

n -TRANSITIVITY OF CERTAIN DIFFEOMORPHISM GROUPS

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ABSTRACT. It is shown that some groups of diffeomorphisms of a manifold act n -transitively for each finite n .

Let M be a connected smooth manifold of dimension $\dim M \geq 2$. We say that a subgroup G of the group $\text{Diff}(M)$ of all smooth diffeomorphisms acts **n -transitively on M** , if for any two ordered sets of n different points (x_1, \dots, x_n) and (y_1, \dots, y_n) in M there is a smooth diffeomorphism $f \in G$ such that $f(x_i) = y_i$ for each i .

Theorem. *Let M be a connected smooth (or real analytic) manifold of dimension $\dim M \geq 2$. Then the following subgroups of the group $\text{Diff}(M)$ of all smooth diffeomorphisms with compact support act n -transitively on M , for each finite n :*

- (1) *The group $\text{Diff}_c(M)$ of all smooth diffeomorphisms with compact support.*
- (2) *The group $\text{Diff}^\omega(M)$ of all real analytic diffeomorphisms.*
- (3) *If (M, σ) is a symplectic manifold, the group $\text{Diff}_c(M, \sigma)$ of all symplectic diffeomorphisms with compact support, and even the subgroup of all globally Hamiltonian symplectomorphisms.*
- (4) *If (M, σ) is a real analytic symplectic manifold, the group $\text{Diff}^\omega(M, \sigma)$ of all real analytic symplectic diffeomorphisms, and even the subgroup of all globally Hamiltonian real analytic symplectomorphisms.*
- (5) *If (M, μ) is a manifold with a smooth volume density, the group $\text{Diff}_c(M, \mu)$ of all volume preserving diffeomorphisms with compact support.*
- (6) *If (M, μ) is a manifold with a real analytic volume density, the group $\text{Diff}^\omega(M, \mu)$ of all real analytic volume preserving diffeomorphisms.*
- (7) *If (M, α) is a contact manifold, the group $\text{Diff}_c(M, \alpha)$ of all contact diffeomorphisms with compact support.*
- (8) *If (M, α) is a real analytic contact manifold, the group $\text{Diff}^\omega(M, \alpha)$ of all real analytic contact diffeomorphisms.*

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Result (1) is folklore, the first trace is in [8]. The results (3), (5), and (7) are due to [3] for 1-transitivity, and to [1] in the general case. Result (2) is from [7]. We shall give here a short uniform proof, following an argument from [7]. That this argument suffices to prove all results was noted by the referee, many thanks to him.

Proof. Let us fix a finite $n \in \mathbb{N}$. Let $M^{(n)}$ denote the open submanifold of all n -tuples $(x_1, \dots, x_n) \in M^n$ of pairwise distinct points. Since M is connected and of dimension ≥ 2 , each $M^{(n)}$ is connected.

The group $\text{Diff}(M)$ acts on $M^{(n)}$ by the diagonal action, and we have to show, that any of the subgroups G described above acts transitively. We shall show below that for each G the G -orbit through any n -tuple $(x_1, \dots, x_n) \in M^{(n)}$ contains an open neighborhood of (x_1, \dots, x_n) in $M^{(n)}$, thus any orbit is open; since $M^{(n)}$ is connected, there can then be only one orbit. \square

Lemma. *Let M be a real analytic manifold. Then for any real analytic vector bundle $E \rightarrow M$ the space $C^\omega(E)$ of real analytic sections of E is dense in the space $C^\infty(E)$ of smooth sections. In particular the space $\mathfrak{X}^\omega(M)$ of real analytic vector fields is dense in the space $\mathfrak{X}(M)$ of smooth vector fields, in the Whitney C^∞ -topology.*

Proof. For functions instead of sections this is [2, Proposition 8]. Using results from [2] it can easily be extended to sections, as is done in [6, 7.5]. \square

The cases (2) and (1). We choose a complete Riemannian metric g on M and we let $(Y_{ij})_{j=1}^m$ be an orthonormal basis of $T_{x_i}M$ with respect to g , for all i . Then we choose real analytic vector fields X_k for $1 \leq k \leq N = nm$ which satisfy the following conditions:

$$(9) \quad \begin{aligned} |X_k(x_i) - Y_{ij}|_g &< \varepsilon && \text{for } k = (i-1)m + j, \\ |X_k(x_i)|_g &< \varepsilon && \text{for all } k \notin [(i-1)m + 1, im], \\ |X_k(x)|_g &< 2 && \text{for all } x \in M \text{ and all } k. \end{aligned}$$

Since these conditions describe a Whitney C^0 open set, such vector fields exist by the lemma. The fields are bounded with respect to a complete Riemannian metric, so they have complete real analytic flows Fl^{X_k} , see e.g. [4]. We consider the real analytic mapping

$$f: \mathbb{R}^N \rightarrow M^{(n)}$$

$$f(t_1, \dots, t_N) := \begin{pmatrix} (\text{Fl}_{t_1}^{X_1} \circ \dots \circ \text{Fl}_{t_N}^{X_N})(x_1) \\ \dots \\ (\text{Fl}_{t_1}^{X_1} \circ \dots \circ \text{Fl}_{t_N}^{X_N})(x_n) \end{pmatrix}$$

which has values in the $\text{Diff}^\omega(M)$ -orbit through (x_1, \dots, x_n) . To get the tangent mapping at 0 of f we consider the partial derivatives

$$\frac{\partial}{\partial t_k} \Big|_0 f(0, \dots, 0, t_k, 0, \dots, 0) = (X_k(x_1), \dots, X_k(x_n)).$$

If $\varepsilon > 0$ is small enough, this is near an orthonormal basis of $T_{(x_1, \dots, x_n)}M^{(n)}$ with respect to the product metric $g \times \dots \times g$. So T_0f is invertible and the image of f contains thus an open subset.

In case (1), we can choose smooth vector fields X_k with compact support which satisfy conditions (9). □

For the remaining cases we just indicate the changes which are necessary in this proof.

The cases (4) and (3). Let (M, σ) be a connected real analytic symplectic smooth manifold of dimension $m \geq 2$. We choose real analytic functions f_k for $1 \leq k \leq N = nm$ whose Hamiltonian vector fields $X_k = \text{grad}^\sigma(f_k)$ satisfy conditions (9). Since these conditions describe Whitney C^1 open subsets, such functions exist by [2, Proposition 8]. Now we may finish the proof as above. □

Contact manifolds.

Let M be a smooth manifold of dimension $m = 2n + 1 \geq 3$. A **contact form** on M is a 1-form $\alpha \in \Omega^1(M)$ such that $\alpha \wedge (d\alpha)^n \in \Omega^{2n+1}(M)$ is nowhere zero. This is sometimes called an **exact** contact structure. The pair (M, α) is called a **contact manifold** (see [5]). The **contact vector field** $X_\alpha \in \mathfrak{X}(M)$ is the unique vector field satisfying $i_{X_\alpha}\alpha = 1$ and $i_{X_\alpha}d\alpha = 0$.

A diffeomorphism $f \in \text{Diff}(M)$ with $f^*\alpha = \lambda_f \cdot \alpha$ for a nowhere vanishing function $\lambda_f \in C^\infty(M, \mathbb{R} \setminus 0)$ is called a **contact diffeomorphism**. Note that then $\lambda_f = i_{X_\alpha}(\lambda_f \cdot \alpha) = i_{X_\alpha}f^*\alpha = f^*(i_{(f^{-1})^*X_\alpha}\alpha) = f^*(i_{f_*X_\alpha}\alpha)$. The group of all contact diffeomorphisms will be denoted by $\text{Diff}(M, \alpha)$.

A vector field $X \in \mathfrak{X}(M)$ is called a contact vector field if $\mathcal{L}_X\alpha = \mu_X \cdot \alpha$ for a smooth function $\mu_X \in C^\infty(M, \mathbb{R})$. The linear space of all contact vector fields will be denoted by $\mathfrak{X}_\alpha(M)$ and it is clearly a Lie algebra. Contraction with α is a linear mapping again denoted by $\alpha: \mathfrak{X}_\alpha(M) \rightarrow C^\infty(M, \mathbb{R})$. It is bijective since we may apply i_{X_α} to the equation $\mathcal{L}_X\alpha = i_X d\alpha + d\alpha(X) = \mu_X \cdot \alpha$ and get $0 + i_{X_\alpha}d\alpha(X) = \mu_X$; but the equation uniquely determines X from $\alpha(X)$ and μ_X . The inverse $f \mapsto \text{grad}^\alpha(f)$ of $\alpha: \mathfrak{X}_\alpha(M) \rightarrow C^\infty(M, \mathbb{R})$ is a linear differential operator of order 1.

The cases (8) and (7). Let (M, α) be a connected real analytic contact manifold of dimension $m \geq 2$. We choose real analytic functions f_k for $1 \leq k \leq N = nm$ such that their contact vector fields $X_k = \text{grad}^\alpha(f_k)$ satisfy conditions (9).

Since these conditions describe Whitney C^1 open subsets, such functions exist by [2, Proposition 8]. Now we may finish the proof as above. \square

The cases (6) and (5). Let (M, μ) be a connected real analytic manifold of dimension $m \geq 2$ with a real analytic positive volume density. We can find a real analytic Riemannian metric γ on M whose volume form is μ . Then the divergence of a vector field $X \in \text{Vect}(M)$ is $\text{div } X = *d * X^\flat$, where $X^\flat = \gamma(X) \in \Omega^1(M)$ (here we view $\gamma: TM \rightarrow T^*M$) and $*$ is the Hodge star operator of γ . We also choose a complete Riemannian metric g .

First we assume that M is orientable. We choose real analytic $(m-2)$ -forms β_k for $1 \leq k \leq N = nm$ such that the vector fields $X_k = (-1)^{m+1} \gamma^{-1} * d\beta_k$ satisfy conditions (9). Since these conditions describe Whitney C^1 open subsets, such $(m-2)$ -forms exist by the lemma. The real analytic vector fields X_k are then divergence free since $\text{div } X_k = *d * \gamma X_k = *dd\beta_k = 0$. Now we may finish the proof as usual.

For non-orientable M , we let $\pi: \tilde{M} \rightarrow M$ be the real analytic connected oriented double cover of M , and let $\varphi: \tilde{M} \rightarrow \tilde{M}$ be the real analytic involutive covering map. We let $\pi^{-1}(x_i) = \{x_i^1, x_i^2\}$, and we pull back both metrics to \tilde{M} , so $\tilde{\gamma} := \pi^* \gamma$ and $\tilde{g} := \pi^* g$. We choose real analytic $(m-2)$ -forms $\beta_k \in \Omega^{m-2}(\tilde{M})$ for $1 \leq k \leq N = nm$ whose vector fields $X_{\beta_k} = (-1)^{m+1} \tilde{\gamma}^{-1} * d\beta_k$ satisfy the following conditions, where we put $Y_{ij}^p := T_{x_{ij}^p} \pi^{-1} \cdot Y_{ij}$ for $p = 1, 2$:

$$(10) \quad \begin{aligned} & |X_{\beta_k}(x_i^p) - Y_{ij}^p|_{\tilde{g}} < \varepsilon && \text{for } k = (i-1)m + j, p = 1, 2, \\ & |X_{\beta_k}(x_i^p)|_{\tilde{g}} < \varepsilon && \text{for all } k \notin [(i-1)m + 1, im], p = 1, 2, \\ & |X_{\beta_k}|_{\tilde{g}} < 2 && \text{for all } x \in \tilde{M} \text{ and all } k. \end{aligned}$$

Since these conditions describe Whitney C^1 open subsets, such $(m-2)$ -forms exist by the lemma. Then the vector fields $\frac{1}{2}(X_{\beta_k} + \varphi_* X_{\beta_k})$ still satisfy the conditions (10), are still divergence free and induce divergence free vector fields $Z_{\beta_k} \in \mathfrak{X}(M)$ which satisfy the conditions (9) on M as in the oriented case, and we may finish the proof as above. \square

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