_0$ such that $m_{i_0} > k$. Since $\mu_n(x) = \sum t_i(x)(b_{\sigma_i}, m_i)$ (see (4.30) for the definition of $\sigma_i$), we conclude that $\mu_n(x) \notin \{M^k_{n+1}\}$. Finally, by Lemma 4.6(iii),

$$\pi_{n+1}^n(x) = \theta_n(x) = f_n(\mu_n(x)) \notin \{M^k_{n+1}\}.$$  \hfill (4.38)

To verify (ii), let $x \in E_{\sigma}^{n+1}$ for $\sigma \in K_{n+1}^{(k+1)}$. Then, by the definition of $\pi_{n+1}^k$,

$$\pi_{n+1}^k(x) = \{\hat{\sigma}, f_n(\mu_n(x)), \beta_{n+1}(x)\}.$$  \hfill (4.39)

We show that $\pi_{n+1}^k(x) \in \rho_{n+1}^1(B([\sigma'], \varepsilon_n) \cap V_n^{-1}([0, \varepsilon_n]) \cap \gamma_n^{-1}([0, \varepsilon_n]))$ (see (4.30) for the definition of $\sigma'$); this will yield (ii) via an application of (4.25) (to the case of $m = n$).

We recall that $\beta_{n+1}(x) \leq \varepsilon_n$. By the definition of $\gamma_n$, we have

$$\gamma_n(\pi_{n+1}^k(x)) = \gamma_n([\hat{\sigma}, f_n(\mu_n(x)), \beta_{n+1}(x)]) = \beta_{n+1}(x) \leq \varepsilon_n;$$  \hfill (4.40)

and by (4.24) and Lemma 4.6(v), $\varepsilon_n(\pi_{n+1}^k(x)) = \nu(K_{n+1}^{(k+1)}, n)(f_n(\mu_n(x))) \leq \varepsilon_n$ (the “subdivision map” $f_n$ was found for $\varepsilon = \varepsilon_n$). It remains to show that $\rho_n(\pi_{n+1}^k(x)) \in B([\sigma', \varepsilon_n])$. By (4.21),

$$\rho(\pi_{n+1}^k(x)) = r_n(\pi_{n+1}^k(x)) = r_n(f_n(\mu_n(x))).$$  \hfill (4.41)

Since, by Lemma 4.6(ii), $d(r_n(\mu_n(x)), \check{\mu}_n(x)) < \varepsilon_n$, we will be done if only $\hat{\check{\mu}_n}(\mu_n(x)) \notin [\sigma']$; but this is a consequence of (4.31) and the fact that $C_{\sigma} \supset E_{\sigma}^{n+1}$ (see (4.36)).
Let \( z, z' \in \pi_{n+1}^{-1}(E_{\sigma}^{n+1}) \), that is, \( z = (\pi_{m}(z)) \) and \( z' = (\pi_{m}(z')) \). Using the fact that \( \pi_{n+1}(z), \pi_{n+1}(z') \in E_{\sigma}^{n+1} \), we can estimate

\[
d_{Z}(z, z') = \sum_{m=1}^{\infty} 2^{-m} d_{m}(\pi_{m}(z), \pi_{m}(z')) \\
= \sum_{m=1}^{n} 2^{-m} d_{m}(\pi_{m}(z), \pi_{m}(z')) + \sum_{m=n+1}^{\infty} 2^{-m} d_{m}(\pi_{m}(z), \pi_{m}(z')) \\
\leq \sum_{m=1}^{n} 2^{-m} d_{m}(\pi_{n+1}^{m}(\pi_{n+1}(z)), \pi_{n+1}^{m}(\pi_{n+1}(z'))) + 2^{-n} \\
\leq \left( \sum_{m=1}^{n} 2^{-m} 2^{-n} \right) + 2^{-n} < 2 \cdot 2^{-n} = 2^{-n+1}.
\] (4.42)

Item (iii) easily follows from Corollary 4.4(ii) and the fact that \( C_{\sigma} \cap C_{\tau} = D_{\sigma} \cap D_{\tau} \) for \( \sigma \neq \tau \).

According to the definition of \( Z_{n} \), for every \( n \geq 1 \),

\[
Z_{n} = |M_{n}^{n-1}| \cup \bigcup \{ E_{\sigma}^{n} \mid \sigma \in K_{n}^{(k_{n})} \};
\] (4.43)

recall that \( E_{\sigma}^{n} = C_{\sigma} \setminus |M_{n}^{n-1}| \). It follows that \( Z = P_{0} \cup \bigcup_{n=1}^{\infty} P_{n} \), where

\[
P_{0} = \bigcap_{n=1}^{\infty} \pi_{n}^{-1}\left( \bigcup \{ E_{\sigma}^{n} \mid \sigma \in K_{n}^{(k_{n})} \} \right), \quad Y_{n} = \pi_{n}^{-1}\left( |M_{n}^{n-1}| \right). \] (4.44)

It is enough to show that \( \dim(P_{n}) < \infty \) for \( n = 0, 1, \ldots \).

Since, for every \( n \), the space \( P_{0} \) is covered by the family \( \{ \pi_{n}^{-1}(E_{\sigma}^{n}) \mid \sigma \in K_{n}^{(k_{n})} \} \), which consists of open and pairwise disjoint sets of diameter less than \( 2^{-n+2} \) (see Lemma 4.9(ii) and (iii)), we conclude that \( \dim(P_{0}) \leq 0 \).

On the other hand, we show that \( \dim(P_{n}) \leq n - 1 \) for \( n \geq 1 \). Since in this case \( P_{n} = \pi_{n}^{-1}(|M_{n}^{n-1}|) \), we have that \( P_{n} = \lim(\pi_{m}(P_{n}), \pi_{m}^{k} \mid \pi_{k}(P_{n})) \). Now, it is enough to show that \( \pi_{m}(P_{n}) \subset |M_{m}^{m-1}| \) for all \( m \geq n \). To this end, take \( z \in P_{n} = \pi_{n}^{-1}(|M_{n}^{n-1}|) \); so, \( \pi_{n}(z) \in |M_{n}^{n-1}| \). Since \( \pi_{n}^{m}(\pi_{n}(z)) = \pi_{n}(z) \), it follows that \( \pi_{m}(z) \in (\pi_{n}^{m})^{-1}(|M_{n}^{n-1}|) \subset |M_{m}^{m-1}| \); the last inclusion is a consequence of Lemma 4.9(i).

4.2. The map \( \varphi : Z \to X \). This section provides details for the statements of Step 3.

For every \( z \in Z \) and \( n \geq 1 \), let \( \sigma_{n}(z) \) be the smallest simplex \( \sigma_{n}(z) \in K_{n}^{(k_{n})} \) with \( \pi_{n}(z) \in C_{\sigma_{n}(z)} \), and let \( s_{n}(z) \) be the smallest simplex of \( K_{n} \) such that \( |\sigma_{n}(z)| \subset |s_{n}(z)| \); that is, \( s_{n}(z) \) is the smallest simplex of \( K_{n} \) such that \( \rho_{n}(\pi_{n}(z)) \subset |s_{n}(z)| \).

We set

\[
F_{n}(z) = \bigcap_{\alpha \in s_{n}(z)} \tilde{V}_{\alpha}.
\] (4.45)
Clearly, we have that \( F_n(z) \) is a compact subset of \( X \), and
\[
\text{diam} \left( F_n(z) \right) \leq \Delta_n
\]  
(4.46)
(see (K4) for the definition of \( \Delta_n \)).

**Lemma 4.10.** For every \( 1 \leq n \leq m, x \in F_n(z), \) and \( y \in F_m(z), \) \( d_{\| \cdot \|}(x, y) \leq 2\Delta_n. \)

**Proof.** First, we verify that for all \( 1 \leq n < m, s_n(z) \leq q_{n,m}(s_m(z)) \), where \( q_{n,m} = q_n \circ q_{n+1} \circ \cdots \circ q_{m-1} \). Actually, we can assume that \( m = n + 1 \). Assign to \( z \) the simplex \( \sigma_{n+1}(z) \in K_{n+1}(k_{n+1}) \) accordingly, and write briefly \( \sigma_{n+1}(z) = \sigma \). Using (4.30), consider \( \hat{\sigma} \in K_n(k_n) \) and \( \sigma' \in K_n(k_{n+1}) \); hence, \( |\sigma'| \subset |\sigma| \). Since \( \pi_{n+1}(z) \in C_{\sigma} \) and by (4.36), \( \pi_n(z) = \pi_{n+1}^{n+1}(\pi_{n+1}(z)) \in C_{\hat{\sigma}} \). By the minimality of \( \sigma_n(z) \), we have that \( \sigma_n(z) \leq \hat{\sigma} \). Since \( |\sigma_{n+1}(z)| \subset |s_{n+1}(z)| \), we obtain \( |\sigma'| \subset |q_n(s_{n+1}(z))| \). The fact that \( q_n(s_{n+1}(z)) \in K_n \) implies that \( |\sigma'| \subset |\sigma| \subset |q_n(s_{n+1}(z))| \) (by the minimality of \( \hat{\sigma} \)) and, furthermore, it implies \( s_n(z) \leq q_n(s_{n+1}(z)) \) (by the minimality of \( s_n(z) \) and the fact \( |\sigma_n(z)| \subset |\sigma| \subset |q_n(s_{n+1}(z))| \)).

Now, use the fact that \( q_{n,m} \) is a projection to see that
\[
F_m(z) \subset \{ V_{\alpha} | \alpha \in q_{n,m}(s_m(z)) \}. 
\]  
(4.47)
By the fact that \( s_n(z) \subset q_{n,m}(s_m(z)) \),
\[
F_n(z) \cup F_m(z) \subset \bigcup \{ V_{\alpha} | \alpha \in q_{n,m}(s_m(z)) \}. 
\]  
(4.48)
However, \( q_{n,m}(s_m(z)) \) is a simplex; hence, the intersection of the above family is nonempty, and therefore, \( d(x, y) \leq 2\Delta_n \) for every \( x \in F_n(z) \).

Applying **Lemma 4.10**, we see that for every \( z \), \( (F_n(z)) \) is a Cauchy sequence in the hyperspace of \( X \). This, together with (4.46), shows that \( \varphi(z) = \lim F_n(z) \) well defines \( \varphi : Z \to X \). To verify condition (4.4a) of **Lemma 4.1**, let \( \alpha \in A_n \) such that \( \rho_n(\pi_n(z)) \in \text{st}(\alpha, K_\alpha) \). Then, \( \alpha \in s_n(z) \) and hence \( F_n(z) \subset \bar{V}_\alpha \). This, together with **Lemma 4.10**, shows that \( d(\varphi(z), \bar{V}_\alpha) \leq 3\Delta_n \). This completes the proof of **Lemma 4.1**.

**References**


Revisiting Cauty’s proof of the Schauder conjecture


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Space dynamics is a very general title that can accommodate a long list of activities. This kind of research started with the study of the motion of the stars and the planets back to the origin of astronomy, and nowadays it has a large list of topics. It is possible to make a division in two main categories: astronomy and astrodynamics. By astronomy, we can relate topics that deal with the motion of the planets, natural satellites, comets, and so forth. Many important topics of research nowadays are related to those subjects. By astrodynamics, we mean topics related to spaceflight dynamics.

It means topics where a satellite, a rocket, or any kind of man-made object is travelling in space governed by the gravitational forces of celestial bodies and/or forces generated by propulsion systems that are available in those objects. Many topics are related to orbit determination, propagation, and orbital maneuvers related to those spacecrafts. Several other topics that are related to this subject are numerical methods, nonlinear dynamics, chaos, and control.

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